Constraint Satisfaction with Counting Quantifiers 2 Sequel to Constraint Satisfaction with Counting Quantifiers (CSR 2012)

Barnaby Martin and Juraj Stacho

Foundations of Computing Group, Middlesex University, London CSR 2014, Moscow

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The Constraint Satisfaction Problem CSP(B) takes as input a primitive positive ($\{1\}$ -pp) sentence Φ , i.e. of the form

$$\exists v_1 \ldots v_j \ \phi(v_1, \ldots, v_j),$$

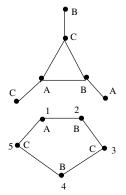
where ϕ is a conjunction of atoms, and asks whether $\mathcal{B} \models \Phi$.

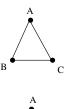
This is equivalent to the Homomorphism Problem – has A a homomorphism to B?

The structure \mathcal{B} is known as the template.



Example homomorphisms.







$$\Phi := \exists v_1, v_2, v_3, v_4, v_5 \quad E(v_1, v_2) \wedge E(v_2, v_1) \wedge E(v_2, v_3) \wedge E(v_3, v_2) \\ E(v_3, v_4) \wedge E(v_4, v_3) \wedge E(v_4, v_5) \\ E(v_5, v_4) \wedge E(v_5, v_1) \wedge E(v_1, v_5).$$

Finite CSPs occur a lot in nature.

- CSP(\mathcal{K}_m) is graph *m*-colourability.
- CSP($\{0,1\}$; R_{NAE}), where B_{NAE} is $\{0,1\}^3 \setminus \{(0,0,0),(1,1,1)\}$ is not-all-equal 3-satisfiabilty.
- CSP($\{0,1\}$; R_{TTT} , R_{TTF} , R_{TFF} , R_{FFF}) is 3-satisfiabilty.
- CSP({0,1}; {0}, {1}, {(0,0), (1,1)}) is graph s-t unreachability.

Also vertex cover, clique and hamilton path – but these require non-fixed template.

Infinite CSPs also occur a lot in nature (another story...)



Feder-Vardi dichotomy conjecture. Each $\mathsf{CSP}(\mathcal{B})$ is either in P or is NP-complete.

Compare with Ladner non-dichotomy for NP.

Still open, but known for:

- Structures size 2 (Schaefer 1978).
- Structures size 3 (Bulatov 2002).
- Structures with unary relations (Bulatov 2003).
- Smooth digraphs (Barto, Kozik and Niven 2010).
- Structures size 4 (Marković 2011?).





The Quantified CSP QCSP(\mathcal{B}) takes as input a *positive Horn* ($\{1, |B|\}$ -pp) sentence Φ , i.e. of the form

$$\forall \overline{v}_1 \exists \overline{v}_2 \dots, Q \overline{v}_j \ \phi(\overline{v}_1, \overline{v}_2, \dots, \overline{v}_j),$$

where ϕ is a conjunction of atoms, and asks whether $\mathcal{B} \models \Phi$.

 $\mathsf{QCSP}(\mathfrak{B})$ is always in Pspace.



Extant classifications

QCSP classifications are harder than CSP classifications.

- Boolean structures. Dichotomy P, Pspace-complete. (Schaefer 1978 + Creignou et al. 2001/ Dalmau 1997.)
- Graphs of permutations. Trichotomy P, NP-complete, Pspace-complete. (Börner et al. 2002.)
- Various digraphs Dichotomies and trichotomies NL,
 NP-complete, Pspace-complete. (M., Madelaine, Dapić,
 Marković. 2006, 2011, 2013, 2014)
- Structures with 2-semilattice polymorphism. Dichotomy P, coNP-hard. (Chen 2004.)

The algebraic approach is weaker for QCSPs and the combinatorial method has fewer constructs. Separating NP-hard into NP-complete and Pspace-complete is especially difficult.

For \mathcal{B} with |B| = n, let $X \subseteq \{1, ..., n\}$. The X-CSP(\mathcal{B}) has input of the form X-pp

• $\Phi := Q_1 x_1 Q_2 x_2 \dots Q_m x_m \ \phi(x_1, x_2, \dots, x_m),$

where ϕ is a positive conjunction and each Q_i is $\exists^{\geq j}$ for some $j \in X$.

• The yes-instances are those for which $\mathcal{B} \models \Phi$.

Counting quantifiers not studied here before.

• $\exists^{\geq 1}$ is \exists and $\exists^{\geq n}$ is \forall .

So,

- $\{1\}$ -CSP(\mathcal{B}) is CSP(\mathcal{B}), and
- $\{1, |B|\}$ -CSP(\mathcal{B}) is QCSP(\mathcal{B}).

X-CSP(\mathfrak{B}) is always in Pspace.



Basic results.

(CSR 2012.) Consider X a singleton.

- 1. $\{1\}$ -CSP(\mathcal{B}) is in NP for all \mathcal{B} . For each $n \geq 2$, there exists a template \mathcal{B}_n of size n s.t. $\{1\}$ -CSP(\mathcal{B}_n) is NP-complete.
- 2. $\{|B|\}$ -CSP(\mathcal{B}) is in L for all \mathcal{B} .
- 3. For each $n \ge 3$, there exists a template \mathcal{B}_n of size n s.t. $\{j\}$ -CSP (\mathcal{B}_n) is Pspace-complete for all 1 < j < n.



The case of Cycles.

Theorem (CSR 2012)

For $n \ge 3$ and $X \subseteq \{1, ..., n\}$, the problem X-CSP(\mathfrak{C}_n) is either in L, is NP-complete or is Pspace-complete. Namely:

- (i) X- $CSP(\mathfrak{C}_n) \in L$ if n = 4, or $1 \notin X$, or n is even and $X \cap \{2, \ldots, n/2\} = \emptyset$.
- (ii) X- $CSP(\mathcal{C}_n)$ is NP-complete if n is odd and $X = \{1\}$.
- (iii) X- $CSP(\mathcal{C}_n)$ is Pspace-complete in all other cases.



The case of Cliques.

Theorem (CSR 2012)

For $n \in \mathbb{N}$ and $X \subseteq \{1, \ldots, n\}$:

- (i) X- $CSP(\mathfrak{X}_n)$ is in L if $n \leq 2$ or $X \cap \{1, \ldots, \lfloor n/2 \rfloor\} = \emptyset$.
- (ii) X- $CSP(\mathfrak{K}_n)$ is NP-complete if n > 2 and $X = \{1\}$.
- (iii) X- $CSP(\mathcal{K}_n)$ is Pspace-complete if n > 2 and either $j \in X$ for 1 < j < n/2 or $\{1, j\} \subseteq X$ for $j \in \{\lceil n/2 \rceil, \dots, n\}$.

This is a near trichotomy – where n is even and we have just $\exists \geq n/2$ is open. Clearly $\{1\}$ -CSP (\mathcal{K}_2) is in L.

Theorem (CSR 2014)

- (iv-i) $\{2\}$ -CSP(\mathcal{K}_4) is in P.
- (iv-ii) $\{j\}$ -CSP (\mathfrak{K}_{2j}) is Pspace-complete, for $j \geq 3$.



Hell and Nešetřil

Theorem (Hell and Nešetřil 1990)

Let \mathcal{H} be a (undirected) graph. Then

- $CSP(\mathcal{H})$ ∈ P, if \mathcal{H} is bipartite
- $CSP(\mathcal{H})$ is NP-complete, otherwise.

What can we say when we augment \exists with $\exists \geq 2$?





Generalising Hell and Nešetřil

Let $[1^m2^*]$ -pp be the fragment of $\{1,2\}$ -pp in which m $\exists^{\geq 2}$ quantifiers are followed by nothing but $\exists^{\geq 1} = \exists$.

Theorem (CSR 2012)

Let \mathcal{H} be a graph. Then

- [2^m1*]-CSP(\mathcal{H}) ∈ P for all m, if \mathcal{H} is a forest or a bipartite graph containing \mathcal{C}_4
- $-[2^m1^*]$ - $CSP(\mathcal{H})$ is NP-complete for some m, if otherwise.

Theorem (CSR 2014)

Let $\mathcal H$ be a graph. Then

- $\{1,2\}$ - $CSP(\mathcal{H}) \in P$, if \mathcal{H} is a forest or a bipartite graph containing C_4
- $-\{1,2\}$ -CSP(\mathfrak{H}) is NP-hard, otherwise.



Is that all!?

The sub-case $\{1,2\}$ -CSP (\mathcal{P}_{ω}) in P is already complicated.

but seriously...

the contribution seems so slight, but the combinatorics of counting quantifiers is so awkward!

The CSR submission was 35 pages!

The algebraic method now exists for X-CSP, but it has not proven to be much better.

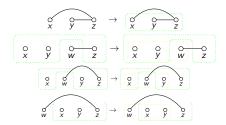


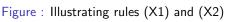
$\{2\}$ -CSP(\mathcal{K}_4) is in P

We iteratively construct the following three sets:

 R^+ , R^- , both ternary and $F \supseteq E$.

- X1 If there are $x, y, z \in V(G)$ such that $\{x, y\} < z$ where $xz, yz \in F$, then add xyz into R^- .
- X2 If there are vertices $x, y, w, z \in V(G)$ such that $\{x, y, w\} < z$ with $wz \in F$ and $xyz \in R^-$, then add xyw into R^+ .







$\{2\}$ -CSP (\mathcal{K}_4) is in P

- X3 If there are $x, y, w, z \in V(G)$ s.t. $\{x, y, w\} < z$, $wz \in F$ and $xyz \in R^+$, then if $\{x, y\} < w$, add xyw to R^- , else add xw, yw to F.
- X4 If there are vertices $x, y, w, z \in V(G)$ s.t. $\{x, w\} < y < z$ with $xyz \in R^+$ and $wyz \in R^-$, then add xw to F, and add xyw to R^+ .
- X5 If there are vertices $x, y, w, z \in V(G)$ such that $\{x, y, w\} < z$ where either $xyz, wyz \in R^+$, or $xyz, wyz \in R^-$, then add xyw into R^+ .
- X6 If there are vertices $x, y, q, w, z \in V(G)$ such that $\{x, y, w\} < q < z$ where either $xyz, wqz \in R^+$, or $xyz, wqz \in R^-$, then add xyw and xyq into R^+ .
- X7 If there are vertices $x, y, q, w, z \in V(G)$ such that $\{x, y, w\} < q < z$ where either $xyz \in R^+$ and $wqz \in R^-$, or $xyz \in R^-$ and $wqz \in R^+$, then add xyq into R^- , and if $\{x, y\} < w$, also add xyw into R^- , else add xw and yw into F.

$\{2\}$ -CSP(\mathcal{K}_4) is in P

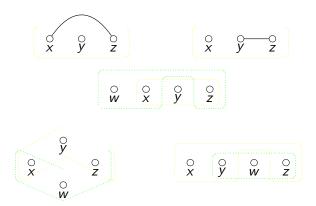


Figure : Five forbidden configurations of $\{2\}$ -CSP (\mathcal{K}_4)



Further interesting results

Theorem

If \mathcal{H} is a bipartite graph, then either $\{1,2\}$ -CSP(\mathcal{H}) is in P, or $\{1,2\}$ -CSP(\mathcal{H}) is Pspace-complete.

Theorem

Let H be a (partially reflexive) graph on at most three vertices, then either $\{1,2\}$ -CSP(H) is in P or it is Pspace-complete.

The smallest graph $\mathcal H$ so that $\{1,2\}$ -CSP $(\mathcal H)$ is in NP-complete is size 4.



Theorem

Let \mathcal{H} be a graph with reflexive dominating vertex, then $\{1,2\}$ -CSP(\mathcal{H}) is either in P or is NP-complete.

Theorem

Let $\mathcal{H} := \mathcal{K}_{a_1,...,a_n}$ be a complete multipartite graph with respective parts of size a_1, \ldots, a_n .

- (i) If n = 2, then $\{1,2\}$ -CSP (\mathcal{H}) is in L.
- (ii) If n > 2 and the multiset $\{\{a_1, \ldots, a_n\}\}$ contains at most 1, then $\{1, 2\}$ -CSP (\mathcal{H}) is NP-complete.
- (iii) $\{1,2\}$ -CSP(\mathcal{H}) is Pspace-complete all other cases.

Conjecture

Let $\mathcal H$ be a graph. Either $\{1,2\}$ -CSP($\mathcal H$) is in P, or it is NP-complete, or it is Pspace-complete.





Combinatorics to a Galois theory.

• A homomorphism from \mathcal{B}^k to \mathcal{B} is termed a k-ary polymorphism.

Let $Pol(\mathcal{B}), sPol(\mathcal{B})$ be the polymorphisms, surjective pols of \mathcal{B} .

- $\operatorname{Inv}(\operatorname{Pol}(\mathcal{B})) = \langle \mathcal{B} \rangle_{\{1\}\text{-pp}}.$
- $\operatorname{Inv}(\operatorname{sPol}(\mathfrak{B})) = \langle \mathfrak{B} \rangle_{\{1,|B|\}\text{-pp}}.$



Call a function $f: B^k \to B$ expanding if,

• for each m, $|X_1|, \ldots, |X_k| = m$ implies $|f(X_1, \ldots, X_k)| \ge m$.

Let ePol(B) be the expanding polymorphisms of B.

Theorem (Bulatov and Hedayaty 2012)

For finite \mathfrak{B} , $\operatorname{Inv}(\operatorname{ePol}(\mathfrak{B})) = \langle \mathfrak{B} \rangle_{\{1,\dots,|\mathcal{B}|\}\text{-pp}}$.

There is some hope this can help in the Mal'tsev case.



Conjecture.

- For j > 1, $\{1, j\}$ -CSP(\mathfrak{B}) is either in P, NP-complete or Pspace-complete.
- $\{1, \ldots, |B|\}$ -CSP(\mathcal{B}) is either in P or Pspace-complete.

