Pseudo-random graphs and bit probe schemes with one-sided error

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# The problem under consideration: bit probe scheme with one-sided error

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Our technique: pseudo-random graphs

#### Bit probe scheme with one-sided error

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Bit probe scheme with one-sided error Given: a set A from universe U  $n = |A| \ll m = |U|$ , e.g.,  $n = m^{0.01}$ ,  $n = \text{poly} \log m$ , etc.

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**To construct:** a *database B* of size *s* such that to answer a query

#### $x \in A$ ?

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**Goal:** minimize 
$$s = |B|$$

Remark:  $s = \Omega(n \log m)$ 

static structures for a set: standard solutions
Given: a set A from universe U
How to encode A?

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## How to encode A?

1. bit vector of size m

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- ▶ good news: read one bit for a query " $x \in A$  ?"
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- 3. Fredman-Komlós-Szemerédi (double hashing):
  - good news: database of size  $O(n \log m)$  bits
  - good news: randomization only to construct the database
  - ▶ bad news: need to read  $O(\log m)$  bits to answer a query

Buhrman–Miltersen–Radhakrishnan–Venkatesh [2001] Two features:

- 1. a randomized algorithm answers a query " $x \in A$ ?"
- 2. a scheme based on a highly unbalanced expander

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- good news: read one bit to answer a query
- good news: memory =  $O(n \log m)$
- bad news: exponential computations
- some news: two-sided errors
- ▶ bad news: need  $\Omega(\frac{n^2 \log m}{\log n})$  for a one-sided error

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computations in poly(m)

- read one bit to answer a query
- memory =  $O(n \log^2 m)$  vs  $O(n \log m)$  in [BMRV]
- computations in  $poly(m) vs exp\{m\}$  in [BMRV]

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one-sided error

- read one bit to answer a query
- memory =  $O(n \log^2 m)$  vs  $O(n \log m)$  in [BMRV]
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one-sided error vs two-sided in [BMRV]

- read one bit to answer a query
- memory =  $O(n \log^2 m)$  vs  $O(n \log m)$  in [BMRV]
- computations in  $poly(m) vs exp\{m\}$  in [BMRV]
- one-sided error vs two-sided in [BMRV]
- memory =  $O(n \log^2 m)$  better than  $\Omega(\frac{n^2 \log m}{\log n})$  !

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Do we cheat ?

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Do we cheat ? Yes, we have changed the model ! We allow *cached* memory of size poly(log m).



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**Theorem.** For any *n*-element set A from an *m*-element universe there exists a randomized bit-probe scheme with one-sided error, with cache of size  $O(\log^c m)$  and database of size  $O(n \log^2 m)$ .

the left part: *m* vertices; degree  $d = O(\log m)$ the right part:  $s = O(n \log^2 m)$  vertices



in the left part: set A of n vertices the right part:  $s = O(n \log^2 m)$  vertices





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Bad news: there is no graph suitable for *every* sets A.

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1st idea: take a random graph and cache it

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2nd idea: take a *pseudo-random* graph, cache the seed

A graph is called suitable for A if for every  $x \notin A$ *most* neighbors of x are blue Good news: for every A most graphs are suitable. Bad news: there is no graph suitable for *every* sets A. 1st idea: take a *random* graph and *cache* it we cannot, a random graph is too large! 2nd idea: take a *pseudo-random* graph, cache the *seed* We need a good PRG...

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Size of the seed =  $poly(\log m)$ .

Conclusion: a **bit-probe scheme**:

- read one bit to answer a query
- one-sided error
- ▶ 1-st level "cached" memory  $= poly \log m$

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• 2-nd level memory =  $O(n \log^2 m)$ 

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Beyond this talk: combine our construction with Guruswami–Umans–Vadhan

- read two bit to answer a query
- one-sided error
- ▶ 1-st level "cache" memory  $= poly \log m$
- ▶ 2-nd level memory =  $n^{1+\delta}$  poly log m
- computations in time  $poly(n, \log m)$

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Thank you! Questions?