

Matrix Multiplication and Graph Algorithms

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Outline

1. Algebraic matrix multiplication

- a. Strassen's algorithm
- b. Rectangular matrix multiplication

2. Boolean matrix multiplication

- a. Simple reduction to integer matrix multiplication
- b. Computing the transitive closure of a graph.

3. Min-Plus matrix multiplication

- a. Equivalence to the APSP problem
- b. Expensive reduction to algebraic products
- c. Fredman's trick

4. APSP in undirected graphs

- a. An $O(n^{2.38})$ algorithm for **unweighted** graphs (Seidel)
- b. An $O(Mn^{2.38})$ algorithm for **weighted** graphs (Shoshan-Zwick)

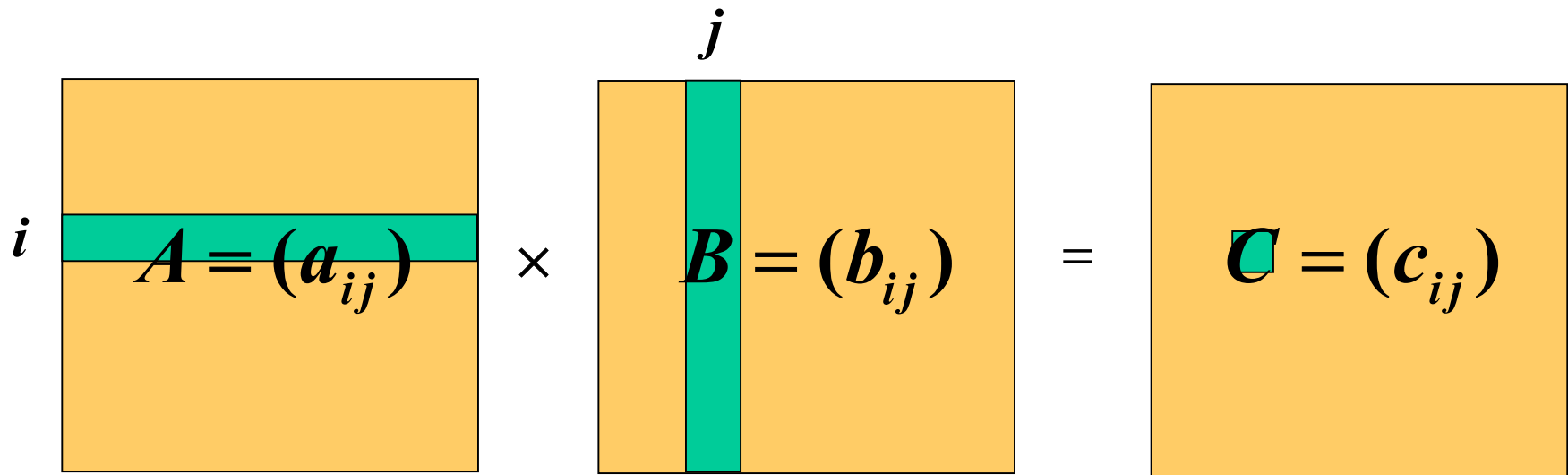
5. APSP in directed graphs

1. An $O(M^{0.68}n^{2.58})$ algorithm (Zwick)
2. An $O(Mn^{2.38})$ preprocessing / $O(n)$ query answering algorithm (Yuster-Zwick)
3. An $O(n^{2.38}\log M)$ $(1+\epsilon)$ -approximation algorithm

6. Summary and open problems

Short introduction to Fast matrix multiplication

Algebraic Matrix Multiplication



$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

Can be computed naively in $O(n^3)$ time.

Matrix multiplication algorithms

Complexity	Authors
n^3	—
$n^{2.81}$	Strassen (1969)
⋮	
$n^{2.38}$	Coppersmith, Winograd (1990)

Conjecture/Open problem: $n^{2+o(1)}$???

Multiplying 2×2 matrices

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22} \quad 8 \text{ multiplications}$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21} \quad 4 \text{ additions}$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

Works over any ring!

Multiplying $n \times n$ matrices

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

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$$C_{21} = A_{21}B_{11} + A_{22}B_{21} \quad 4 \text{ additions}$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

$$T(n) = 8 T(n/2) + O(n^2)$$

$$T(n) = O(n^{\log 8 / \log 2}) = O(n^3)$$

Strassen's 2×2 algorithm

$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22}$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21}$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

$$C_{11} = M_1 + M_4 - M_5 + M_7$$

$$C_{12} = M_3 + M_5$$

$$C_{21} = M_2 + M_4$$

$$C_{22} = M_1 - M_2 + M_3 + M_6$$

$$M_1 = (A_{11} + A_{12})(B_{11} + B_{21})$$

$$M_2 = (A_{21} + A_{22})(B_{11} + B_{12})$$

$$M_3 = A_{11}(B_{12} - B_{22})$$

$$M_4 = A_{22}(B_{21} - B_{11})$$

$$M_5 = (A_{11} + A_{12})B_{22}$$

$$M_6 = (A_{21} - A_{11})(B_{11} + B_{12})$$

$$M_7 = (A_{12} - A_{22})(B_{21} + B_{22})$$

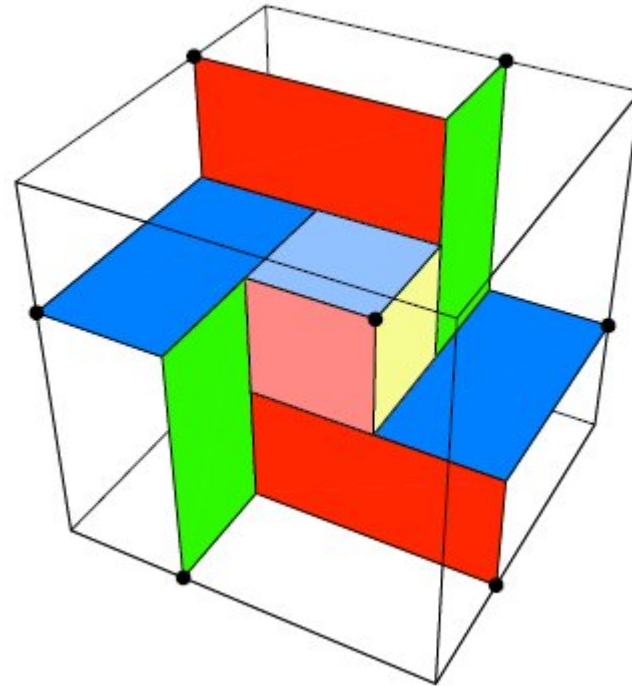
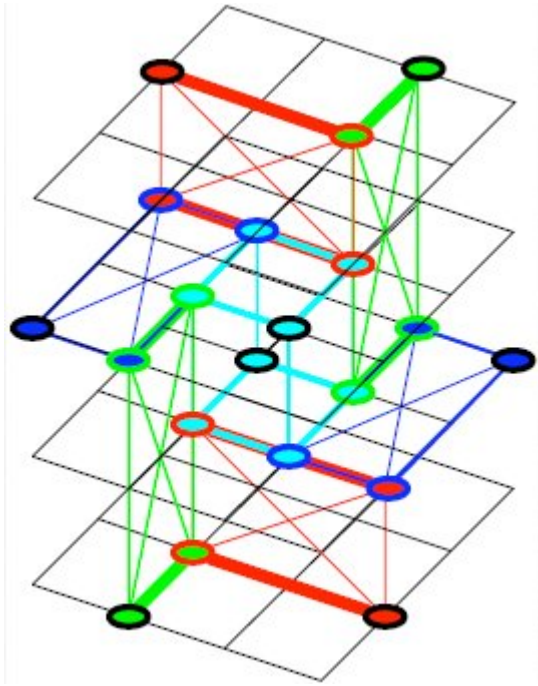
Subtraction!

7 multiplications

18 additions/subtractions

Works over any ring!

“Strassen Symmetry” (by Mike Paterson)



Strassen's $n \times n$ algorithm

View each $n \times n$ matrix as a 2×2 matrix whose elements are $n/2 \times n/2$ matrices.

Apply the 2×2 algorithm recursively.

$$T(n) = 7 T(n/2) + O(n^2)$$

$$T(n) = O(n^{\log 7 / \log 2}) = O(n^{2.81})$$

Matrix multiplication algorithms

The $O(n^{2.81})$ bound of **Strassen** was improved by **Pan**, **Bini-Capovani-Lotti-Romani**, **Schönhage** and finally by **Coppersmith and Winograd** to $O(n^{2.38})$.

The algorithms are much more complicated...

New **group theoretic approach** [Cohn-Umans '03]
[Cohn-Kleinberg-szegedy-Umans '05]

We let $2 \leq \omega < 2.38$ be the exponent of matrix multiplication.

Many believe that $\omega = 2 + o(1)$.

Determinants / Inverses

The title of **Strassen**'s 1969 paper is:
“Gaussian elimination is not optimal”

Other matrix operations that can
be performed in $O(n^\omega)$ time:

- Computing determinants: $\det A$
- Computing inverses: A^{-1}
- Computing **characteristic** polynomials

Matrix Multiplication Determinants / Inverses

What is it good for?

Transitive closure

Shortest Paths

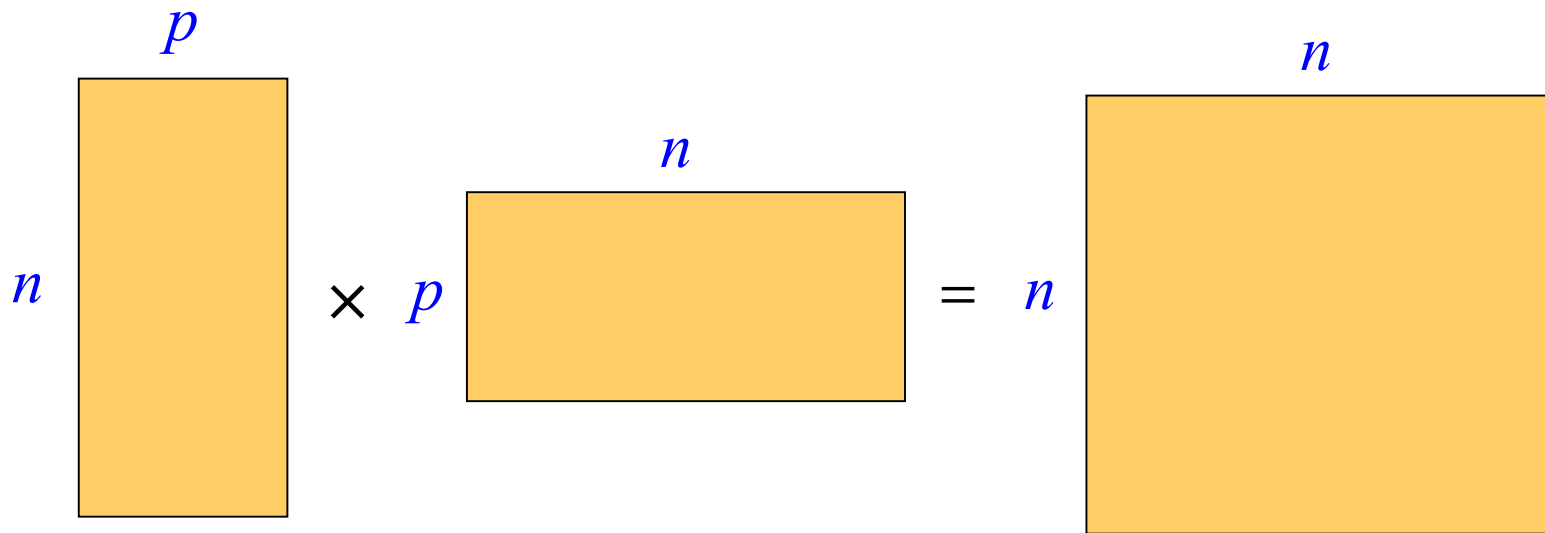
Perfect/Maximum matchings

Dynamic transitive closure

k-vertex connectivity

Counting spanning trees

Rectangular Matrix multiplication



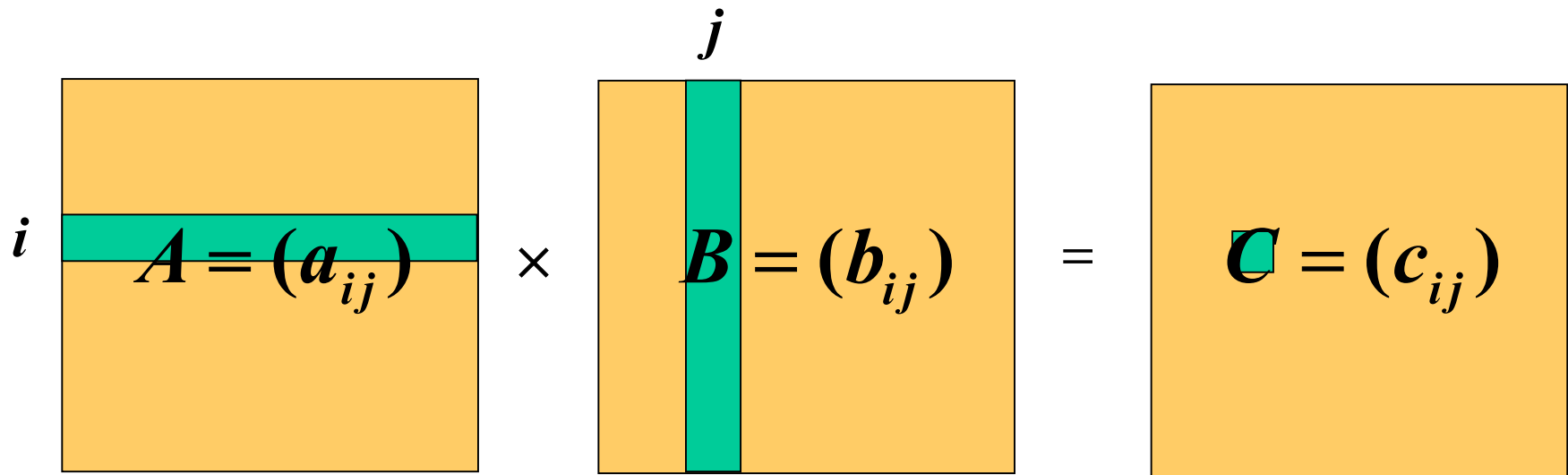
Naïve complexity: n^2p

[Coppersmith '97]: $n^{1.85}p^{0.54} + n^{2+o(1)}$

For $p \leq n^{0.29}$, complexity = $n^{2+o(1)}$!!!

BOOLEAN MATRIX
MULTIPLICATION
and
TRANSITIVE CLOSURE

Boolean Matrix Multiplication



$$c_{ij} = \bigvee_{k=1}^n a_{ik} \wedge b_{kj}$$

Can be computed naively in $O(n^3)$ time.

Algebraic Product

$$C = AB$$

$$c_{ij} = \sum_k a_{ik} b_{kj}$$

$O(n^{2.38})$
algebraic
operations

Boolean Product

$$C = A \cdot B$$

$$c_{ij} = \bigvee_k a_{ik} \wedge b_{kj}$$

$O(n^{2.38})$
But we can work
Logical \vee (\wedge)
over the integers!
operations on
has no inverse!
(modulo $n+1$)
 $O(\log n)$ bit words

Transitive Closure

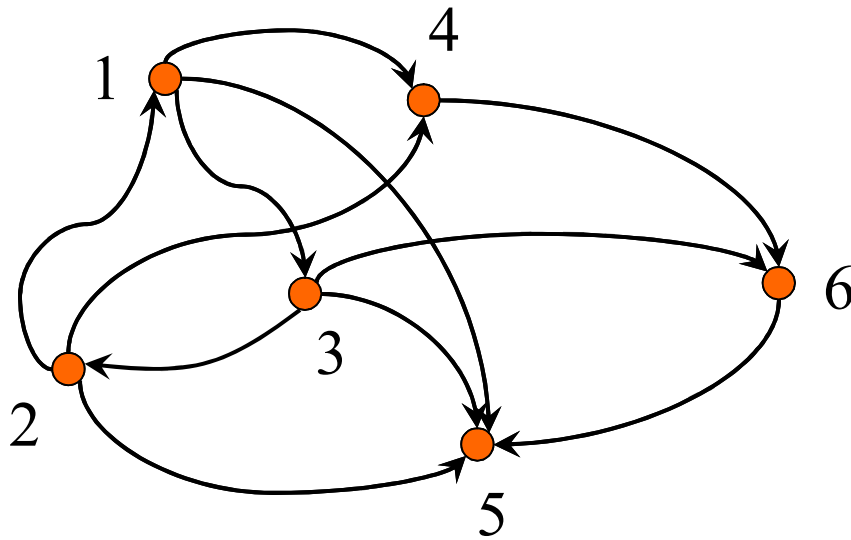
Let $G=(V,E)$ be a directed graph.

The **transitive closure** $G^*=(V,E^*)$ is the graph in which $(u,v) \in E^*$ iff there is a **path** from u to v .

Can be easily computed in $O(mn)$ time.

Can also be computed in $O(n^\omega)$ time.

Adjacency matrix of a directed graph



$$\begin{pmatrix} 0 & 0 & 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Exercise 0: If A is the adjacency matrix of a graph, then $(A^k)_{ij}=1$ iff there is a path of length k from i to j .

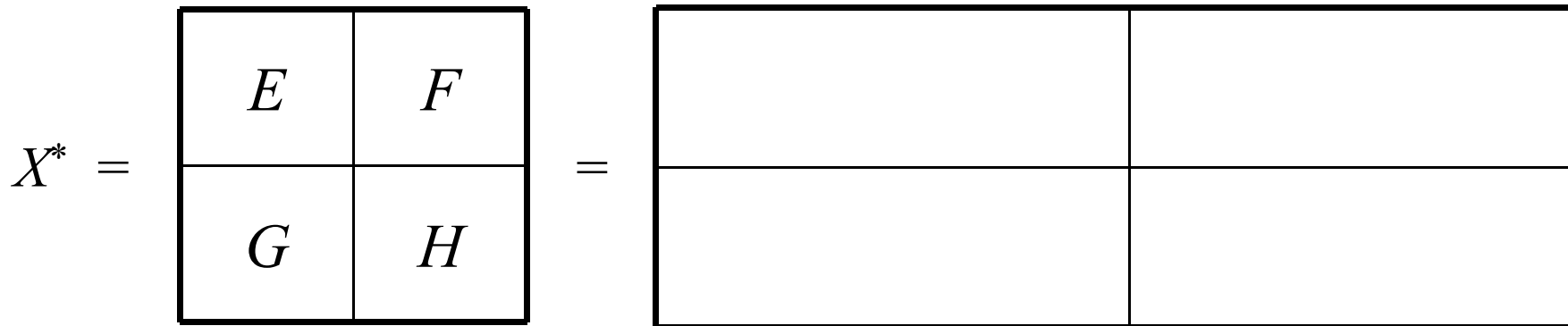
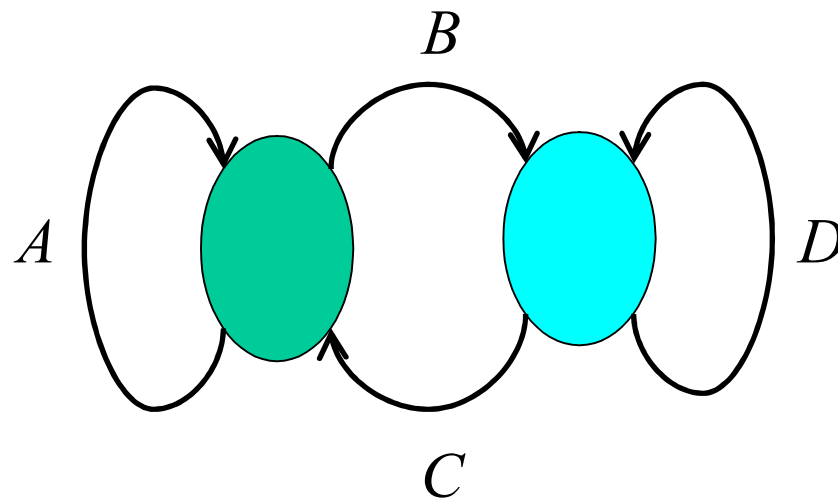
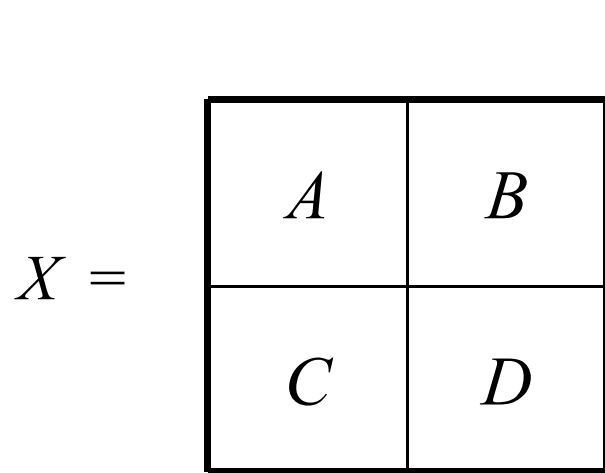
Transitive Closure using matrix multiplication

Let $G=(V,E)$ be a directed graph.

If A is the **adjacency matrix** of G ,
then $(A \vee I)^{n-1}$ is the adjacency matrix of G^* .

The matrix $(A \vee I)^{n-1}$ can be computed by $\log n$
squaring operations in $O(n^\omega \log n)$ time.

It can also be computed in $O(n^\omega)$ time.



$$\text{TC}(n) \leq 2 \text{TC}(n/2) + 6 \text{BMM}(n/2) + O(n^2)$$

Exercise 1: Give $O(n^\omega)$ algorithms for finding, in a directed graph,

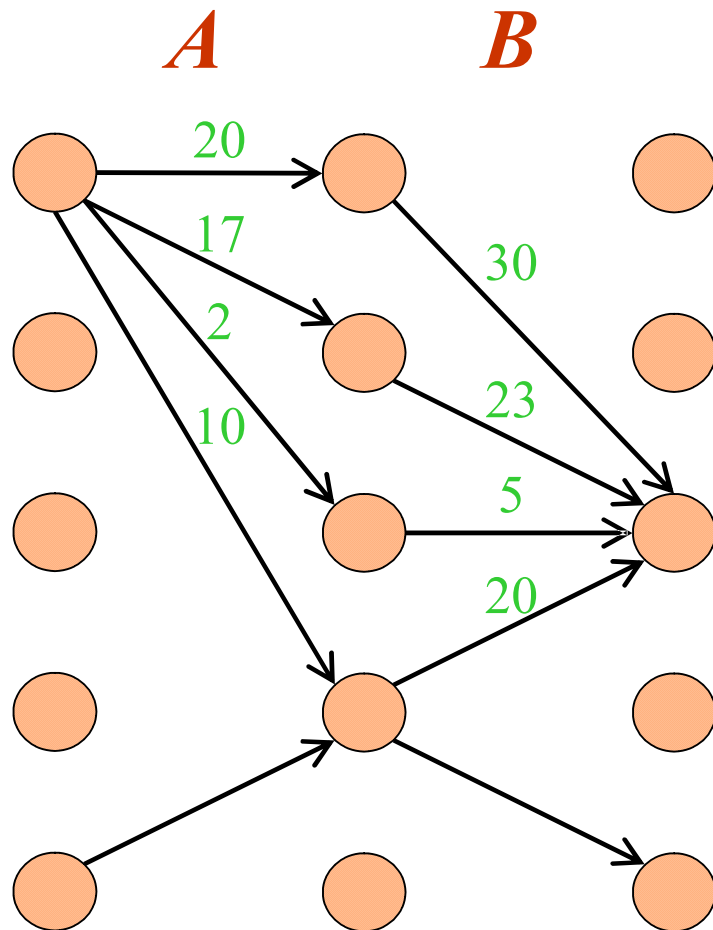
- a) a triangle
- b) a **simple** quadrangle
- c) a **simple** cycle of length k .

Hints:

1. In an **acyclic** graph all paths are simple.
2. In c) running time may be **exponential** in k .
3. **Randomization** makes solution much easier.

MIN-PLUS MATRIX
MULTIPLICATION
and
ALL-PAIRS
SHORTEST PATHS
(APSP)

An interesting special case of the APSP problem



$$C = A * B$$

$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}$$

Min-Plus product

Min-Plus Products

$$C = A * B$$

$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}$$

$$\begin{pmatrix} -6 & -3 & -10 \\ 2 & 5 & -2 \\ -1 & -7 & -5 \end{pmatrix} = \begin{pmatrix} 1 & -3 & 7 \\ +\infty & 5 & +\infty \\ 8 & 2 & -5 \end{pmatrix} * \begin{pmatrix} 8 & +\infty & -4 \\ -3 & 0 & -7 \\ 5 & -2 & 1 \end{pmatrix}$$

Solving APSP by repeated squaring

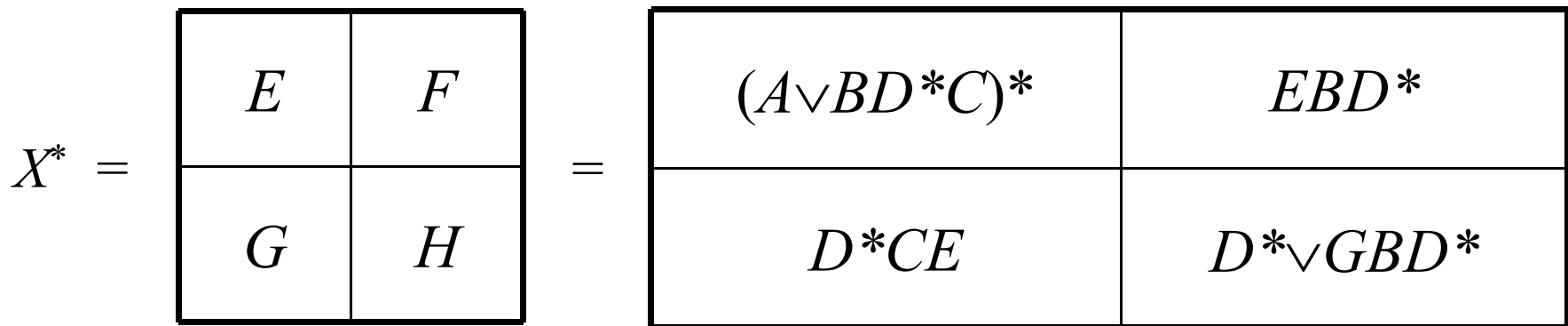
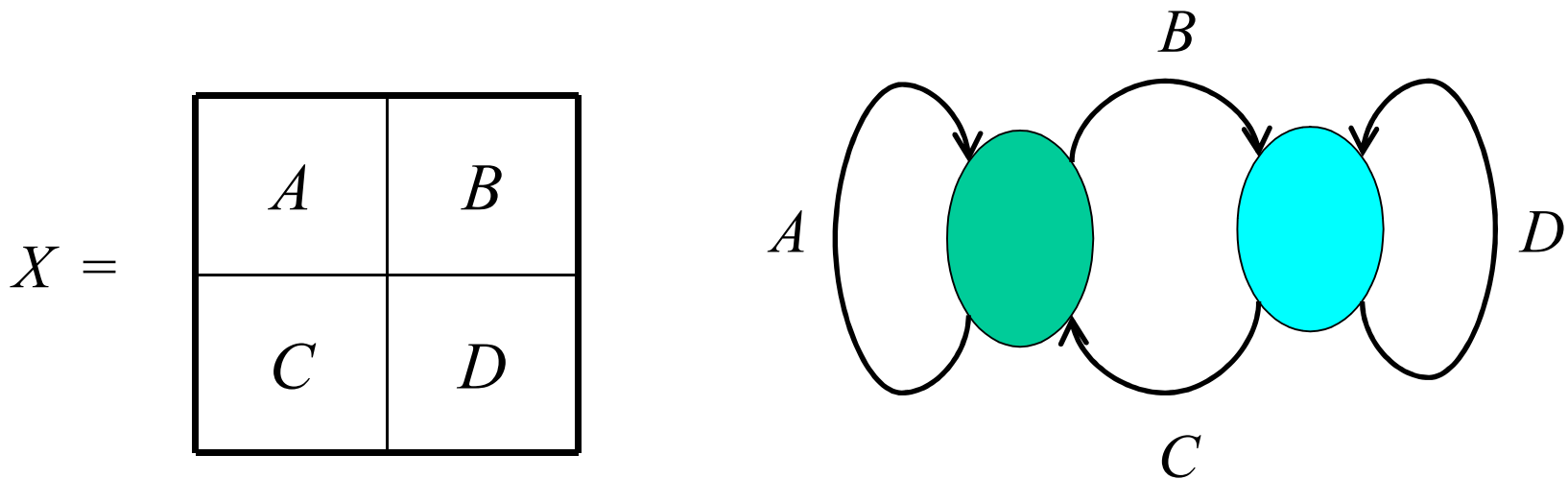
If W is an n by n matrix containing the edge weights of a graph. Then W^n is the distance matrix.

By induction, W^k gives the distances realized by paths that use at most k edges.

```
 $D \leftarrow W$   
for  $i \leftarrow 1$  to  $\lceil \log_2 n \rceil$   
do  $D \leftarrow D * D$ 
```

Thus: $APSP(n) \leq MPP(n) \log n$

Actually: $APSP(n) = O(MPP(n))$



$$\text{APSP}(n) \leq 2 \text{APSP}(n/2) + 6 \text{MPP}(n/2) + O(n^2)$$

Algebraic Product

$$C = A \cdot B$$

$$c_{ij} = \sum_k a_{ik} b_{kj}$$

$$O(n^{2.38})$$

Min-Plus Product

$$C = A * B$$

$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}$$

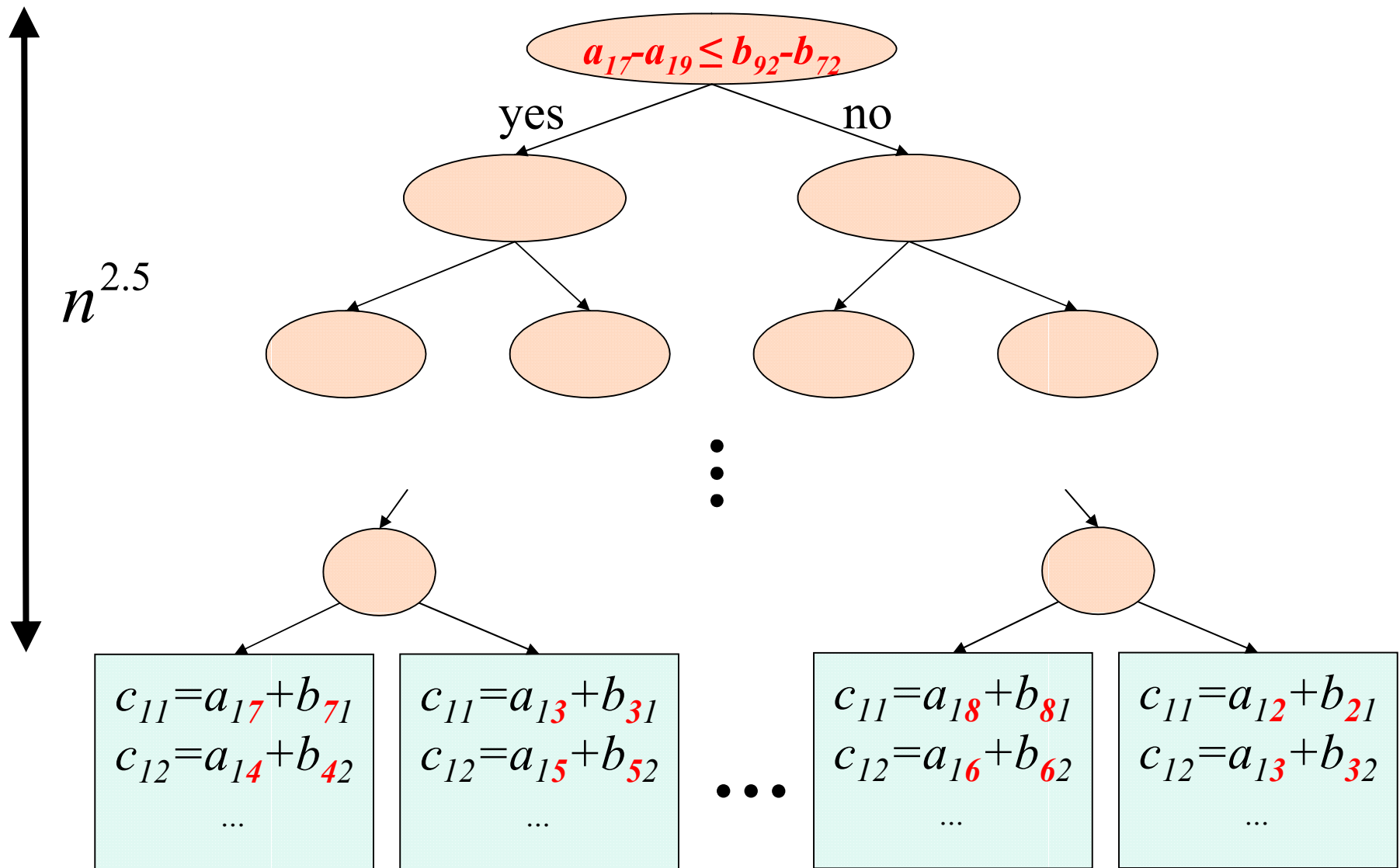
min operation
has no inverse!

Fredman's trick

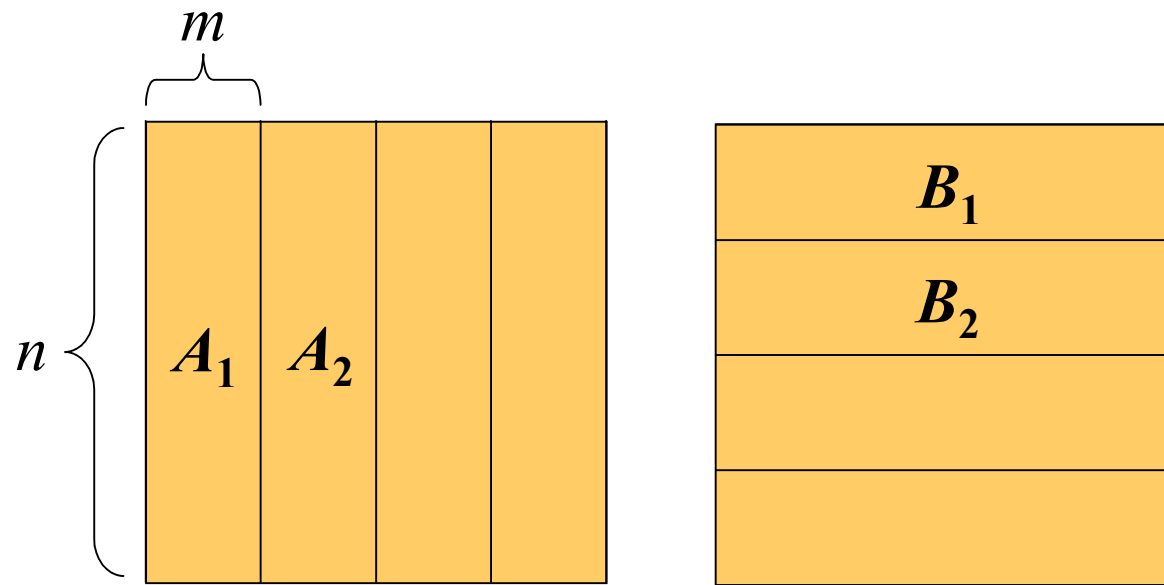
The **min-plus** product of two $n \times n$ matrices can be **deduced** after only $O(n^{2.5})$ additions and comparisons.

It is not known how to implement the algorithm in $O(n^{2.5})$ time.

Algebraic Decision Trees



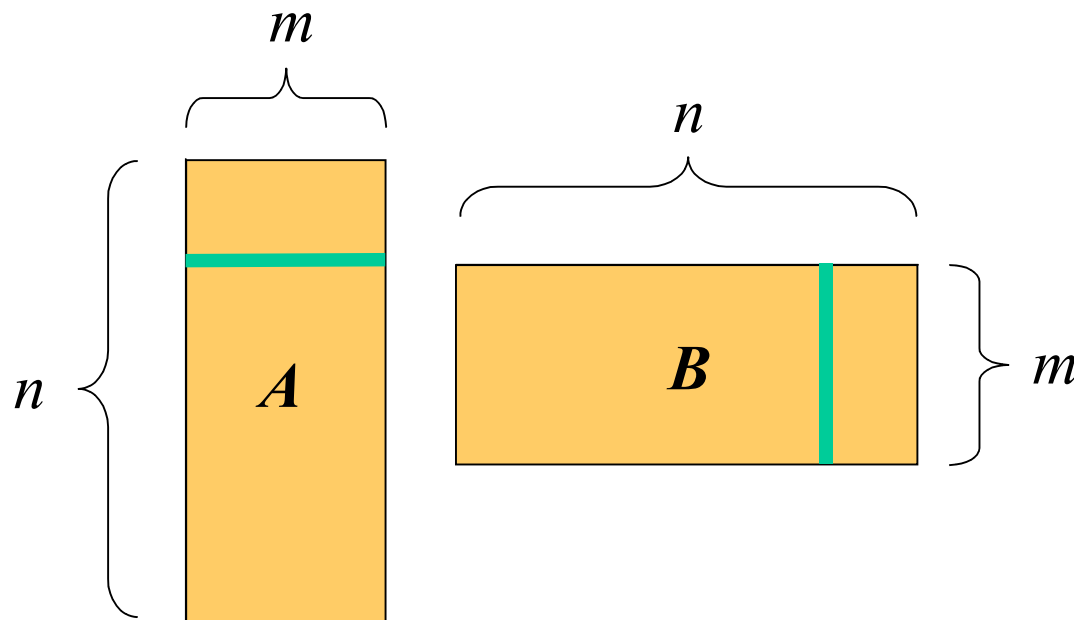
Breaking a square product into several rectangular products



$$A * B = \min_i A_i * B_i$$

$$\text{MPP}(n) \leq (n/m) (\text{MPP}(n, m, n) + n^2)$$

Fredman's trick



$$a_{ir} + b_{rj} \leq a_{is} + b_{sj}$$
$$\Leftrightarrow$$
$$a_{ir} - a_{is} \leq b_{sj} - b_{rj}$$

Naïve calculation requires n^2m operations

Fredman observed that the result can be **inferred** after performing only $O(nm^2)$ operations

Fredman's trick (cont.)

$$a_{ir} + b_{rj} \leq a_{is} + b_{sj} \iff a_{ir} - a_{is} \leq b_{sj} - b_{rj}$$

- **Generate** all the differences $a_{ir} - a_{is}$ and $b_{sj} - b_{rj}$.
- **Sort** them using $O(nm^2)$ comparisons. (Non-trivial!)
- **Merge** the two sorted lists using $O(nm^2)$ comparisons.

The ordering of the elements in the sorted list determines the result of the min-plus product
!!!

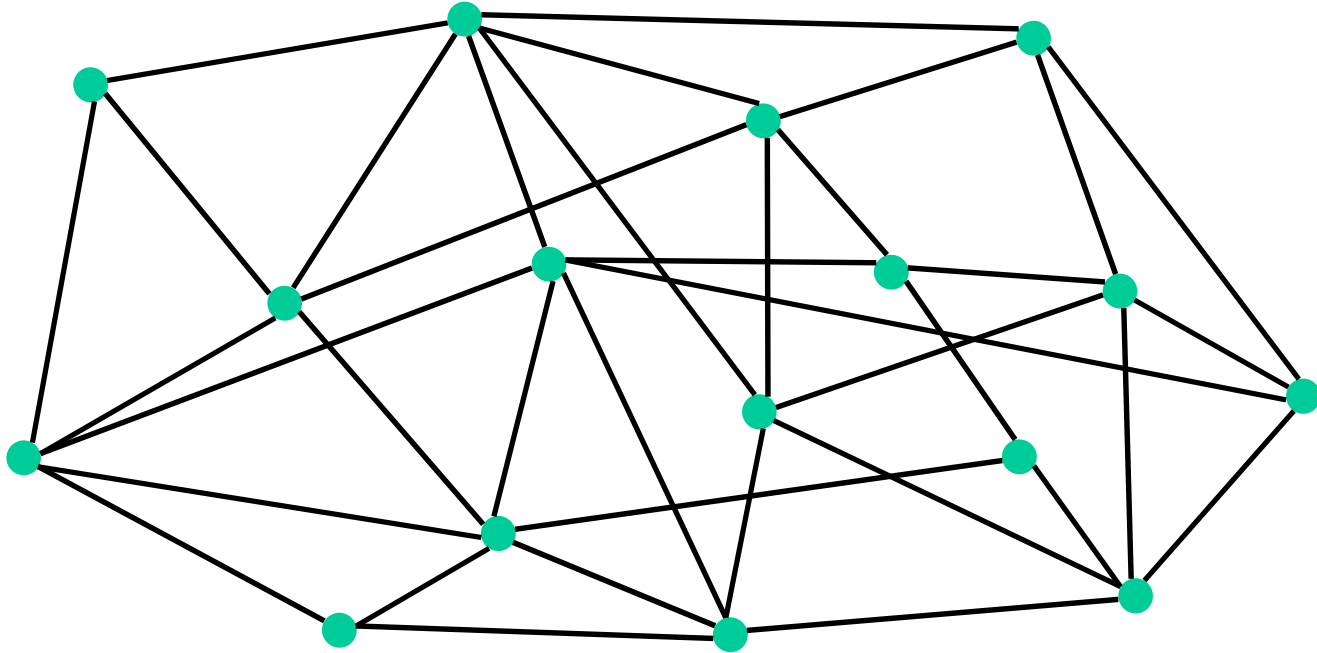
All-Pairs Shortest Paths

in directed graphs with “real” edge weights

Running time	Authors
n^3	[Floyd '62] [Warshall '62]
$n^3 (\log \log n / \log n)^{1/3}$	[Fredman '76]
$n^3 (\log \log n / \log n)^{1/2}$	[Takaoka '92]
$n^3 / (\log n)^{1/2}$	[Dobosiewicz '90]
$n^3 (\log \log n / \log n)^{5/7}$	[Han '04]
$n^3 \log \log n / \log n$	[Takaoka '04]
$n^3 (\log \log n)^{1/2} / \log n$	[Zwick '04]
$n^3 / \log n$	[Chan '05]
$n^3 (\log \log n / \log n)^{5/4}$	[Han '06]
$n^3 (\log \log n)^3 / (\log n)^2$	[Chan '07]

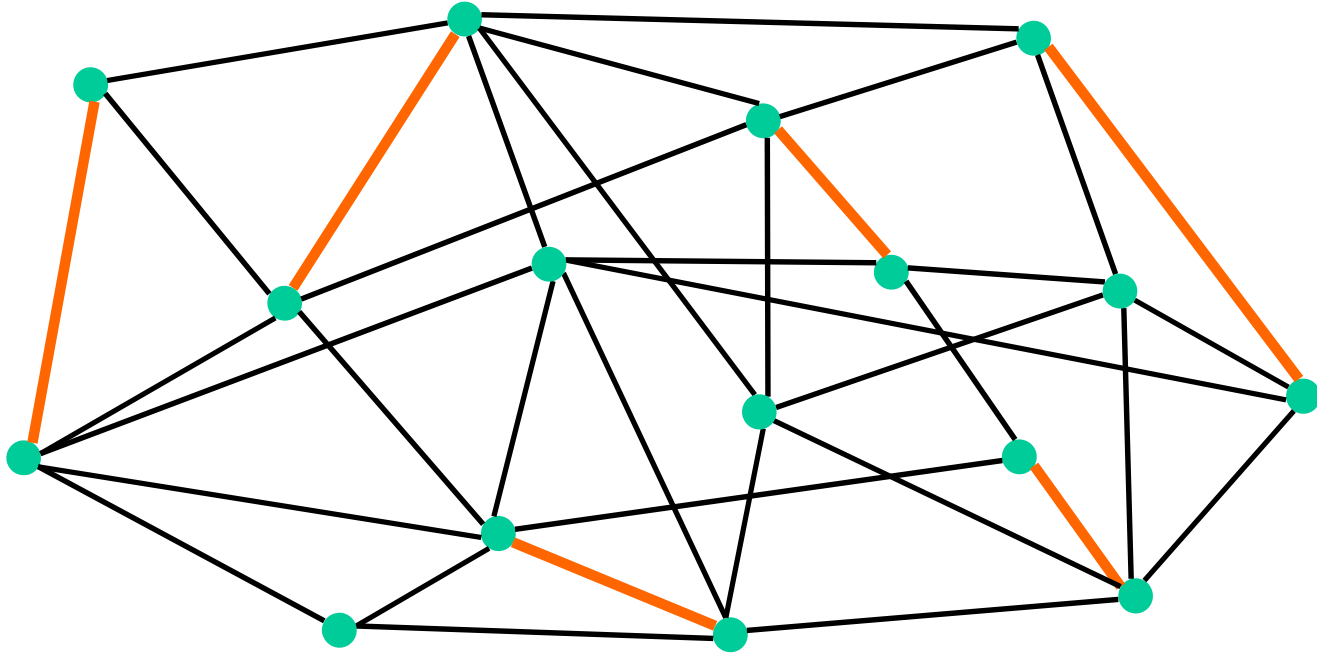
PERFECT MATCHINGS

Matchings



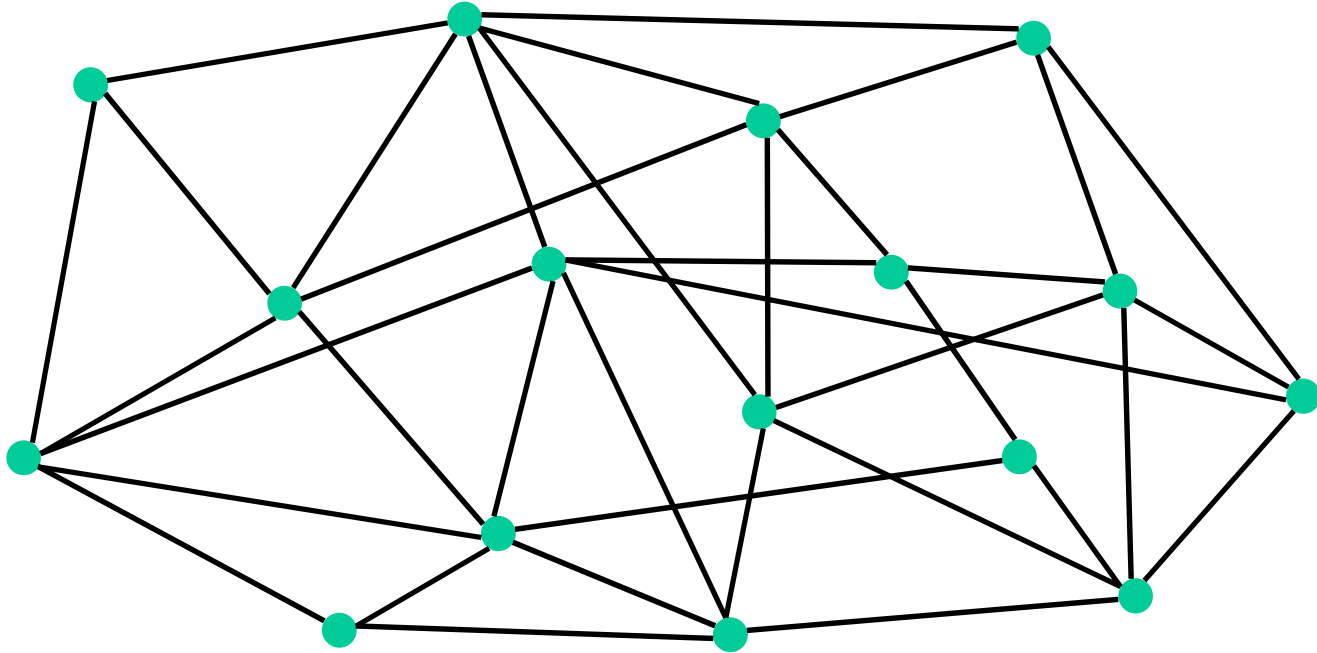
A **matching** is a subset of edges that do not touch one another.

Matchings



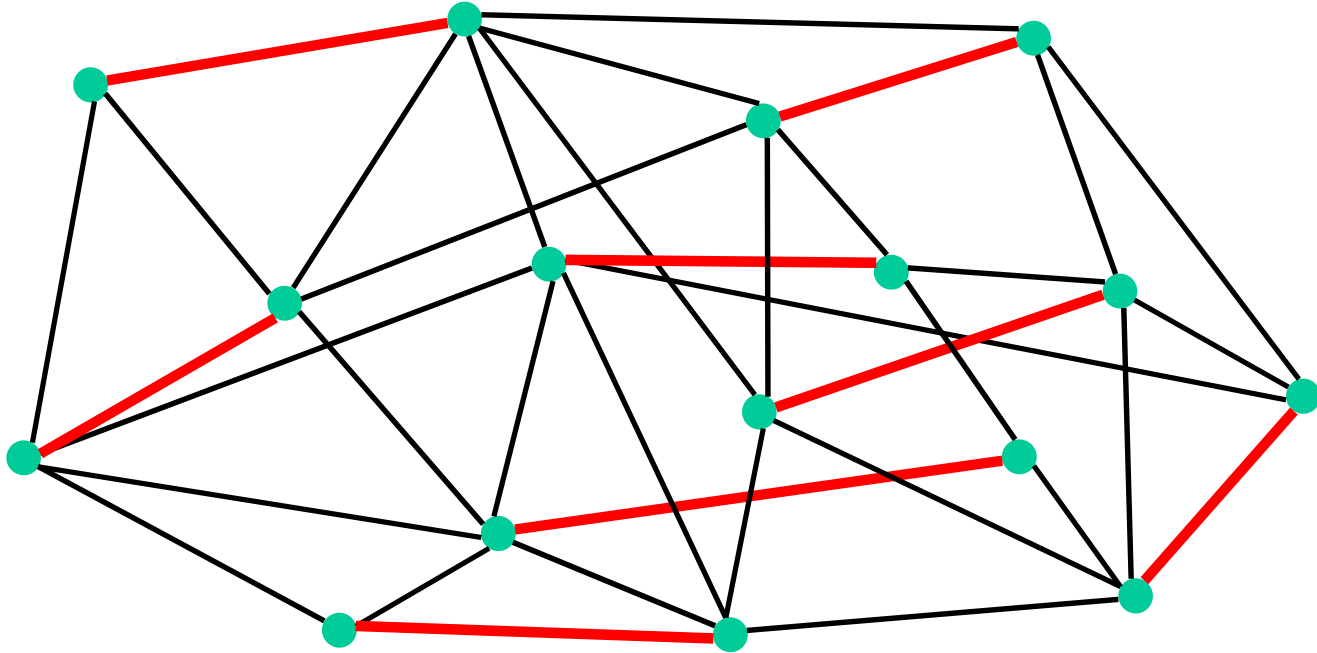
A **matching** is a subset of edges that do not touch one another.

Perfect Matchings



A matching is **perfect** if there are no unmatched vertices

Perfect Matchings



A matching is **perfect** if there are no unmatched vertices

Algorithms for finding perfect or maximum matchings

Combinatorial
approach:

A matching M is a
maximum matching iff it
admits no augmenting paths



Algorithms for finding perfect or maximum matchings

Combinatorial
approach:

A matching M is a
maximum matching iff it
admits no augmenting paths



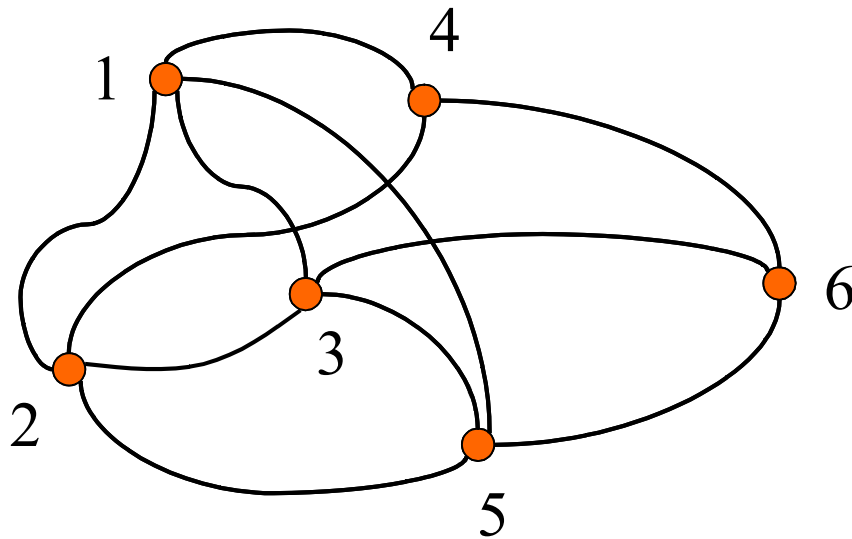
Combinatorial algorithms for finding perfect or maximum matchings

In **bipartite** graphs, augmenting paths can be found quite easily, and maximum matchings can be used using **max flow** techniques.

In **non-bipartite** the problem is much harder.
(**Edmonds'** Blossom shrinking techniques)

Fastest running time (in both cases):
 $O(mn^{1/2})$ [**Hopcroft-Karp**] [**Micali-Vazirani**]

Adjacency matrix of a undirected graph



$$\begin{pmatrix} 0 & 1 & 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 & 0 \end{pmatrix}$$

The adjacency matrix of an undirected graph is **symmetric**.

Matchings, Permanents, Determinants

$$\det(A) = \sum_{\pi \in S_n} \text{sign}(\pi) \prod_{i=1}^n a_{i\pi(i)}$$

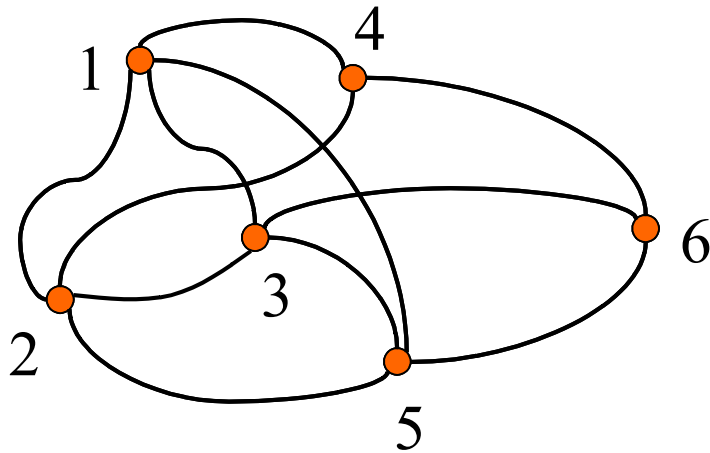
$$\text{per}(A) = \sum_{\pi \in S_n} \prod_{i=1}^n a_{i\pi(i)}$$

Exercise 2: Show that if A is the adjacency matrix of a **bipartite** graph G , then $\text{per}(A)$ is the number of perfect matchings in G .

Unfortunately computing the permanent is **#P-complete**...

Tutte's matrix

(Skew-symmetric symbolic adjacency matrix)



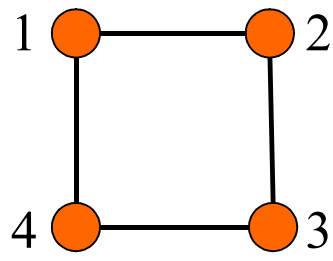
$$\begin{pmatrix} 0 & x_{12} & x_{13} & x_{14} & x_{15} & 0 \\ -x_{12} & 0 & x_{23} & x_{24} & x_{25} & 0 \\ -x_{13} & -x_{23} & 0 & 0 & x_{35} & x_{36} \\ -x_{14} & -x_{24} & 0 & 0 & 0 & x_{46} \\ -x_{15} & -x_{25} & -x_{35} & 0 & 0 & x_{56} \\ 0 & 0 & -x_{36} & -x_{46} & -x_{56} & 0 \end{pmatrix}$$

$$a_{ij} = \begin{cases} x_{ij} & \text{if } \{i, j\} \in E \text{ and } i < j, \\ -x_{ji} & \text{if } \{i, j\} \in E \text{ and } i > j, \\ 0 & \text{otherwise} \end{cases}$$

$$A^T = -A$$

Tutte's theorem

Let $G=(V,E)$ be a graph and let A be its Tutte matrix. Then, G has a perfect matching iff $\det A \neq 0$.

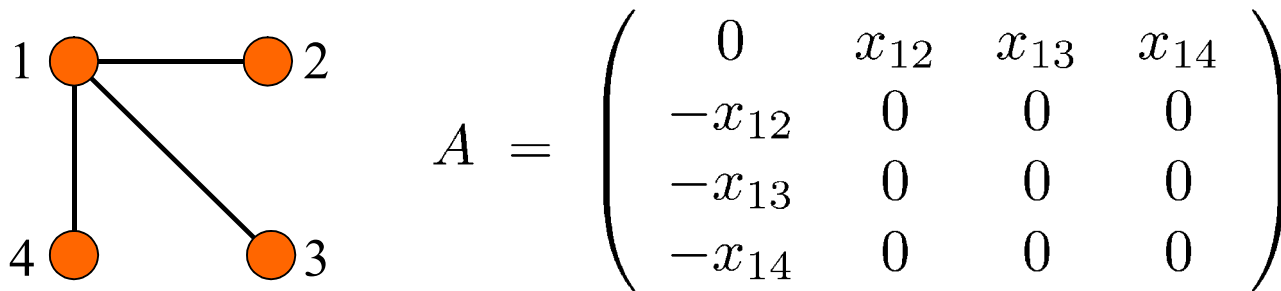

$$A = \begin{pmatrix} 0 & x_{12} & 0 & x_{14} \\ -x_{12} & 0 & x_{23} & 0 \\ 0 & -x_{23} & 0 & -x_{34} \\ -x_{14} & 0 & -x_{34} & 0 \end{pmatrix}$$

$$\det A = x_{12}^2 x_{34}^2 + x_{14}^2 x_{23}^2 + 2x_{12}x_{23}x_{34}x_{41} \neq 0$$

There are perfect matchings

Tutte's theorem

Let $G=(V,E)$ be a graph and let A be its Tutte matrix. Then, G has a perfect matching iff $\det A \neq 0$.



$$\det A = 0$$

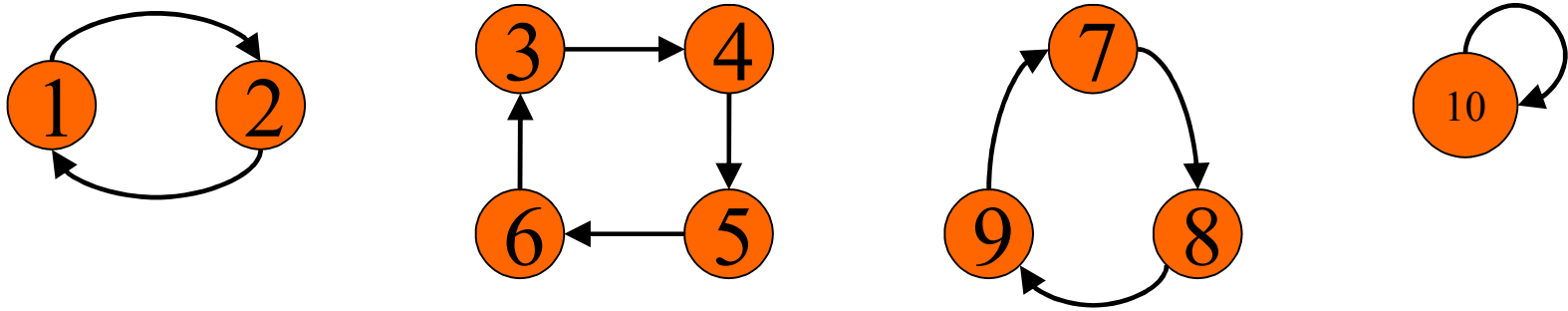
No perfect matchings

Proof of Tutte's theorem

$$\det A = \sum_{\pi \in S_n} \text{sign}(\pi) \prod_{i=1}^n a_{i\pi(i)}$$

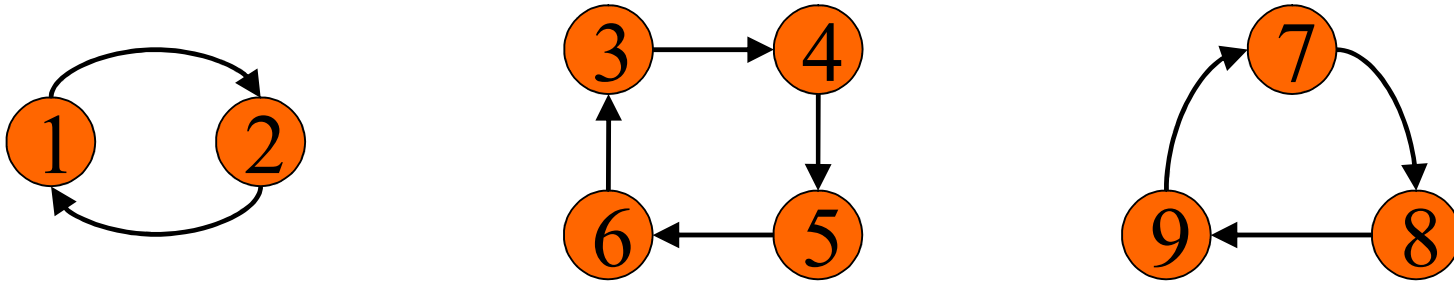
Every permutation $\pi \in S_n$ defines a **cycle collection**

$$\pi = (2 \ 1 \ 4 \ 5 \ 6 \ 3 \ 8 \ 9 \ 7 \ 10)$$



Cycle covers

A permutation $\pi \in S_n$ for which $\{i, \pi(i)\} \in E$, for $1 \leq i \leq k$, defines a **cycle cover** of the graph.

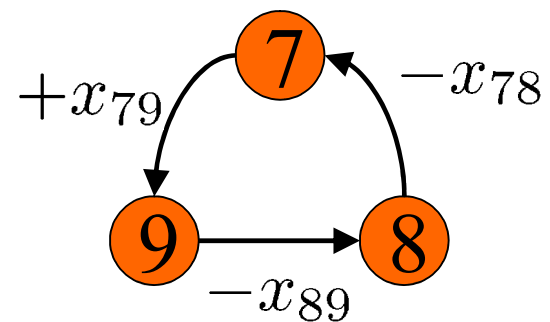
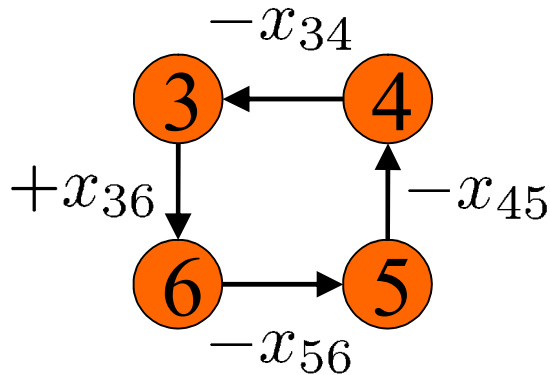
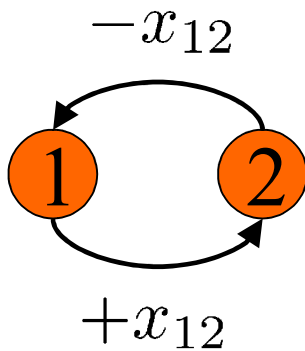
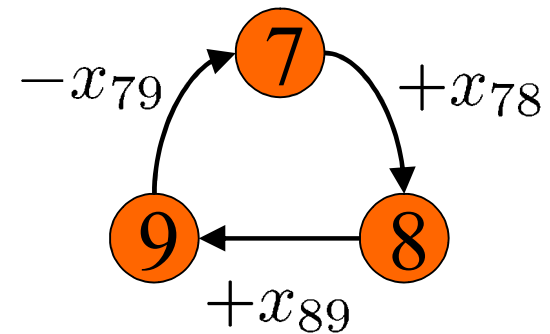
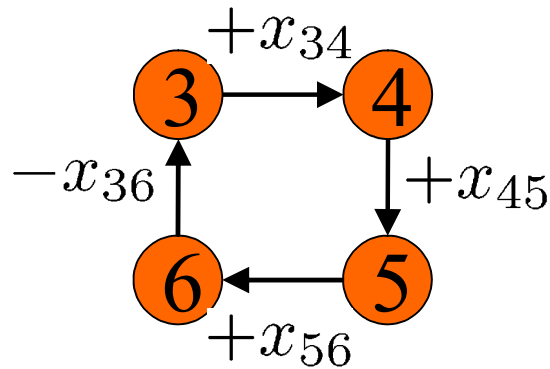
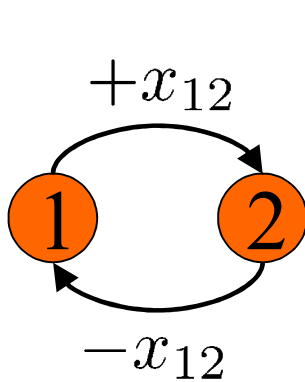


Exercise 3: If π' is obtained from π by **reversing** the direction of a cycle, then $sign(\pi') = sign(\pi)$.

$$\prod_{i=1}^n a_{i\pi'(i)} = \pm \prod_{i=1}^n a_{i\pi(i)}$$

Depending on the parity of the cycle!

Reversing Cycles



$$\prod_{i=1}^n a_{i\pi'(i)} = \pm \prod_{i=1}^n a_{i\pi(i)}$$

Depending on the parity of the cycle!

Proof of Tutte's theorem (cont.)

$$\det A = \sum_{\pi \in S_n} \text{sign}(\pi) \prod_{i=1}^n a_{i\pi(i)}$$

The permutations $\pi \in S_n$ that contain an **odd** cycle cancel each other!

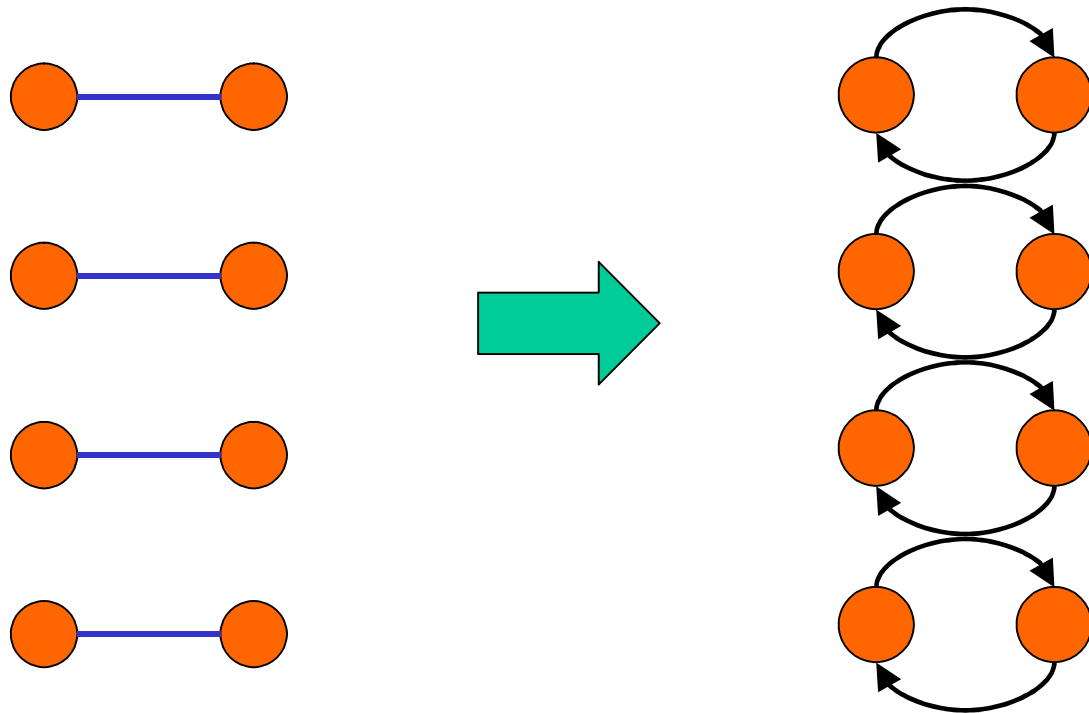
We effectively sum only over **even cycle covers**.

A graph contains a perfect matching
iff it contains an **even cycle cover**.

Proof of Tutte's theorem (cont.)

A graph contains a perfect matching
iff it contains an **even cycle cover**.

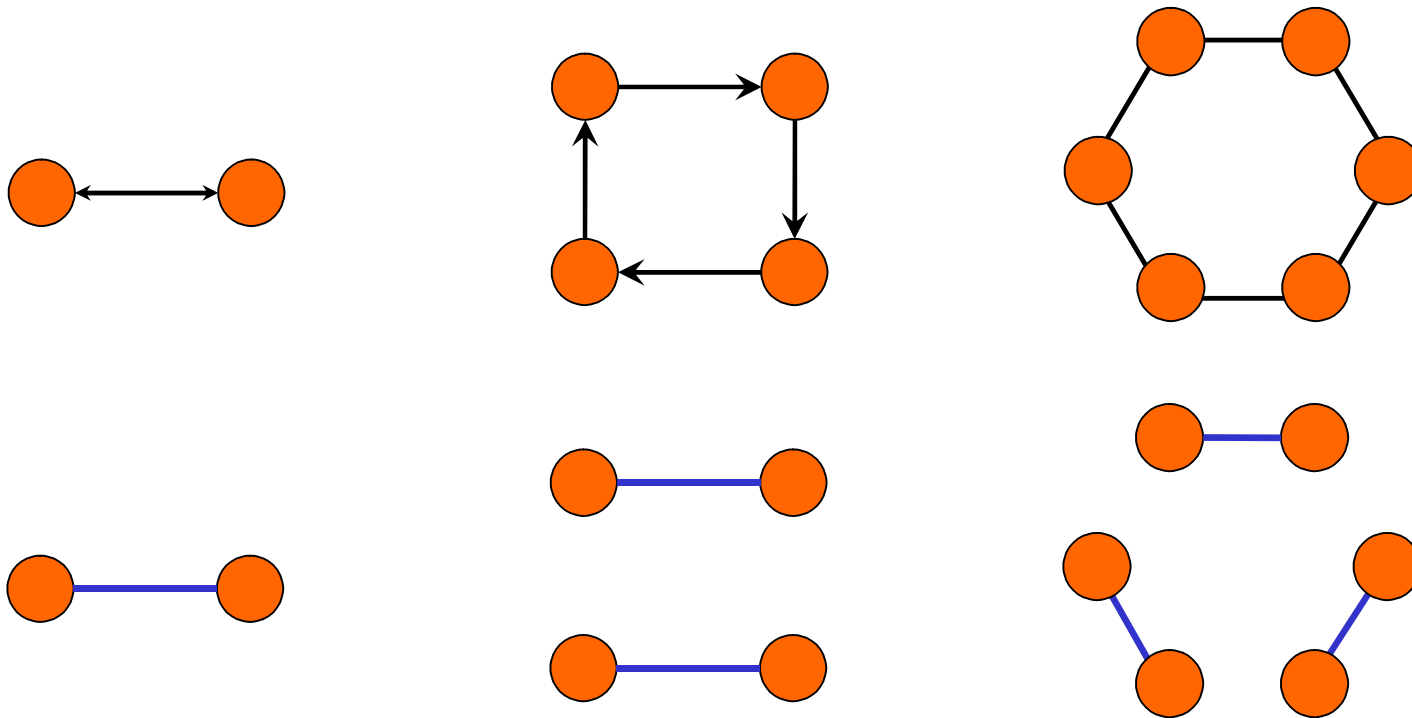
Perfect Matching \rightarrow Even cycle cover



Proof of Tutte's theorem (cont.)

A graph contains a perfect matching
iff it contains an **even cycle cover**.

Even cycle cover \rightarrow Perfect matching



An algorithm for perfect matchings?

- Construct the Tutte matrix A .
- Compute $\det A$.
- If $\det A \neq 0$, say ‘yes’, otherwise ‘no’.

Problem:

$\det A$ is a **symbolic** expression that may be of **exponential** size!

Lovasz's solution:

Replace each variable x_{ij} by a random element of \mathbb{Z}_p , where $p = \Theta(n^2)$ is a prime number

The Schwartz-Zippel lemma

Let $P(x_1, x_2, \dots, x_n)$ be a polynomial of degree d over a field F . Let $S \subseteq F$. If $P(x_1, x_2, \dots, x_n) \neq 0$ and a_1, a_2, \dots, a_n are chosen randomly and independently from S , then

$$\Pr[P(a_1, a_2, \dots, a_n) = 0] \leq \frac{d}{|S|}$$

Proof by induction on n .

For $n=1$, follows from the fact that polynomial of degree d over a field has at most d roots

Lovasz's algorithm for existence of perfect matchings

- Construct the Tutte matrix A .
- Replace each variable x_{ij} by a random element of Z_p , where $p = O(n^2)$ is prime.
- Compute $\det A$.
- If $\det A \neq 0$, say 'yes', otherwise 'no'.

If algorithm says 'yes', then
the graph contains a perfect matching.

If the graph contains a perfect matching, then
the probability that the algorithm says 'no',
is at most $O(1/n)$.

Parallel algorithms

Determinants can be computed
very quickly in **parallel**

$$\text{DET} \in \text{NC}^2$$

Perfect matchings can be detected
very quickly in **parallel** (using **randomization**)

$$\text{PERFECT-MATCH} \in \text{RNC}^2$$

Open problem:

??? PERFECT-MATCH \in NC ???

Finding perfect matchings

Self Reducibility

Delete an edge and check whether there is still a perfect matching

Needs $O(n^2)$ determinant computations

Running time $O(n^{\omega+2})$

Fairly slow...

Not parallelizable!

Finding perfect matchings

Rabin-Vazirani (1986): An edge $\{i,j\} \in E$ is contained in a perfect matching iff $(A^{-1})_{ij} \neq 0$.

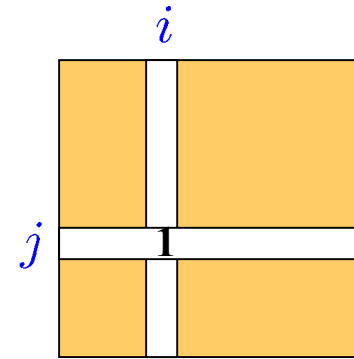
Leads immediately to an $O(n^{\omega+1})$ algorithm:
Find an **allowed** edge $\{i,j\} \in E$, delete it and its vertices from the graph, and **recompute** A^{-1} .

Mucha-Sankowski (2004): Recomputing A^{-1} from scratch is very wasteful. Running time can be reduced to $O(n^{\omega})$!

Harvey (2006): A simpler $O(n^{\omega})$ algorithm.

Adjoint and Cramer's rule

$$(\text{adj}(A))_{ij} = (-1)^{i+j} \det(A^{j,i}) = \det$$



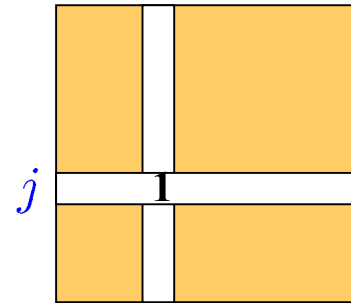
A with the j -th row
and i -th column deleted

Cramer's rule: $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$

Finding perfect matchings

Rabin-Vazirani (1986): An edge $\{i,j\} \in E$ is contained in a perfect matching iff $(A^{-1})_{ij} \neq 0$.

$$(\text{adj}(A))_{ij} = (-1)^{i+j} \det(A^{j,i}) = \det$$



Leads immediately to an $O(n^{\omega+1})$ algorithm:
Find an **allowed** edge $\{i,j\} \in E$, delete it and its vertices from the graph, and **recompute** A^{-1} .

Still not parallelizable

Finding unique minimum weight perfect matchings

[Mulmuley-Vazirani-Vazirani (1987)]

Suppose that edge $\{i,j\} \in E$ has integer weight w_{ij}

Suppose that there is a unique minimum weight perfect matching M of total weight W

Replace x_{ij} by $2^{w_{ij}}$

Then, $2^{2W} \mid \det(A)$ but $2^{2W+1} \nmid \det(A)$

Furthermore, $\{i,j\} \in M$ iff $\frac{2^{w_{ij}} \det(A^{ij})}{2^{2W}}$ is odd

Isolating lemma

[Mulmuley-Vazirani-Vazirani (1987)]

Suppose that G has a perfect matching

Assign each edge $\{i,j\} \in E$
a **random** integer weight $w_{ij} \in [1, 2m]$

With probability of at least $\frac{1}{2}$, the minimum weight perfect matching of G is unique

Lemma holds for general collections of sets,
not just perfect matchings

Proof of Isolating lemma

[Mulmuley-Vazirani-Vazirani (1987)]

An edge $\{i,j\}$ is **ambivalent** if there is a minimum weight perfect matching that contains it and another that does not

Suppose that weights were assigned
to all edges except for $\{i,j\}$

Let a_{ij} be the **largest** weight for which $\{i,j\}$ participates in
some minimum weight perfect matchings

If $w_{ij} < a_{ij}$, then $\{i,j\}$ participates in
all minimum weight perfect matchings

The probability that $\{i,j\}$ is ambivalent is at most $1/(2m)!$

Finding perfect matchings

[Mulmuley-Vazirani-Vazirani (1987)]

Choose **random** weights in $[1, 2m]$

Compute determinant and adjoint

Read off a perfect matching (w.h.p.)

Is using m -bit integers **cheating**?

Not if we are willing to pay for it!

Complexity is $O(mn^\omega) \leq O(n^{\omega+2})$

Finding perfect matchings in RNC²

Improves an RNC³ algorithm by

[Karp-Upfal-Wigderson (1986)]

Multiplying two N -bit numbers

“School method”

$$N^2$$

[Schönhage-Strassen (1971)]

$$N \log N \log \log N$$

[Fürer (2007)]

[De-Kurur-Saha-Saptharishi (2008)]

$$N \log N 2^{O(\log^* N)}$$

For our purposes... $\tilde{O}(N)$

Finding perfect matchings

We are not over yet...

[Mucha-Sankowski (2004)]

Recomputing A^{-1} from scratch is wasteful.

Running time can be reduced to $O(n^\omega)$!

[Harvey (2006)]

A simpler $O(n^\omega)$ algorithm.

Using matrix multiplication to compute min-plus products

$$\begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \\ & & \mathbf{0} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ & & \mathbf{0} \end{pmatrix} * \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \\ & & \mathbf{0} \end{pmatrix}$$

$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}$$

$$\begin{pmatrix} c'_{11} & c'_{12} \\ c'_{21} & c'_{22} \\ & & \mathbf{0} \end{pmatrix} = \begin{pmatrix} x^{a_{11}} & x^{a_{12}} \\ x^{a_{21}} & x^{a_{22}} \\ & & \mathbf{0} \end{pmatrix} \times \begin{pmatrix} x^{b_{11}} & x^{b_{12}} \\ x^{b_{21}} & x^{b_{22}} \\ & & \mathbf{0} \end{pmatrix}$$

$$c'_{ij} = \sum_k x^{a_{ik} + b_{kj}}$$

$$c_{ij} = \text{first}(c'_{ij})$$

Using matrix multiplication to compute min-plus products

Assume: $0 \leq a_{ij}, b_{ij} \leq M$

$$\begin{pmatrix} c'_{11} & c'_{12} \\ c'_{21} & c'_{22} \\ & & \mathbf{0} \end{pmatrix} = \begin{pmatrix} x^{a_{11}} & x^{a_{12}} \\ x^{a_{21}} & x^{a_{22}} \\ & & \mathbf{0} \end{pmatrix} * \begin{pmatrix} x^{b_{11}} & x^{b_{12}} \\ x^{b_{21}} & x^{b_{22}} \\ & & \mathbf{0} \end{pmatrix}$$

n^ω		M		Mn^ω
polynomial products	×	operations per polynomial product	*	operations per max-plus product

SHORTEST PATHS

APSP – All-Pairs Shortest Paths

SSSP – Single-Source Shortest Paths

UNWEIGHTED
UNDIRECTED
SHORTEST PATHS

4. APSP in undirected graphs

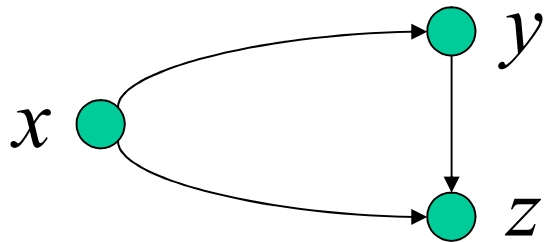
- ➔ a. An $O(n^{2.38})$ algorithm for **unweighted** graphs (**Seidel**)
- b. An $O(Mn^{2.38})$ algorithm for **weighted** graphs (**Shoshan-Zwick**)

5. APSP in directed graphs

1. An $O(M^{0.68}n^{2.58})$ algorithm (**Zwick**)
2. An $O(Mn^{2.38})$ preprocessing / $O(n)$ query answering algorithm (**Yuster-Zwick**)
3. An $O(n^{2.38}\log M)$ $(1+\varepsilon)$ -approximation algorithm

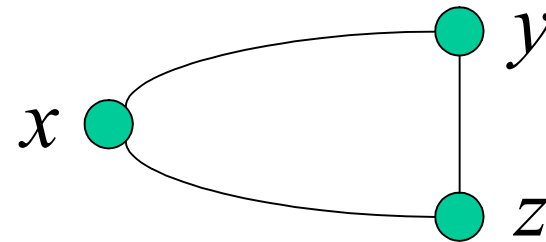
6. Summary and open problems

Directed versus undirected graphs



$$\delta(x,z) \leq \delta(x,y) + \delta(y,z)$$

Triangle inequality



$$\delta(x,z) \leq \delta(x,y) + \delta(y,z)$$

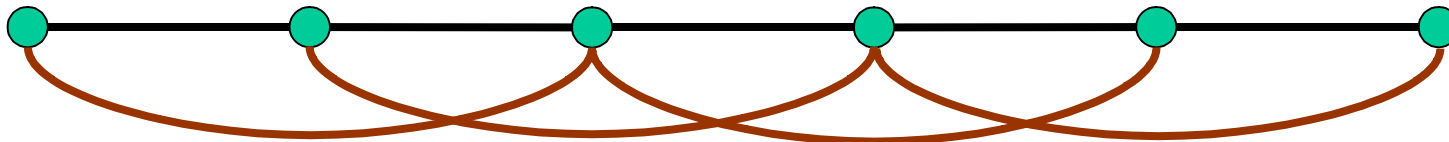
$$\delta(x,y) \leq \delta(x,z) + \delta(z,y)$$

$$\delta(x,z) \geq \delta(x,y) - \delta(y,z)$$

Inverse triangle inequality

Distances in G and its square G^2

Let $G=(V,E)$. Then $G^2=(V,E^2)$, where $(u,v) \in E^2$ if and only if $(u,v) \in E$ or there exists $w \in V$ such that $(u,w), (w,v) \in E$



Let $\delta(u,v)$ be the distance from u to v in G .
Let $\delta^2(u,v)$ be the distance from u to v in G^2 .

Distances in G and its square G^2 (cont.)

Lemma: $\delta^2(u,v) = \lceil \delta(u,v)/2 \rceil$, for every $u,v \in V$.



$$\delta^2(u,v) \leq \lceil \delta(u,v)/2 \rceil$$



$$\delta(u,v) \leq 2\delta^2(u,v)$$

Thus: $\delta(u,v) = 2\delta^2(u,v)$ or
 $\delta(u,v) = 2\delta^2(u,v) - 1$

Distances in G and its square G^2 (cont.)

Lemma: If $\delta(u,v) = 2\delta^2(u,v)$ then for every neighbor w of v we have $\delta^2(u,w) \geq \delta^2(u,v)$.

Lemma: If $\delta(u,v) = 2\delta^2(u,v) - 1$ then for every neighbor w of v we have $\delta^2(u,w) \leq \delta^2(u,v)$ and for at least one neighbor $\delta^2(u,w) < \delta^2(u,v)$.

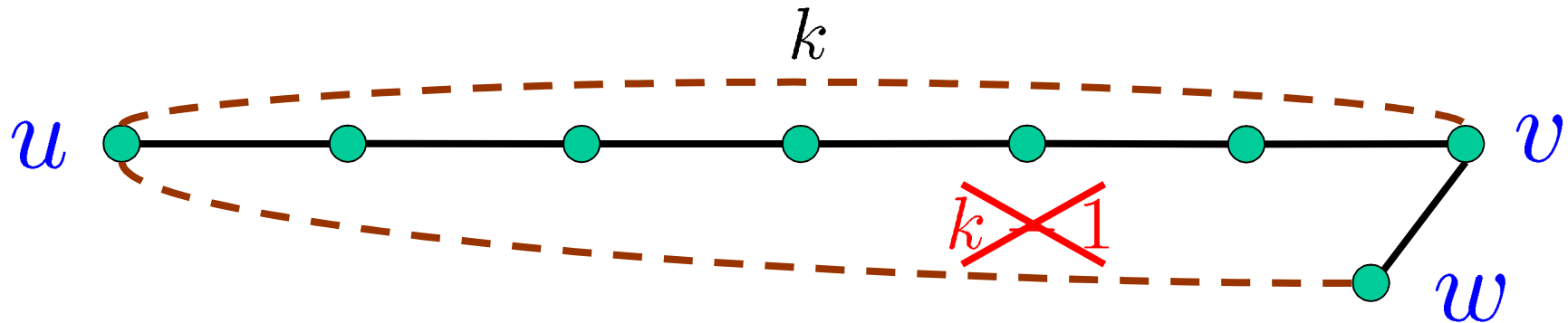
Let A be the adjacency matrix of the G .

Let C be the distance matrix of G^2

$$\sum_{(v,w) \in E} c_{uw} = \sum_{w \in V} c_{uw} a_{wv} = (CA)_{uv} \geq \deg(v) c_{uv}$$

Even distances

Lemma: If $\delta(u,v) = 2\delta^2(u,v)$ then for every neighbor w of v we have $\delta^2(u,w) \geq \delta^2(u,v)$.



Let A be the adjacency matrix of the G .

Let C be the distance matrix of G^2

$$\sum_{(v,w) \in E} c_{uw} = \sum_{w \in V} c_{uw} a_{wv} = (CA)_{uv} \geq \deg(v) c_{uv}$$

Odd distances

Lemma: If $\delta(u,v) = 2\delta^2(u,v) - 1$ then for every neighbor w of v we have $\delta^2(u,w) \leq \delta^2(u,v)$ and for at least one neighbor $\delta^2(u,w) < \delta^2(u,v)$.

Exercise 4: Prove the lemma.

Let A be the adjacency matrix of the G .

Let C be the distance matrix of G^2

$$\sum_{(v,w) \in E} c_{uw} = \sum_{w \in V} c_{uw} a_{wv} = (CA)_{uv} < \deg(v) c_{uv}$$

Seide

Assume that A has 1's on the diagonal.

1. If A is an all one matrix, then all distances are 1.
2. Compute A^2 , the adjacency matrix of the squared graph.
3. Find, recursively, the distances in the squared graph.
4. Decide, using one integer matrix multiplication, for every two vertices u, v , whether their distance is **twice** the distance in the square, or **twice minus 1**.

Boolean matrix multiplication

else

$C \leftarrow \text{APD}(A^2)$

$X \leftarrow CA, \text{deg} \leftarrow Ae-1$

Integer matrix multiplication

Complexity:

$O(n^{\omega} \log n)$

Exercise 5: (*) Obtain a version of Seidel's algorithm that uses only **Boolean** matrix multiplications.

Hint: Look at distances also modulo 3.

Distances vs. Shortest Paths

We described an algorithm for computing all **distances**.

How do we get a representation of the **shortest paths**?

We need **witnesses** for the Boolean matrix multiplication.

Witnesses for Boolean Matrix Multiplication

$$C = AB$$
$$c_{ij} = \bigvee_{k=1}^n a_{ik} \wedge b_{kj}$$

A matrix W is a matrix of **witnesses** iff

If $c_{ij} = 0$ then $w_{ij} = 0$

If $c_{ij} = 1$ then $w_{ij} = k$ where $a_{ik} = b_{kj} = 1$

Can be computed naively in $O(n^3)$ time.

Can also be computed in $O(n^\omega \log n)$ time.

Exercise 6:

- a) Obtain a deterministic $O(n^\omega)$ -time algorithm for finding **unique** witnesses.
- b) Let $1 \leq d \leq n$ be an integer. Obtain a randomized $O(n^\omega)$ -time algorithm for finding witnesses for all positions that have between d and $2d$ witnesses.
- c) Obtain an $O(n^\omega \log n)$ -time algorithm for finding all witnesses.

Hint: In b) use **sampling**.

All-Pairs Shortest Paths in graphs with small integer weights

Undirected graphs.

Edge weights in $\{0, 1, \dots, M\}$

Running time	Authors
Mn^ω	[Shoshan-Zwick '99]

Improves results of
[Alon-Galil-Margalit '91] [Seidel '95]

DIRECTED SHORTEST PATHS

Exercise 7:

Obtain an $O(n^\omega \log n)$ time algorithm for computing the **diameter** of an unweighted directed graph.

Using matrix multiplication to compute min-plus products

$$\begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \\ & & \mathbf{0} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ & & \mathbf{0} \end{pmatrix} * \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \\ & & \mathbf{0} \end{pmatrix}$$

$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}$$

$$\begin{pmatrix} c'_{11} & c'_{12} \\ c'_{21} & c'_{22} \\ & & \mathbf{0} \end{pmatrix} = \begin{pmatrix} x^{a_{11}} & x^{a_{12}} \\ x^{a_{21}} & x^{a_{22}} \\ & & \mathbf{0} \end{pmatrix} \times \begin{pmatrix} x^{b_{11}} & x^{b_{12}} \\ x^{b_{21}} & x^{b_{22}} \\ & & \mathbf{0} \end{pmatrix}$$

$$c'_{ij} = \sum_k x^{a_{ik} + b_{kj}}$$

$$c_{ij} = \text{first}(c'_{ij})$$

Using matrix multiplication to compute min-plus products

Assume: $0 \leq a_{ij}, b_{ij} \leq M$

$$\begin{pmatrix} c'_{11} & c'_{12} \\ c'_{21} & c'_{22} \\ \mathbf{0} \end{pmatrix} = \begin{pmatrix} x^{a_{11}} & x^{a_{12}} \\ x^{a_{21}} & x^{a_{22}} \\ \mathbf{0} \end{pmatrix} * \begin{pmatrix} x^{b_{11}} & x^{b_{12}} \\ x^{b_{21}} & x^{b_{22}} \\ \mathbf{0} \end{pmatrix}$$

n^{ω}		M		Mn^{ω}
polynomial products	×	operations per polynomial product	*	operations per max-plus product

Trying to implement the repeated squaring algorithm

```
 $D \leftarrow W$   
for  $i \leftarrow 1$  to  $\log_2 n$   
do  $D \leftarrow D * D$ 
```

Consider an easy case:
all weights are 1.

After the i -th iteration, the finite elements in D are in the range $\{1, \dots, 2^i\}$.

The cost of the min-plus product is $2^i n^\omega$

The cost of the last product is $n^{\omega+1}$!!!

Sampled Repeated Squaring (Z '98)

```
 $D \leftarrow W$   
for  $i \leftarrow 1$  to  $\log_{3/2} n$  do  
{  
   $s \leftarrow (3/2)^{i+1}$   
   $B \leftarrow \text{rand}(V, (9n \ln n)/s)$   
   $D \leftarrow \min\{D, D[V,B]*D[B,V]\}$   
}
```

Choose a subset of V
of size $\approx n/s$

Select the columns

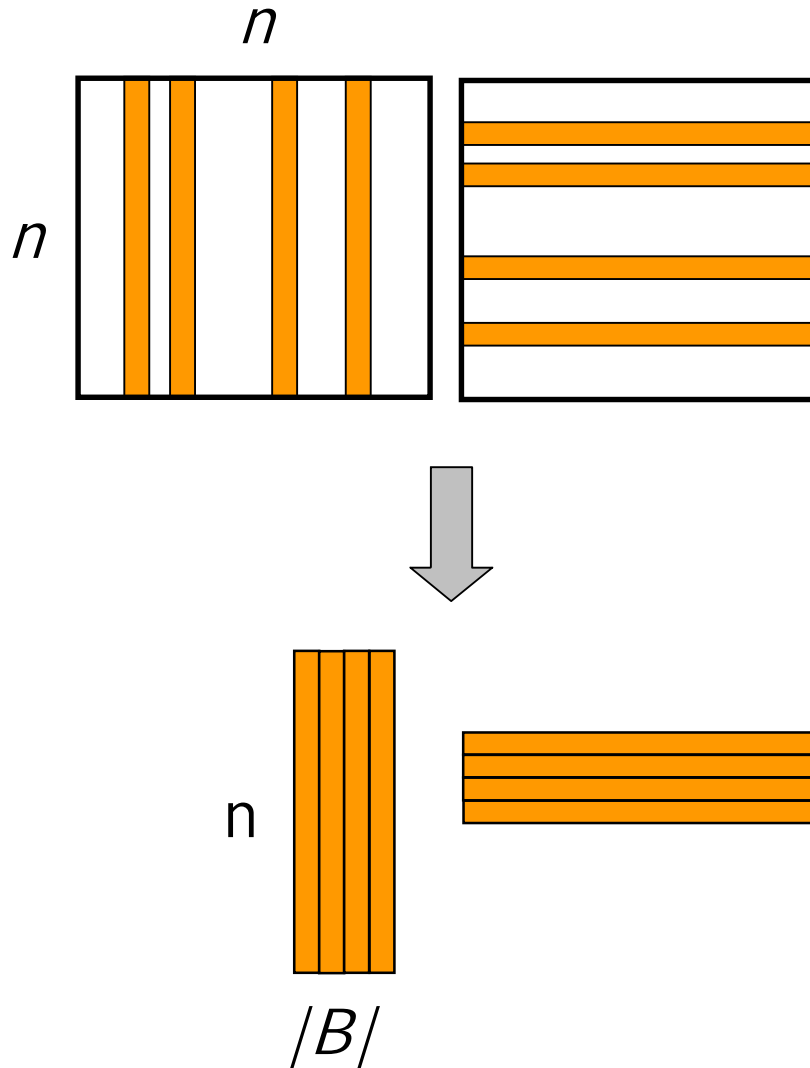
The is also a slightly more complicated
of D whose
indices are in B

With high probability, D whose
deterministic algorithm
distances are correct

Select the rows

of D whose
indices are in B

Sampled Distance Products (Z '98)



In the i -th iteration, the set B is of size $\approx n/s$, where $s = (3/2)^{i+1}$

The matrices get **smaller and smaller** but the elements get **larger and larger**

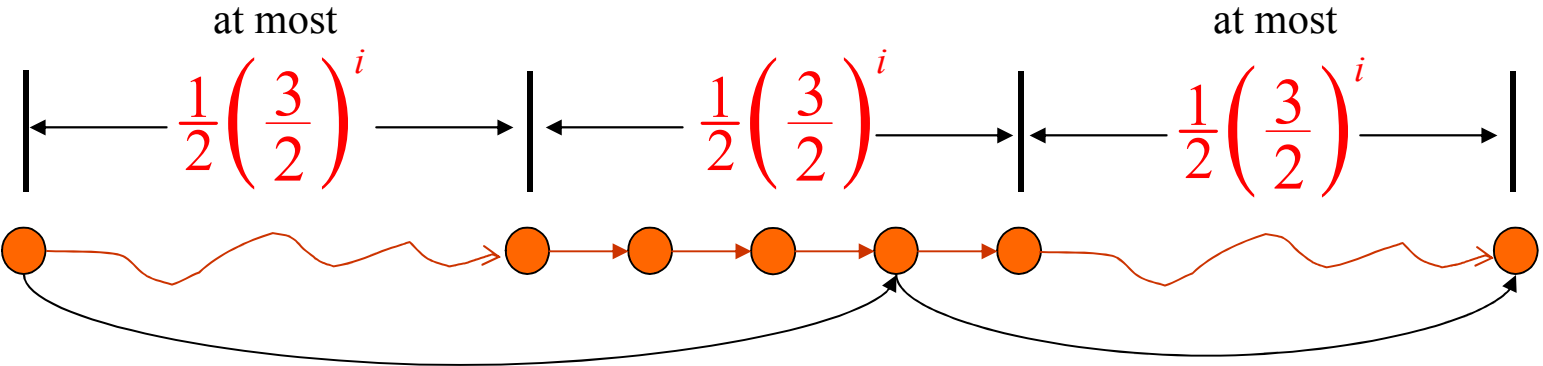
Sampled Repeated Squaring - Correctness

```

D ← W
for i ← 1 to log3/2n do
{
  s ← (3/2)i+1
  B ← rand(V, (9n ln n)/s)
  D ← min{ D , D[V,B]*D[B,V] }
}
    
```

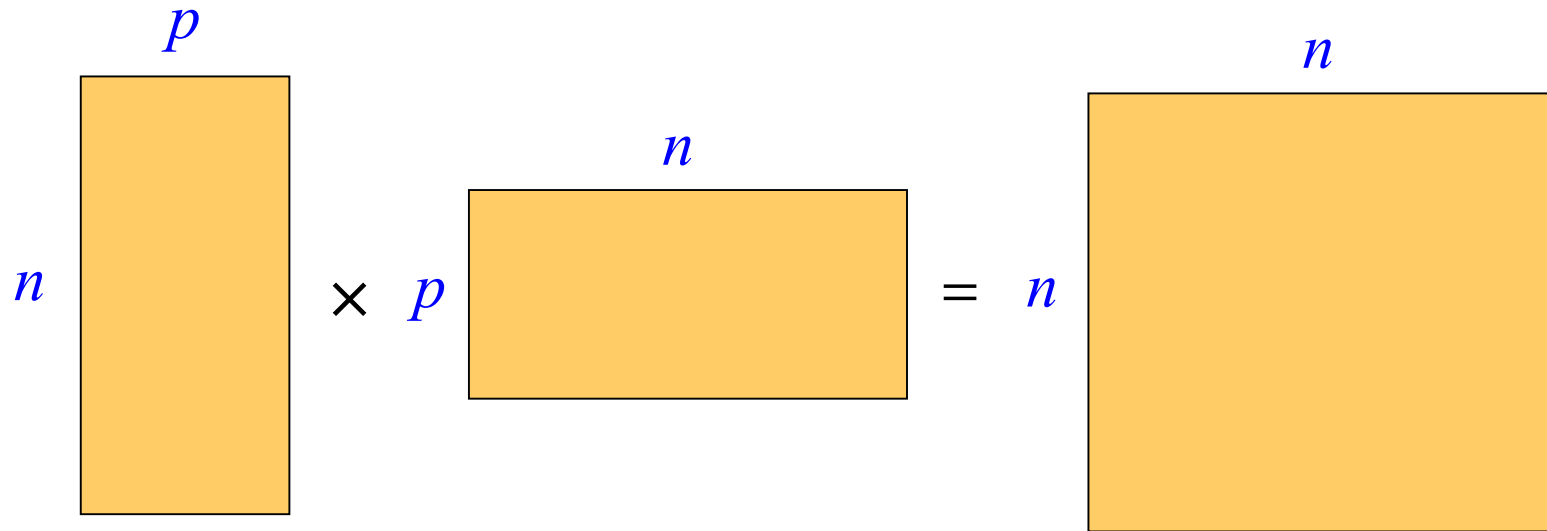
Invariant: After the i -th iteration, distances that are attained using at most $(3/2)^i$ edges are correct.

Consider a shortest path that uses at most $(3/2)^{i+1}$ edges



Let $s = (3/2)^{i+1}$ Failure probability : $\left(1 - \frac{9 \ln n}{s}\right)^{s/3} < n^{-3}$

Rectangular Matrix multiplication



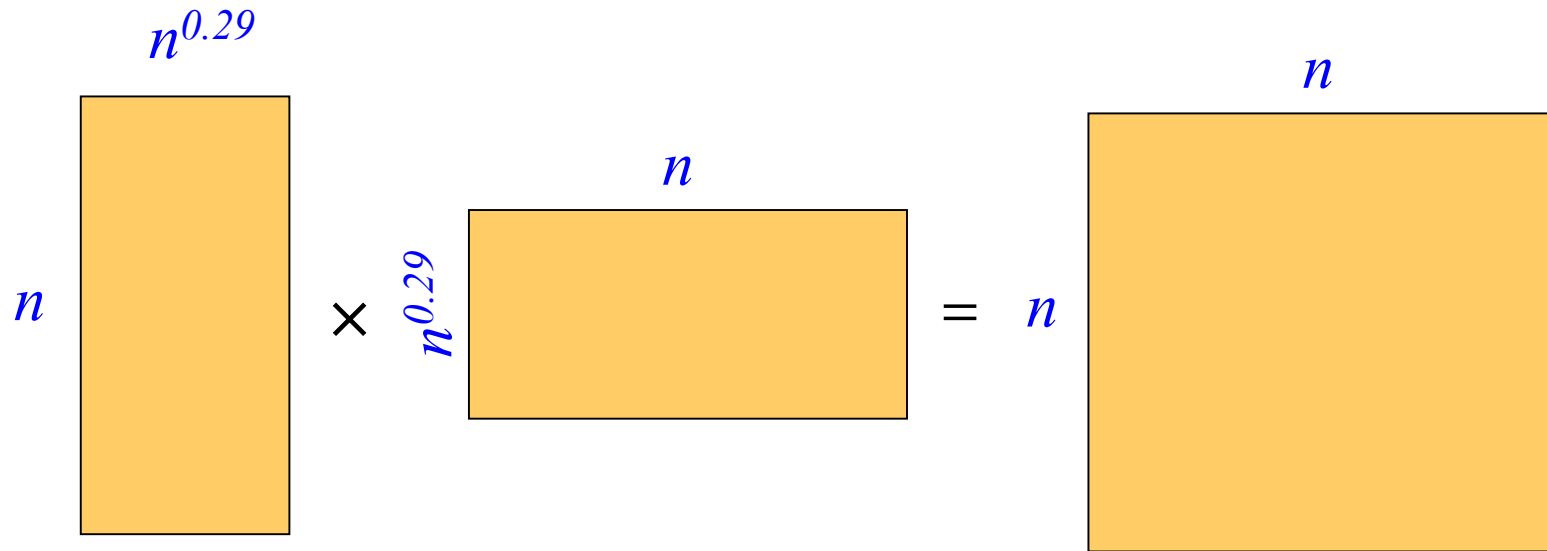
Naïve complexity: n^2p

[Coppersmith (1997)] [Huang-Pan (1998)]

$$n^{1.85}p^{0.54} + n^{2+o(1)}$$

For $p \leq n^{0.29}$, complexity = $n^{2+o(1)}$!!!

Rectangular Matrix multiplication



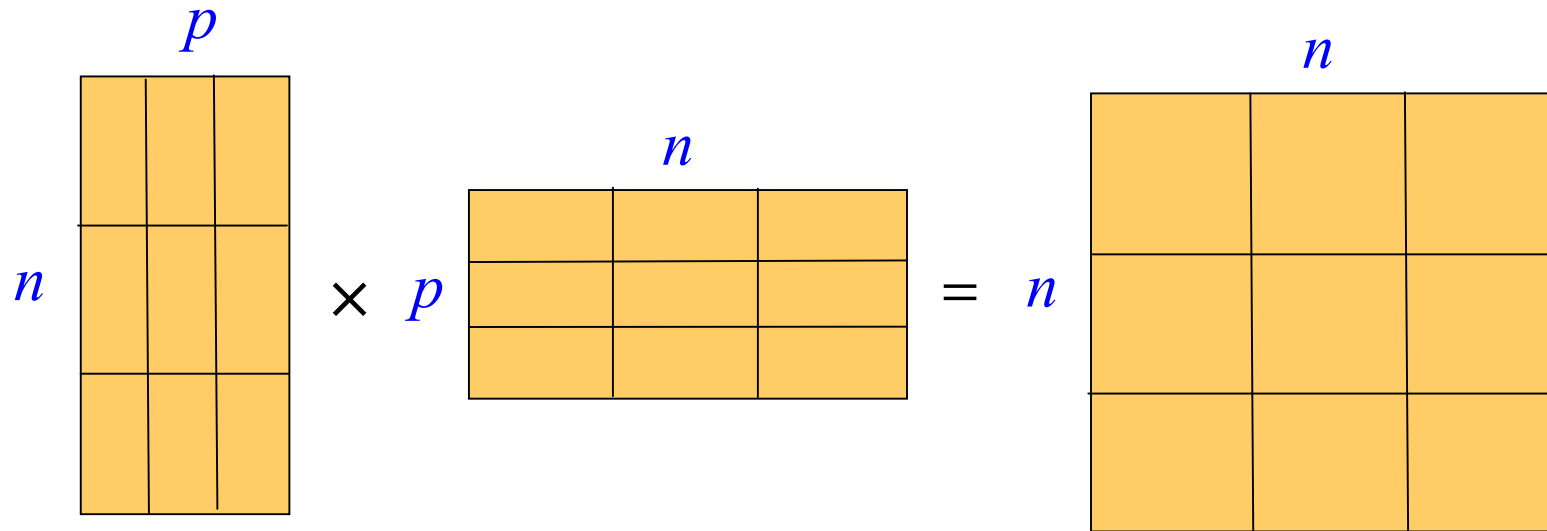
[Coppersmith (1997)]

$n \times n^{0.29}$ by $n^{0.29} \times n$

$n^{2+o(1)}$ operations!

$\alpha = 0.29\dots$

Rectangular Matrix multiplication



[Huang-Pan (1998)]

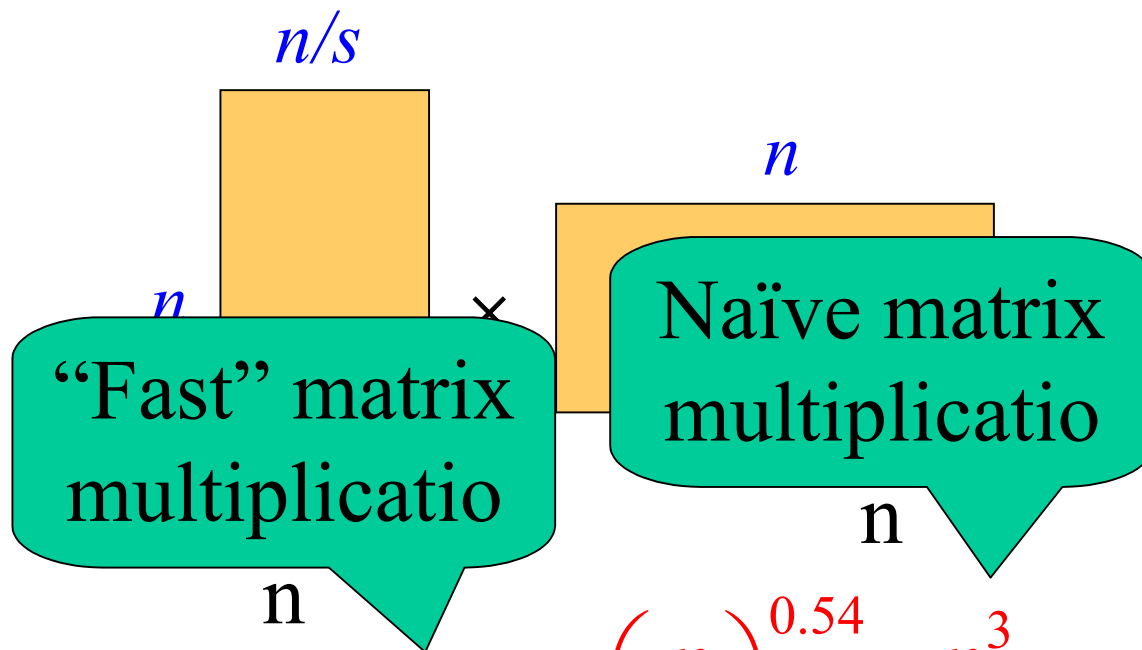
Break into $q \times q^\alpha$ and $q^\alpha \times q$ sub-matrices

$$q = \left(\frac{n}{p}\right)^{\frac{1}{1-\alpha}} \quad \left(\frac{n}{q}\right)^\omega \cdot q^2 = n^{\omega - \frac{\omega-2}{1-\alpha}} \cdot p^{\frac{\omega-2}{1-\alpha}}$$

$$\approx n^{1.85} p^{0.54}$$

Complexity of APSP algorithm

The i -th iteration:



$$s = (3/2)^{i+1}$$

The elements are of absolute value at most M_s

$$\min \left\{ M_s \cdot n^{1.85} \left(\frac{n}{s} \right)^{0.54}, \frac{n^3}{s} \right\} \leq M^{0.68} n^{2.58}$$

All-Pairs Shortest Paths in graphs with small integer weights

Undirected graphs.
Edge weights in $\{0, 1, \dots, M\}$

Running time	Authors
$Mn^{2.38}$	[Shoshan-Zwick '99]

Improves results of
[Alon-Galil-Margalit '91] [Seidel '95]

All-Pairs Shortest Paths in graphs with small integer weights

Directed graphs.

Edge weights in $\{-M, \dots, 0, \dots, M\}$

Running time	Authors
$M^{0.68} n^{2.58}$	[Zwick '98]

Improves results of
[Alon-Galil-Margalit '91] [Takaoka '98]

Open problem:

Can **APSP** in directed graphs
be solved in $O(n^\omega)$ time?

[Yuster-Z (2005)]

A directed graphs can be processed in $O(n^\omega)$
time so that any **distance query** can be
answered in $O(n)$ time.

Corollary:

SSSP in directed graphs in $O(n^\omega)$ time.

Also obtained, using a different technique, by
Sankowski (2005)

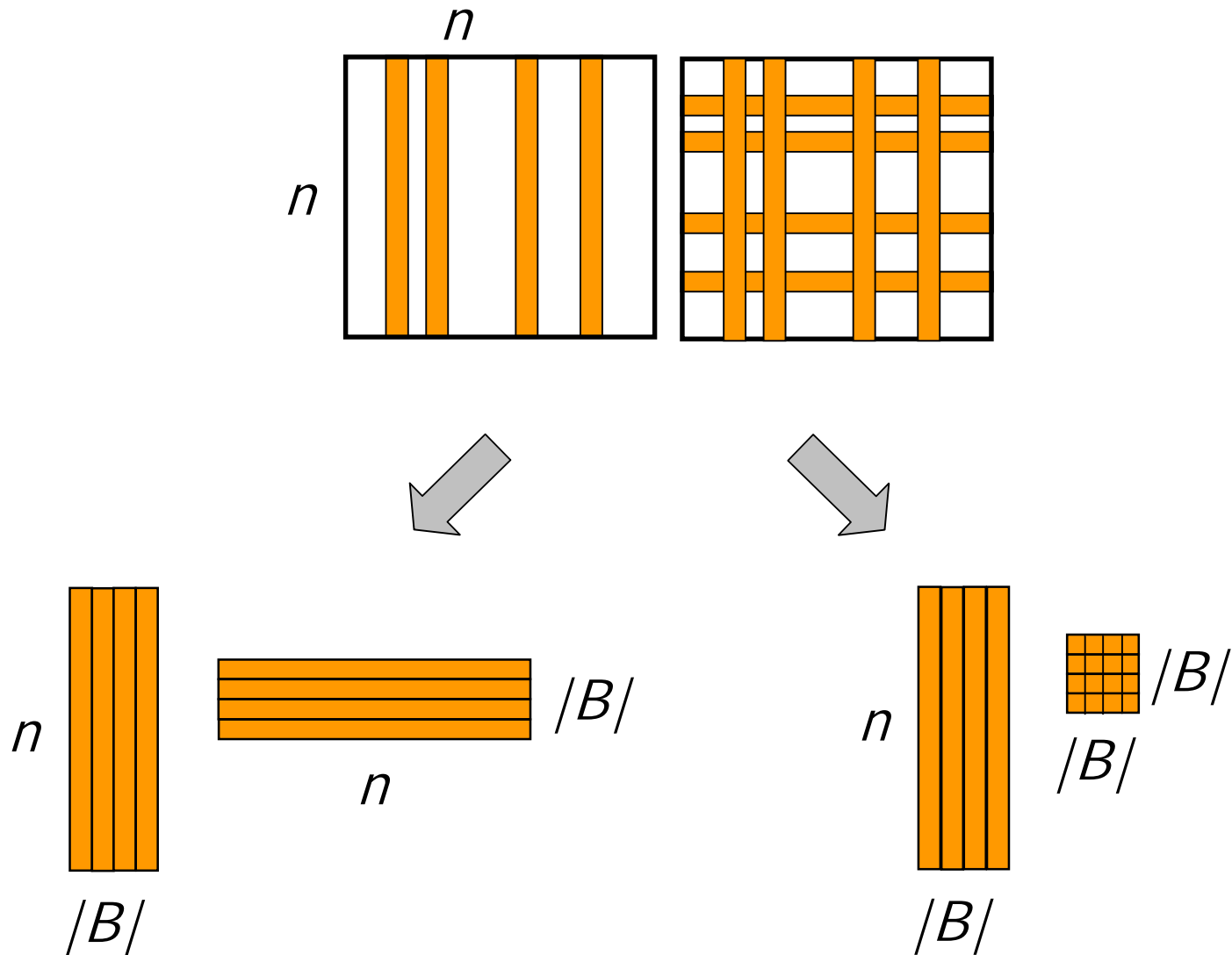
The preprocessing algorithm (YZ '05)

```
 $D \leftarrow W ; B \leftarrow V$   
for  $i \leftarrow 1$  to  $\log_{3/2} n$  do  
{  
   $s \leftarrow (3/2)^{i+1}$   
   $B \leftarrow \text{rand}(B, (9n \ln n)/s)$   
   $D[V, B] \leftarrow \min\{ D[V, B], D[V, B] * D[B, B]$   
  }  
   $D[B, V] \leftarrow \min\{ D[B, V], D[B, B] * D[B, V]$   
  }  
}
```

The APSP algorithm

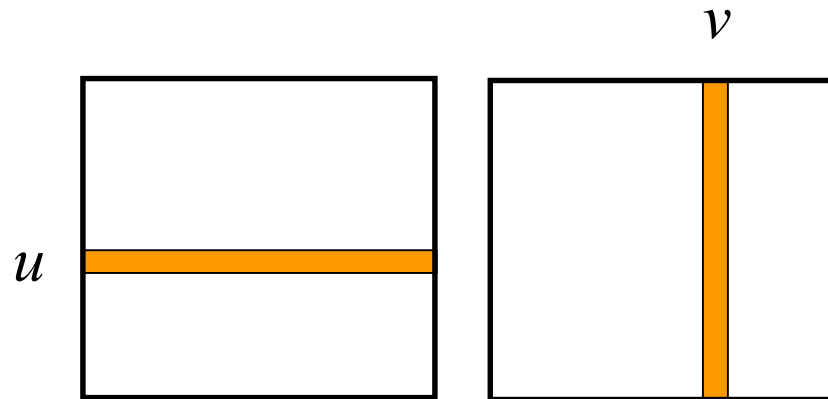
```
 $D \leftarrow W$   
for  $i \leftarrow 1$  to  $\log_{3/2} n$  do  
{  
   $s \leftarrow (3/2)^{i+1}$   
   $B \leftarrow \text{rand}(V, (9n \ln n)/s)$   
   $D \leftarrow \min\{ D, D[V, B] * D[B, V] \}$   
}
```

Twice Sampled Distance Products



The query answering algorithm

$$\delta(u,v) \leftarrow D[\{u\},V]*D[V,\{v\}]$$



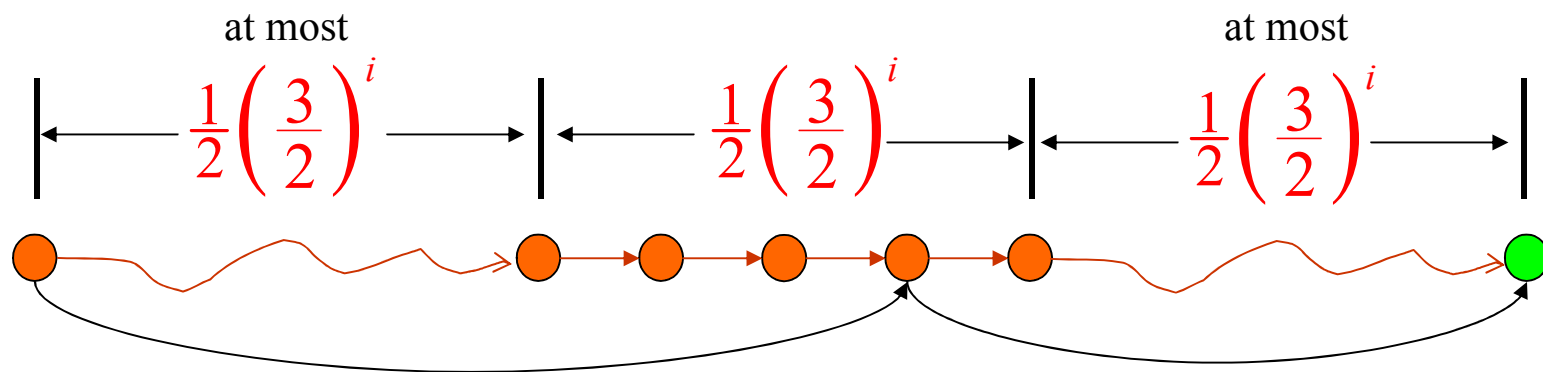
Query time: $O(n)$

The preprocessing algorithm: Correctness

Let B_i be the i -th sample. $B_1 \supseteq B_2 \supseteq B_3 \supseteq \dots$

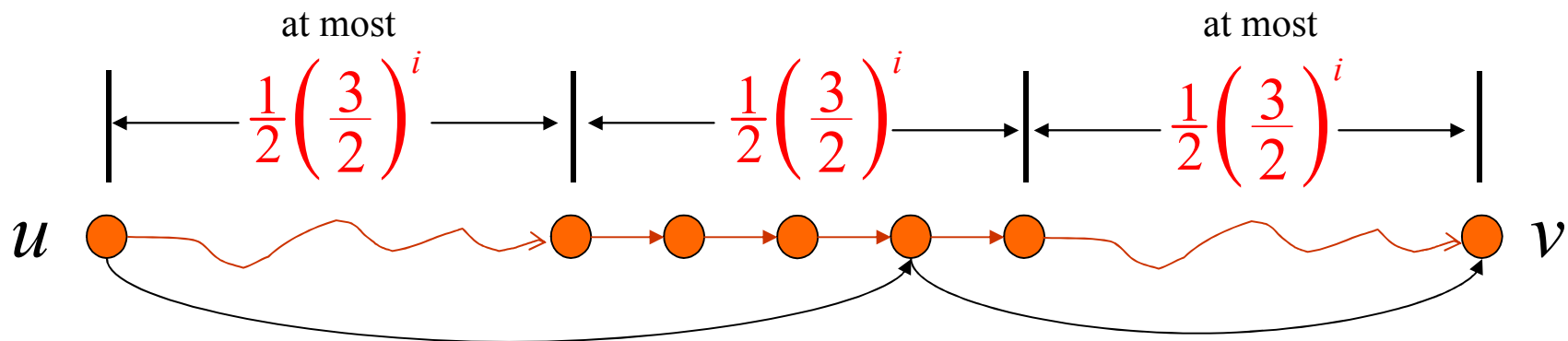
Invariant: After the i -th iteration, if $u \in B_i$ or $v \in B_i$ and there is a shortest path from u to v that uses at most $(3/2)^i$ edges, then $D(u,v) = \delta(u,v)$.

Consider a shortest path that uses at most $(3/2)^{i+1}$ edges



The query answering algorithm: Correctness

Suppose that the shortest path from u to v uses between $(3/2)^i$ and $(3/2)^{i+1}$ edges



1. Algebraic matrix multiplication

- a. Strassen's algorithm
- b. Rectangular matrix multiplication

2. Min-Plus matrix multiplication

- a. Equivalence to the APSP problem
- b. Expensive reduction to algebraic products
- c. Fredman's trick

3. APSP in undirected graphs

- a. An $O(n^{2.38})$ algorithm for unweighted graphs (Seidel)
- b. An $O(Mn^{2.38})$ algorithm for weighted graphs (Shoshan-Zwick)

4. APSP in directed graphs

- 1. An $O(M^{0.68}n^{2.58})$ algorithm (Zwick)
- 2. An $O(Mn^{2.38})$ preprocessing / $O(n)$ query answering alg. (Yuster-Z)

➡ 3. An $O(n^{2.38}\log M)$ $(1+\epsilon)$ -approximation algorithm

5. Summary and open problems

Approximate min-plus products

Obvious idea: scaling

$$\text{SCALE}(A, M, R): \quad a'_{ij} \leftarrow \begin{cases} \lceil Ra_{ij} / M \rceil & , \text{ if } 0 \leq a_{ij} \leq M \\ +\infty & , \text{ otherwise} \end{cases}$$

APX-MPP(A, B, M, R) :

$A' \leftarrow \text{SCALE}(A, M, R)$

$B' \leftarrow \text{SCALE}(B, M, R)$

return MPP(A', B')

Complexity is $Rn^{2.38}$, instead of $Mn^{2.38}$, but small values can be greatly distorted.

Addaptive Scaling

APX-MPP(A, B, M, R) :

$C' \leftarrow \infty$

for $r \leftarrow \log_2 R$ to $\log_2 M$ do

$A' \leftarrow \text{SCALE}(A, 2^r, R)$

$B' \leftarrow \text{SCALE}(B, 2^r, R)$

$C' \leftarrow \min\{C', \text{MPP}(A', B')\}$

end

Complexity is $Rn^{2.38} \log M$

Stretch at most $1 + 4/R$

1. Algebraic matrix multiplication

- a. Strassen's algorithm
- b. Rectangular matrix multiplication

2. Min-Plus matrix multiplication

- a. Equivalence to the APSP problem
- b. Expensive reduction to algebraic products
- c. Fredman's trick

3. APSP in undirected graphs

- a. An $O(n^{2.38})$ algorithm for unweighted graphs (Seidel)
- b. An $O(Mn^{2.38})$ algorithm for weighted graphs (Shoshan-Zwick)

4. APSP in directed graphs

1. An $O(M^{0.68}n^{2.58})$ algorithm (Zwick)
2. An $O(Mn^{2.38})$ preprocessing / $O(n)$ query answering alg. (Yuster-Z)
3. An $O(n^{2.38}\log M)$ $(1+\epsilon)$ -approximation algorithm

5. Summary and open problems

Answering distance queries

Directed graphs. Edge weights in $\{-M, \dots, 0, \dots, M\}$

Preprocessing time	Query time	Authors
$Mn^{2.38}$	n	[Yuster-Zwick '05]

In particular, any $Mn^{1.38}$ distances can be computed in $Mn^{2.38}$ time.

For dense enough graphs with small enough edge weights, this improves on **Goldberg's** SSSP algorithm.

$Mn^{2.38}$ vs. $mn^{0.5} \log M$

Approximate All-Pairs Shortest Paths in graphs with non-negative integer weights

Directed graphs.

Edge weights in $\{0, 1, \dots, M\}$

$(1+\varepsilon)$ -approximate distances

Running time	Authors
$(n^{2.38} \log M)/\varepsilon$	[Zwick '98]

Open problems

An $O(n^\omega)$ algorithm for the directed unweighted **APSP** problem?

An $O(n^{3-\varepsilon})$ algorithm for the **APSP** problem with edge weights in $\{1, 2, \dots, n\}$?

An $O(n^{2.5-\varepsilon})$ algorithm for the **SSSP** problem with edge weights in $\{-1, 0, 1, 2, \dots, n\}$?

DYNAMIC
TRANSITIVE CLOSURE

Dynamic transitive closure

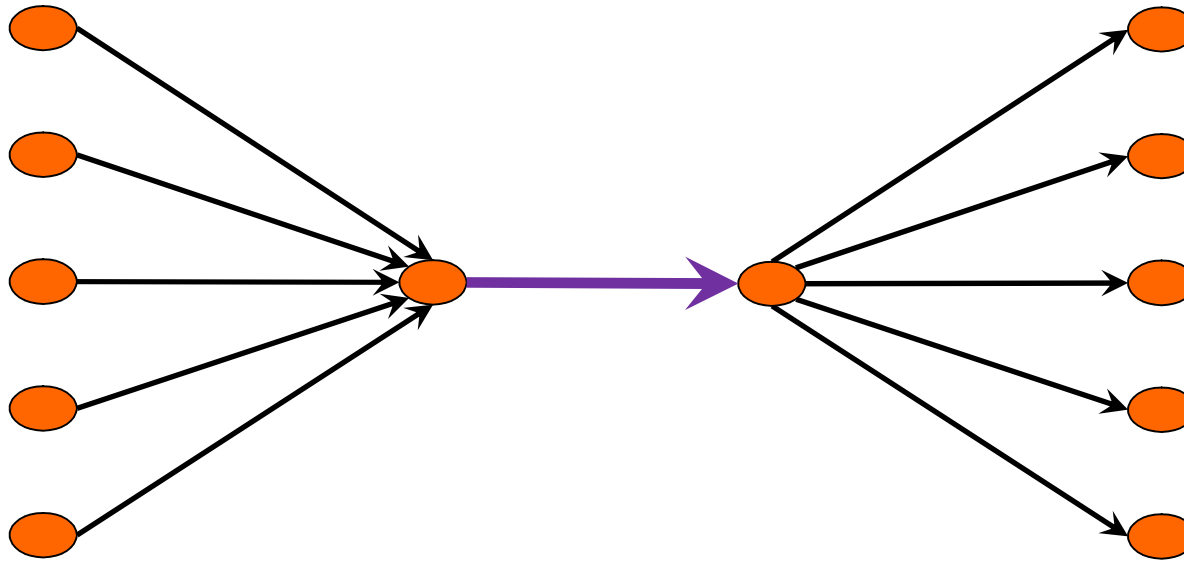
- **Edge-Update**(e) – add/remove an edge e
- **Vertex-Update**(v) – add/remove edges touching v .
- **Query**(u, v) – is there are directed path from u to v ?

[Sankowski '04]

Edge-Update			
Vertex-Update			
Query			

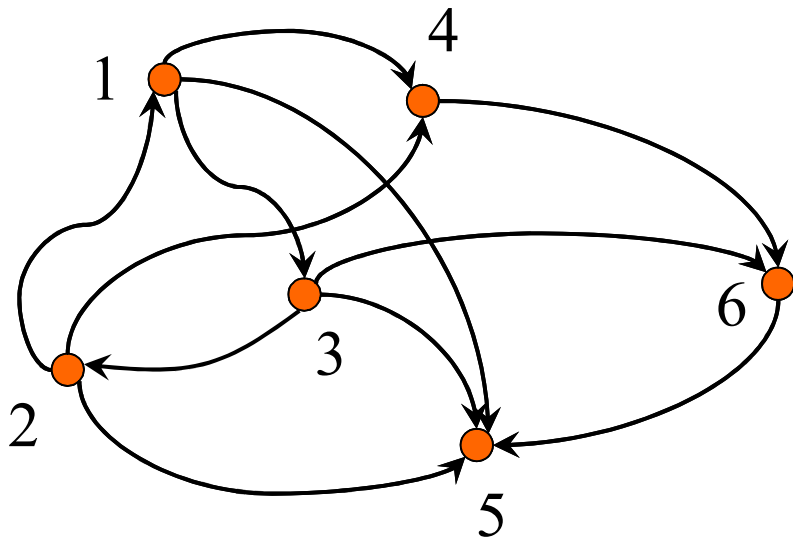
(improving [Demetrescu-Italiano '00], [Roditty '03])

Inserting/Deleting an edge



May change $\Omega(n^2)$ entries of the transitive closure matrix

Symbolic Adjacency matrix



$$\begin{pmatrix} 1 & 0 & x_{13} & x_{14} & x_{15} & 0 \\ x_{21} & 1 & 0 & x_{24} & x_{25} & 0 \\ 0 & x_{32} & 1 & 0 & x_{35} & x_{36} \\ 0 & 0 & 0 & 1 & 0 & x_{46} \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & x_{56} & 1 \end{pmatrix}$$

$$\det(A) \neq 0$$

Reachability via adjoint

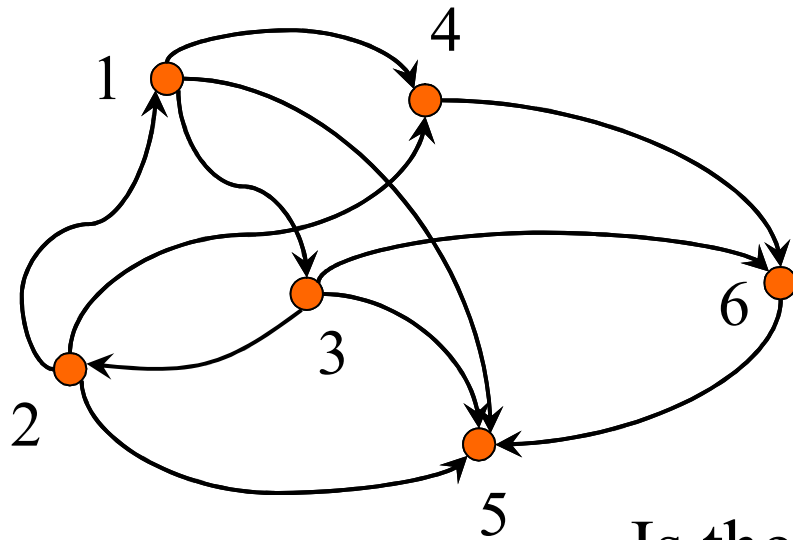
[Sankowski '04]

Let A be the symbolic adjacency matrix of G .
(With 1s on the diagonal.)

There is a directed path from i to j in G iff

$$(\text{adj}(A))_{ij} \neq 0$$

Reachability via adjoint (example)



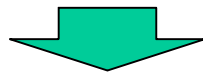
$$\begin{pmatrix} 1 & 0 & x_{13} & x_{14} & x_{15} & 0 \\ x_{21} & 1 & 0 & x_{24} & x_{25} & 0 \\ 0 & x_{32} & 1 & 0 & x_{35} & x_{36} \\ 0 & 0 & 0 & 1 & 0 & x_{46} \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & x_{65} & 1 \end{pmatrix}$$

Is there a path from 1 to 5?

$$\det \begin{pmatrix} 0 & 0 & x_{13} & x_{14} & x_{15} & 0 \\ 0 & 1 & 0 & x_{24} & x_{25} & 0 \\ 0 & x_{32} & 1 & 0 & x_{35} & x_{36} \\ 0 & 0 & 0 & 1 & 0 & x_{46} \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & x_{65} & 1 \end{pmatrix} = \begin{aligned} & -x_{15} \\ & -x_{13}x_{32}x_{25} \\ & +x_{13}x_{35} \\ & -x_{13}x_{36}x_{56} \\ & -x_{14}x_{46}x_{65} \\ & -x_{13}x_{32}x_{24}x_{46}x_{65} \end{aligned}$$

Dynamic transitive closure

- **Edge-Update**(e) – add/remove an edge e
- **Vertex-Update**(v) – add/remove edges touching v .
- **Query**(u, v) – is there are directed path from u to v ?

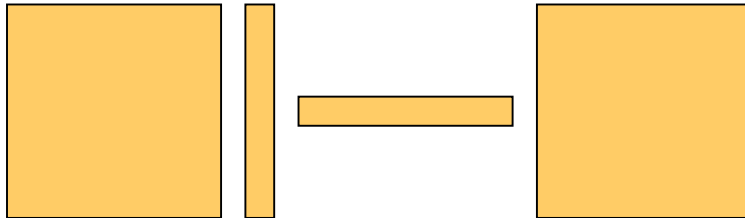


Dynamic matrix inverse

- **Entry-Update**(i, j, x) – Add x to A_{ij}
- **Row-Update**(i, v) – Add v to the i -th row of A
- **Column-Update**(j, u) – Add u to the j -th column of A
- **Query**(i, j) – return $(A^{-1})_{ij}$

Sherman-Morrison formula

$$(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + v^T A^{-1}u}$$

$$A^{-1}uv^T A^{-1} :$$


$$v^T A^{-1}u :$$


Inverse of a **rank one correction**
is a **rank one correction** of the inverse

Inverse updated in $O(n^2)$ time

$O(n^2)$ update / $O(1)$ query algorithm [Sankowski '04]

Let $p \approx n^3$ be a prime number

Assign random values $a_{ij} \in F_p$ to the variables x_{ij}

Maintain A^{-1} over F_p

Edge-Update \rightarrow Entry-Update

Vertex-Update \rightarrow Row-Update + Column-Update

Perform updates using the **Sherman-Morrison** formula

Small error probability
(by the **Schwartz-Zippel** lemma)

Lazy updates

Consider single entry updates

$$A_k = A_{k-1} + a_k u_k v_k$$
$$a_k = \pm a_{i_k, j_k} \quad u_k = e_{i_k} \quad v_k = e_{j_k}^T$$

$$A_k^{-1} = A_{k-1}^{-1} + \alpha_k u'_k v'_k$$

$$\alpha_k = 1 + a_k v_k A_{k-1}^{-1} u_k = 1 + a_k (A_{k-1}^{-1})_{j_k, i_k}$$

$$u'_k = A_{k-1}^{-1} u_k = (A_{k-1}^{-1})_{*, i_k}$$

$$v'_k = v_k A_{k-1}^{-1} = (A_{k-1}^{-1})_{j_k, *}$$

$$A_k^{-1} = A_0^{-1} + \sum_{i=1}^k \alpha_i u'_i v'_i$$

Lazy updates (cont.)

$$A_k^{-1} = A_0^{-1} + \sum_{i=1}^k \alpha_i u'_i v'_i$$

Do not maintain A_k^{-1} explicitly!

Maintain $\alpha_i, u'_i, v'_i, i = 1, 2, \dots, k$

Querying $(A_k^{-1})_{r,c} - O(k)$ time

Computing $\alpha_k, u'_k, v'_k - O(nk)$ time

Queries and updates get more and more expensive!

Lazy updates (cont.)

$$A_k^{-1} = A_0^{-1} + \sum_{i=1}^k \alpha_i u'_i v'_i$$

Query time – $O(k)$

Update time – $O(nk)$

Compute A_k^{-1} explicitly after each K updates

Time required – $O(M(n, K, n))$ time

Amortized update time – $O(nK + M(n, K, n)/K)$

Update time minimized when $K \approx n^{0.575}$

Can be made **worst-case**

Even Lazier updates

$$A_k^{-1} = A_0^{-1} + \sum_{i=1}^k \alpha_i u'_i v'_i$$

After ℓ updates in positions
 $(r_1, c_1), (r_2, c_2), \dots, (r_\ell, c_\ell)$

maintain:

$$\alpha_i, (u'_i)_{c_j}, (v'_i)_{r_j}, \text{ for } 1 \leq i, j \leq \ell$$

Query time – $O(k^2)$

Update time – $O(k^2)$

After K , explicitly update A_k^{-1}

Dynamic transitive closure

- **Edge-Update**(e) – add/remove an edge e
- **Vertex-Update**(v) – add/remove edges touching v .
- **Query**(u, v) – is there are directed path from u to v ?

[Sankowski '04]

Edge-Update	n^2	$n^{1.575}$	$n^{1.495}$
Vertex-Update	n^2	—	—
Query	1	$n^{0.575}$	$n^{1.495}$

(improving [Demetrescu-Italiano '00], [Roditty '03])

Finding triangles in $O(m^{2\omega/(\omega+1)})$ time

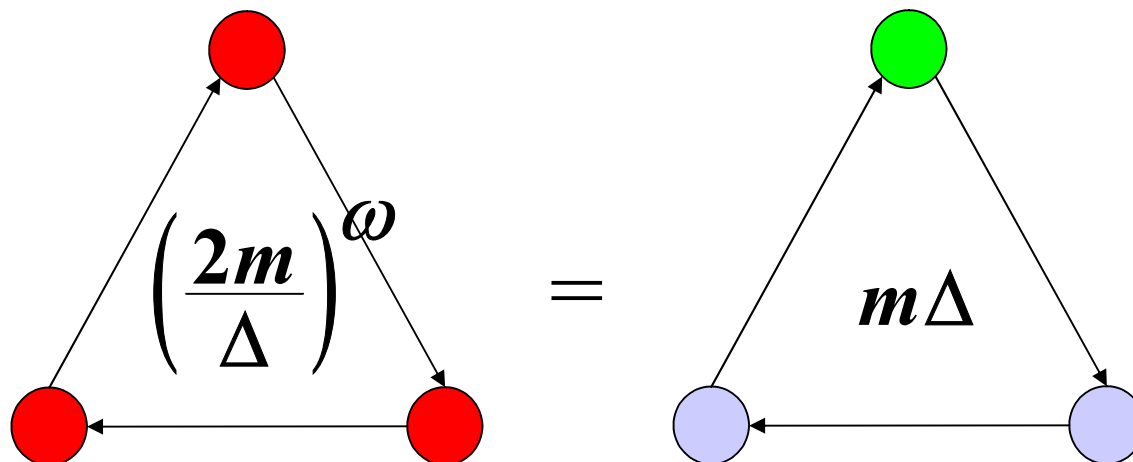
[Alon-Yuster-Z (1997)]

Let Δ be a parameter. $\Delta = m^{(\omega-1)/(\omega+1)}$

High degree vertices: vertices of degree $\geq \Delta$.

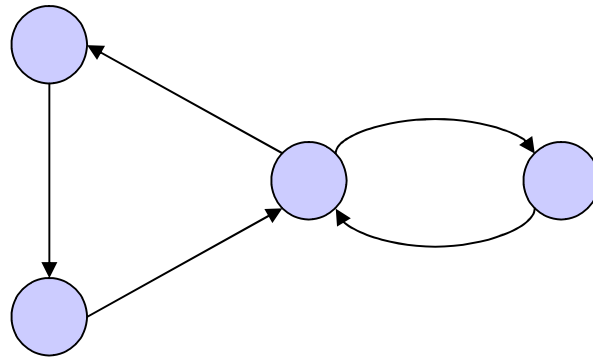
Low degree vertices: vertices of degree $< \Delta$.

There are at most $2m/\Delta$ **high** degree vertices



Finding longer **simple** cycles

A graph G contains a C_k iff $\text{Tr}(A^k) \neq 0$?



We want simple cycles!

Color coding [AYZ '95]

Assign each vertex v a random number $c(v)$ from $\{0, 1, \dots, k-1\}$.

Remove all edges (u, v) for which $c(v) \neq c(u) + 1 \pmod{k}$.

All cycles of length k in the graph are now simple.

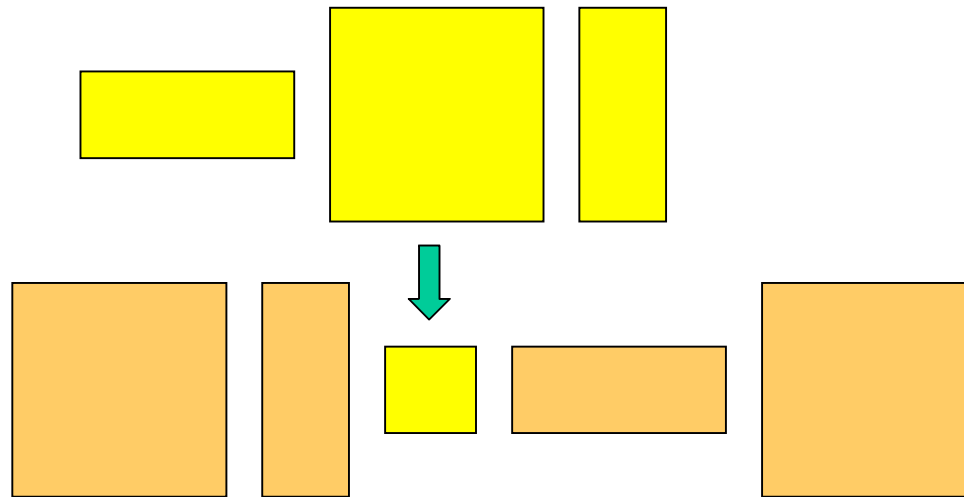
If a graph contains a C_k then with a probability of at least k^{-k} it still contains a C_k after this process.

An improved version works with probability $2^{-O(k)}$.

Can be derandomized at a logarithmic cost.

Sherman-Morrison-Woodbury formula

$$(A + UV^T)^{-1} = A^{-1} - A^{-1}U(I + V^T A^{-1}U)^{-1}V^T A^{-1}$$



Inverse of a rank k correction
is a rank k correction of the inverse
Can be computed in $O(M(n,k,n))$ time.