# Constraint Satisfaction with Counting Quantifiers 2 

Sequel to Constraint Satisfaction with Counting Quantifiers (CSR 2012)

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The Constraint Satisfaction Problem $\operatorname{CSP}(\mathcal{B})$ takes as input a primitive positive ( $\{1\}-\mathrm{pp}$ ) sentence $\Phi$, i.e. of the form

$$
\exists v_{1} \ldots v_{j} \phi\left(v_{1}, \ldots, v_{j}\right)
$$

where $\phi$ is a conjunction of atoms, and asks whether $\mathcal{B} \models \Phi$.
This is equivalent to the Homomorphism Problem - has $\mathcal{A}$ a homomorphism to $\mathcal{B}$ ?

The structure $\mathcal{B}$ is known as the template.

Example homomorphisms.


$$
\begin{array}{rl}
\Phi:=\exists v_{1}, v_{2}, v_{3}, v_{4}, v_{5} & E\left(v_{1}, v_{2}\right) \wedge E\left(v_{2}, v_{1}\right) \wedge E\left(v_{2}, v_{3}\right) \wedge E\left(v_{3}, v_{2}\right) \\
& E\left(v_{3}, v_{4}\right) \wedge E\left(v_{4}, v_{3}\right) \wedge E\left(v_{4}, v_{5}\right) \\
& E\left(v_{5}, v_{4}\right) \wedge E\left(v_{5}, v_{1}\right) \wedge E\left(v_{!}, v_{5}\right) .
\end{array}
$$

Finite CSPs occur a lot in nature.

- $\operatorname{CSP}\left(\mathcal{K}_{m}\right)$ is graph $m$-colourability.
- $\operatorname{CSP}\left(\{0,1\} ; R_{N A E}\right)$, where $B_{\text {NAE }}$ is $\{0,1\}^{3} \backslash\{(0,0,0),(1,1,1)\}$ is not-all-equal 3-satisfiabilty.
- $\operatorname{CSP}\left(\{0,1\} ; R_{\text {TTT }}, R_{\text {TTF }}, R_{\text {TFF }}, R_{\text {FFF }}\right)$ is 3-satisfiabilty.
- $\operatorname{CSP}(\{0,1\} ;\{0\},\{1\},\{(0,0),(1,1)\})$ is graph s-t unreachability.
Also vertex cover, clique and hamilton path - but these require non-fixed template.

Infinite CSPs also occur a lot in nature (another story...)

Feder-Vardi dichotomy conjecture. Each $\operatorname{CSP}(\mathcal{B})$ is either in P or is NP-complete.

- Compare with Ladner non-dichotomy for NP.

Still open, but known for:

- Structures size 2 (Schaefer 1978).
- Structures size 3 (Bulatov 2002).
- Structures with unary relations (Bulatov 2003).
- Smooth digraphs (Barto, Kozik and Niven 2010).
- Structures size 4 (Marković 2011?).

The Quantified $\operatorname{CSP} \operatorname{QCSP}(\mathcal{B})$ takes as input a positive Horn ( $\{1,|B|\}$-pp) sentence $\Phi$, i.e. of the form

$$
\forall \bar{v}_{1} \exists \bar{v}_{2} \ldots, Q \bar{v}_{j} \phi\left(\bar{v}_{1}, \bar{v}_{2}, \ldots, \bar{v}_{j}\right),
$$

where $\phi$ is a conjunction of atoms, and asks whether $\mathcal{B} \models \Phi$.
$\operatorname{QCSP}(\mathcal{B})$ is always in Pspace.

## Extant classifications

QCSP classifications are harder than CSP classifications.

- Boolean structures. Dichotomy P, Pspace-complete. (Schaefer 1978 + Creignou et al. 2001/ Dalmau 1997.)
- Graphs of permutations. Trichotomy P, NP-complete, Pspace-complete. (Börner et al. 2002.)
- Various digraphs Dichotomies and trichotomies NL, NP-complete, Pspace-complete. (M., Madelaine, Dapić, Marković. 2006, 2011, 2013, 2014)
- Structures with 2-semilattice polymorphism. Dichotomy P, coNP-hard. (Chen 2004.)
The algebraic approach is weaker for QCSPs and the combinatorial method has fewer constructs. Separating NP-hard into NP-complete and Pspace-complete is especially difficult.

For $\mathcal{B}$ with $|B|=n$, let $X \subseteq\{1, \ldots, n\}$. The $X-\operatorname{CSP}(\mathcal{B})$ has input of the form $X$-pp

- $\Phi:=Q_{1} x_{1} Q_{2} x_{2} \ldots Q_{m} x_{m} \phi\left(x_{1}, x_{2}, \ldots, x_{m}\right)$,
where $\phi$ is a positive conjunction and each $Q_{i}$ is $\exists^{\geq j}$ for some $j \in X$.
- The yes-instances are those for which $\mathcal{B} \models \Phi$.

Counting quantifiers not studied here before.

- $\exists \geq 1$ is $\exists$ and $\exists \geq n$ is $\forall$.

So,

- $\{1\}-\operatorname{CSP}(\mathcal{B})$ is $\operatorname{CSP}(\mathcal{B})$, and
- $\{1,|B|\}-\operatorname{CSP}(\mathcal{B})$ is $\operatorname{QCSP}(\mathcal{B})$.
$X-\operatorname{CSP}(\mathcal{B})$ is always in Pspace.

Basic results.
(CSR 2012.) Consider $X$ a singleton.

1. $\{1\}-\operatorname{CSP}(\mathcal{B})$ is in NP for all $\mathcal{B}$. For each $n \geq 2$, there exists a template $\mathcal{B}_{n}$ of size $n$ s.t. $\{1\}-\operatorname{CSP}\left(\mathcal{B}_{n}\right)$ is NP-complete.
2. $\{|B|\}-\operatorname{CSP}(\mathcal{B})$ is in $L$ for all $\mathcal{B}$.
3. For each $n \geq 3$, there exists a template $\mathcal{B}_{n}$ of size $n$ s.t. $\{j\}-\operatorname{CSP}\left(\mathcal{B}_{n}\right)$ is Pspace-complete for all $1<j<n$.

The case of Cycles.
Theorem (CSR 2012)
For $n \geq 3$ and $X \subseteq\{1, \ldots, n\}$, the problem $X-\operatorname{CSP}\left(\mathcal{C}_{n}\right)$ is either in L, is NP-complete or is Pspace-complete. Namely:
(i) $X-\operatorname{CSP}\left(\mathrm{C}_{n}\right) \in \mathrm{L}$ if $n=4$, or $1 \notin X$, or $n$ is even and $X \cap\{2, \ldots, n / 2\}=\emptyset$.
(ii) $X-\operatorname{CSP}\left(\mathrm{C}_{n}\right)$ is $N P$-complete if $n$ is odd and $X=\{1\}$.
(iii) $X-\operatorname{CSP}\left(\mathrm{C}_{n}\right)$ is Pspace-complete in all other cases.

The case of Cliques.
Theorem (CSR 2012)
For $n \in \mathbb{N}$ and $X \subseteq\{1, \ldots, n\}$ :
(i) $X-\operatorname{CSP}\left(\mathcal{K}_{n}\right)$ is in $L$ if $n \leq 2$ or $X \cap\{1, \ldots,\lfloor n / 2\rfloor\}=\emptyset$.
(ii) $X-\operatorname{CSP}\left(\mathcal{K}_{n}\right)$ is NP-complete if $n>2$ and $X=\{1\}$.
(iii) $X-\operatorname{CSP}\left(\mathcal{K}_{n}\right)$ is Pspace-complete if $n>2$ and either $j \in X$ for $1<j<n / 2$ or $\{1, j\} \subseteq X$ for $j \in\{\lceil n / 2\rceil, \ldots, n\}$.

This is a near trichotomy - where $n$ is even and we have just $\exists \geq n / 2$ is open. Clearly $\{1\}-\operatorname{CSP}\left(\mathcal{K}_{2}\right)$ is in L .
Theorem (CSR 2014)
(iv-i) $\{2\}-\operatorname{CSP}\left(\mathcal{K}_{4}\right)$ is in $P$.
(iv-ii) $\{j\}-\operatorname{CSP}\left(\mathcal{K}_{2 j}\right)$ is Pspace-complete, for $j \geq 3$.

## Hell and Nešetřil

Theorem (Hell and Nešetřil 1990)
Let $\mathcal{H}$ be a (undirected) graph. Then

- $\operatorname{CSP}(\mathcal{H}) \in \mathrm{P}$, if $\mathcal{H}$ is bipartite
- $\operatorname{CSP}(\mathcal{H})$ is NP-complete, otherwise.

What can we say when we augment $\exists$ with $\exists \geq 2$ ?

## Generalising Hell and Nešetřil

Let [ $\left.1^{m} 2^{*}\right]$-pp be the fragment of $\{1,2\}$-pp in which $m \exists \geq 2$ quantifiers are followed by nothing but $\exists \geq 1=\exists$.
Theorem (CSR 2012)
Let $\mathcal{H}$ be a graph. Then

- [ $\left.2^{m} 1^{*}\right]-\operatorname{CSP}(\mathcal{H}) \in \mathrm{P}$ for all $m$, if $\mathcal{H}$ is a forest or a bipartite graph containing $\mathrm{C}_{4}$
- [2 $\left.2^{m} 1^{*}\right]-\operatorname{CSP}(\mathcal{H})$ is NP-complete for some $m$, if otherwise.

Theorem (CSR 2014)
Let $\mathcal{H}$ be a graph. Then

- $\{1,2\}-\operatorname{CSP}(\mathcal{H}) \in \mathrm{P}$, if $\mathcal{H}$ is a forest or a bipartite graph containing $\mathrm{C}_{4}$
- \{1,2\}-CSP( $\mathcal{H})$ is NP-hard, otherwise.


## Is that all!?

The sub-case $\{1,2\}-\operatorname{CSP}\left(\mathcal{P}_{\omega}\right)$ in P is already complicated.

- but seriously...
the contribution seems so slight, but the combinatorics of counting quantifiers is so awkward!
- The CSR submission was 35 pages!

The algebraic method now exists for $X$-CSP, but it has not proven to be much better.

## $\{2\}-\operatorname{CSP}\left(\mathcal{K}_{4}\right)$ is in P

We iteratively construct the following three sets:

$$
R^{+}, R^{-} \text {, both ternary and } F \supseteq E .
$$

X1 If there are $x, y, z \in V(G)$ such that $\{x, y\}<z$ where $x z, y z \in F$, then add $x y z$ into $R^{-}$.
X2 If there are vertices $x, y, w, z \in V(G)$ such that $\{x, y, w\}<z$ with $w z \in F$ and $x y z \in R^{-}$, then add $x y w$ into $R^{+}$.


Figure: Illustrating rules (X1) and (X2)

## $\{2\}-\operatorname{CSP}\left(\mathcal{K}_{4}\right)$ is in P

X3 If there are $x, y, w, z \in V(G)$ s.t. $\{x, y, w\}<z, w z \in F$ and $x y z \in$ $R^{+}$, then if $\{x, y\}<w$, add $x y w$ to $R^{-}$, else add $x w, y w$ to $F$.

X4 If there are vertices $x, y, w, z \in V(G)$ s.t. $\{x, w\}<y<z$ with $x y z \in R^{+}$and $w y z \in R^{-}$, then add $x w$ to $F$, and add $x y w$ to $R^{+}$.

X5 If there are vertices $x, y, w, z \in V(G)$ such that $\{x, y, w\}<z$ where either $x y z, w y z \in R^{+}$, or $x y z, w y z \in R^{-}$, then add $x y w$ into $R^{+}$.

X6 If there are vertices $x, y, q, w, z \in V(G)$ such that $\{x, y, w\}<q<z$ where either $x y z, w q z \in R^{+}$, or $x y z, w q z \in R^{-}$, then add $x y w$ and $x y q$ into $R^{+}$.

X7 If there are vertices $x, y, q, w, z \in V(G)$ such that $\{x, y, w\}<q<z$ where either $x y z \in R^{+}$and $w q z \in R^{-}$, or $x y z \in R^{-}$and $w q z \in R^{+}$, then add $x y q$ into $R^{-}$, and if $\{x, y\}<w$, also add $x y w$ into $R^{-}$, else add $x w$ and $y w$ into $F$.

## $\{2\}-\operatorname{CSP}\left(\mathcal{K}_{4}\right)$ is in P



$$
\begin{array}{c:c:c:c}
\bigcirc & \bigcirc & \bigcirc & \bigcirc \\
w & x & y & z
\end{array}
$$



Figure: Five forbidden configurations of $\{2\}-\operatorname{CSP}\left(\mathcal{K}_{4}\right)$

## Further interesting results

## Theorem

If $\mathcal{H}$ is a bipartite graph, then either $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is in $P$, or $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is Pspace-complete.

Theorem
Let $H$ be a (partially reflexive) graph on at most three vertices, then either $\{1,2\}-\operatorname{CSP}(H)$ is in $P$ or it is Pspace-complete.
The smallest graph $\mathcal{H}$ so that $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is in NP-complete is size 4.

## Theorem

Let $\mathcal{H}$ be a graph with reflexive dominating vertex, then $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is either in $P$ or is NP-complete.

Theorem
Let $\mathcal{H}:=\mathcal{K}_{a_{1}, \ldots, a_{n}}$ be a complete multipartite graph with respective parts of size $a_{1}, \ldots, a_{n}$.
(i) If $n=2$, then $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is in $L$.
(ii) If $n>2$ and the multiset $\left\{\left\{a_{1}, \ldots, a_{n}\right\}\right\}$ contains at most 1 , then $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is NP-complete.
(iii) $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is Pspace-complete all other cases.

## Conjecture

Let $\mathcal{H}$ be a graph. Either $\{1,2\}-\operatorname{CSP}(\mathcal{H})$ is in $P$, or it is NP-complete, or it is Pspace-complete.

Combinatorics to a Galois theory.

- A homomorphism from $\mathcal{B}^{k}$ to $\mathcal{B}$ is termed a $k$-ary polymorphism.
Let $\operatorname{Pol}(\mathcal{B}), \operatorname{sPol}(\mathcal{B})$ be the polymorphisms, surjective pols of $\mathcal{B}$.
- $\operatorname{Inv}(\operatorname{Pol}(\mathcal{B}))=\langle\mathcal{B}\rangle_{\{1\}-\mathrm{pp}}$.
- $\operatorname{Inv}(\operatorname{sPol}(\mathcal{B}))=\langle\mathcal{B}\rangle_{\{1,|B|\}-\mathrm{pp}}$.

Call a function $f: B^{k} \rightarrow B$ expanding if,

- for each $m,\left|X_{1}\right|, \ldots,\left|X_{k}\right|=m$ implies $\left|f\left(X_{1}, \ldots, X_{k}\right)\right| \geq m$.

Let $\operatorname{ePol}(\mathcal{B})$ be the expanding polymorphisms of $\mathcal{B}$.
Theorem (Bulatov and Hedayaty 2012)
For finite $\mathcal{B}, \operatorname{Inv}(\operatorname{ePol}(\mathcal{B}))=\langle\mathcal{B}\rangle_{\{1, \ldots,|B|\}-\mathrm{pp}}$.
There is some hope this can help in the Mal'tsev case.

Conjecture.

- For $j>1,\{1, j\}-\operatorname{CSP}(\mathcal{B})$ is either in P, NP-complete or Pspace-complete.
- $\{1, \ldots,|B|\}-\operatorname{CSP}(\mathcal{B})$ is either in P or Pspace-complete.

