

The complexity of inversion of explicit Goldreich's function by DPLL algorithms

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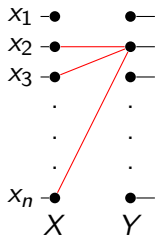
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June 15

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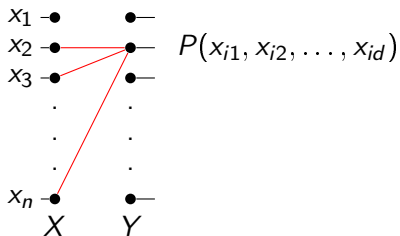
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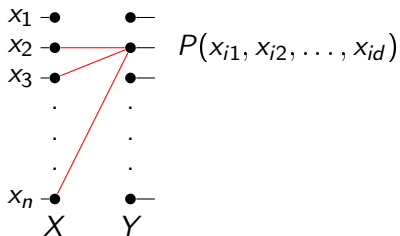
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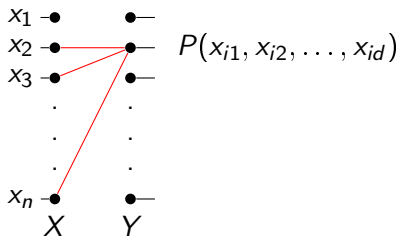
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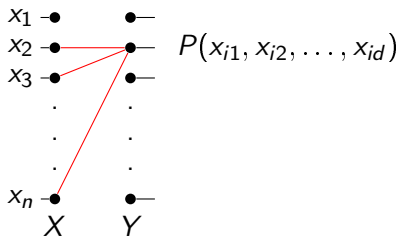
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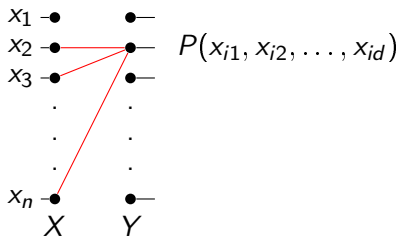
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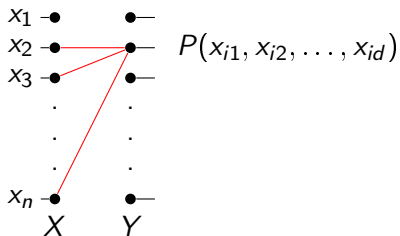
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then function f is a one-way.

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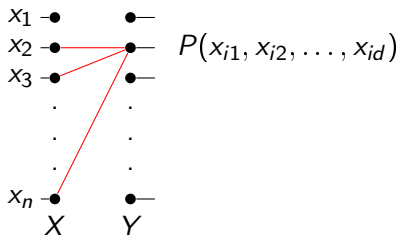
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- f is computed by constant depth circuit;

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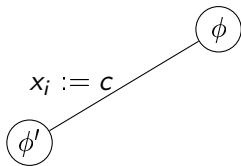
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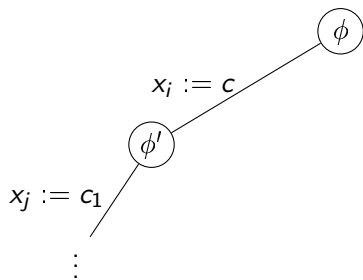
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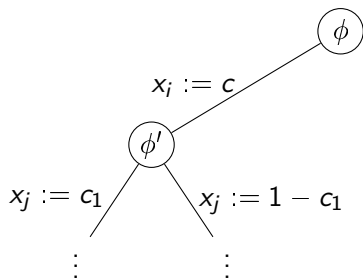
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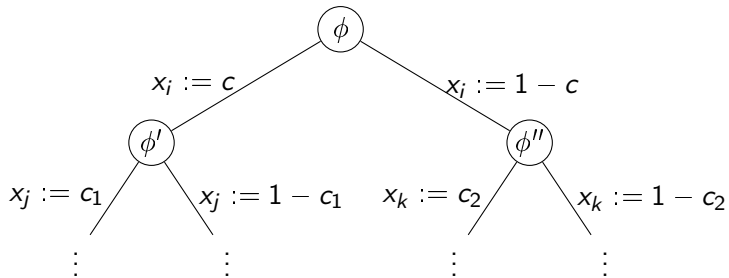
- f is computed by constant depth circuit;
- [Applebaum, Ishai, Kushilevitz 2006] If one-way functions exist then there is a one-way function that can be computed by constant depth circuit.

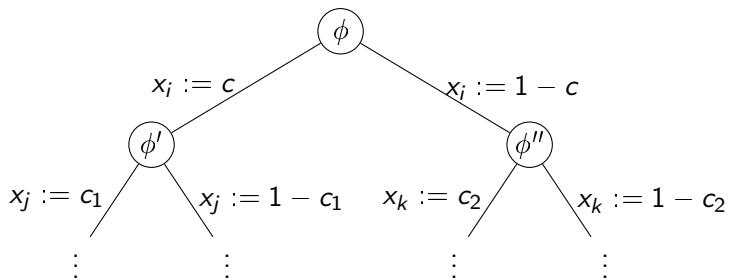




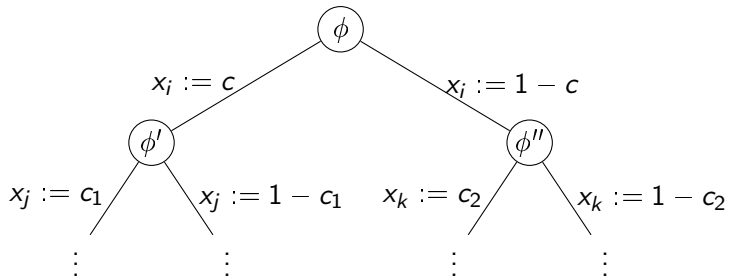




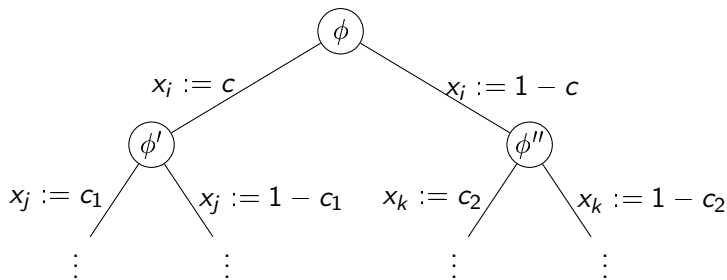




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- Simplification rules:
 - unit clause elimination;
 - pure literal rule.

Lower bounds for DPLL algorithms

- Unsatisfiable formulas
 - Exponential lower bounds for resolution refutations of unsatisfiable formulas translate to backtracking algorithms.
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 - [Nikolenko 2002], [Achlioptas, Beame, Molloy 2003-2004] exponential lower bound for specific backtracking algorithms.
 - [Alekhnovich, Hirsch, Itsykson 2005] Exponential lower bound for myopic and drunken algorithms.

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 - [Nikolenko 2002], [Achiliotas, Beame, Molloy 2003-2004] exponential lower bound for specific backtracking algorithms.
 - [Alekhovich, Hirsch, Itsykson 2005] Exponential lower bound for myopic and drunken algorithms.
 - Exponential lower bound for inversion of Goldreich's function by myopic [J. Cook et al. 2009] and drunken [Itsykson 2010] algorithms.

Drunken and myopic algorithms

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Drunken algorithms:

- **A**: any;
- **B**: random 50 : 50.

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Our results

$P(x_1, \dots, x_d) = x_1 \oplus x_2 \oplus \dots \oplus x_{d-k} \oplus Q(x_{d-k+1}, \dots, x_d)$, Q is an arbitrary, $k < d/4$.

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Theorem

There exists *an explicit* graph G such that every myopic or drunken DPLL algorithm makes at least $2^{n^{\Omega(1)}}$ steps on “ $f(x) = f(a)$ ” for almost all $a \in \{0, 1\}^n$.

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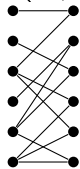
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- For myopic
 - we simplify previous proof and
 - $K = n^{1-\epsilon}$

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Graph construction

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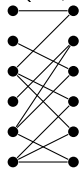


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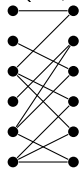
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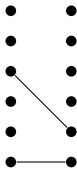
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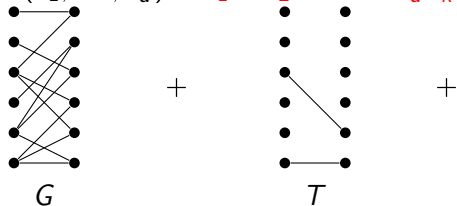


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- G is an expander;
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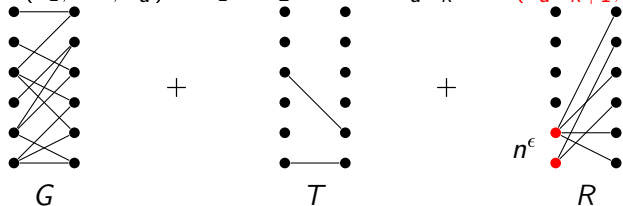
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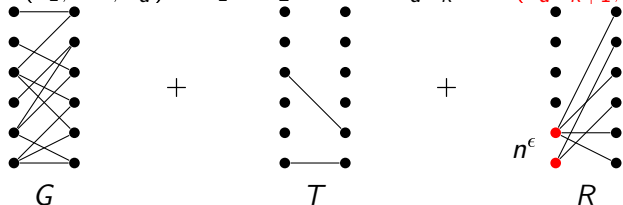
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- R contains nonlinear edges. $|\{x \mid x \in X, \deg(x) \neq 0\}| \leq n^\epsilon$.
 - $G + T + R$ is an expander.

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 - $G + T + R$ is an expander.
 - Size of preimages no more than 2^{n^ϵ} .

We can invert $f_{G+T+R,P}$ in time $\text{poly}(n)2^{n^\epsilon}$, but this is still much!

Plan of the proof

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 - G is an expander.
 - f is almost bijection.
 - Myopic algorithm can't recognize different absolute terms.