

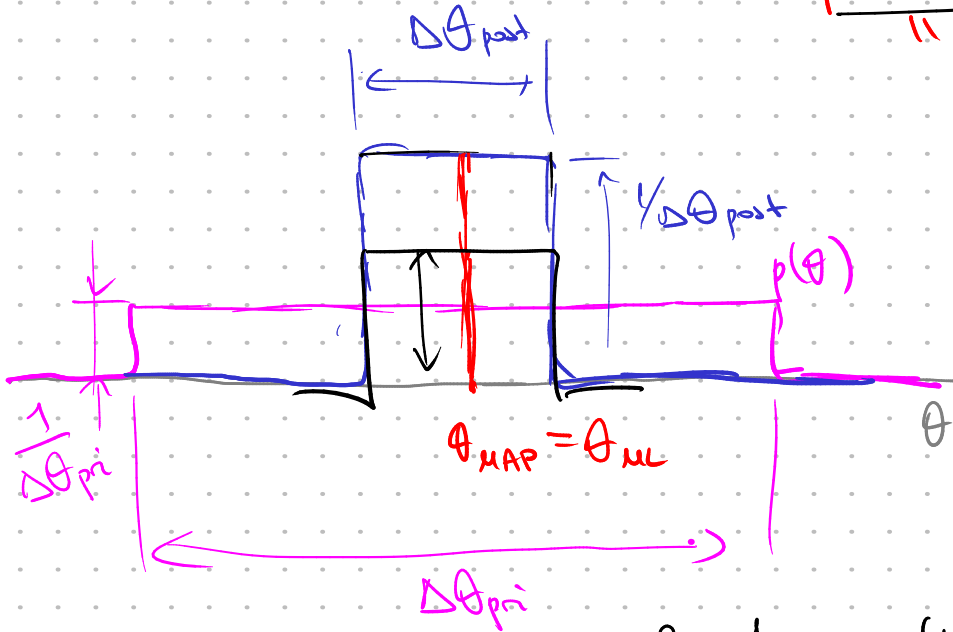
D, M_1, M_2, \dots, M_k

$$p(M_i | D) \propto \underbrace{p(M_i)}_{\text{prior}} \underbrace{p(D | M_i)}$$

$$p(\theta | D, M_i) = \frac{p(\theta | M_i) p(D | \theta, M_i)}{p(D | M_i)}$$

$$p(D | M_i) = \int p(\theta | M_i) p(D | \theta, M_i) d\theta$$

$$= \int p(D, \theta | M_i) d\theta$$



M repeats

$$p(D) = \int p(\theta) p(D | \theta) d\theta = \int \frac{1}{\Delta\theta_{pri}} \cdot p(D | \theta) d\theta =$$

$$= \int \frac{1}{\Delta\theta_{post}} p(D | \theta_{ML}) d\theta = p(D | \theta_{ML}) \cdot \left(\frac{\Delta\theta_{post}}{\Delta\theta_{pri}} \right)^M$$

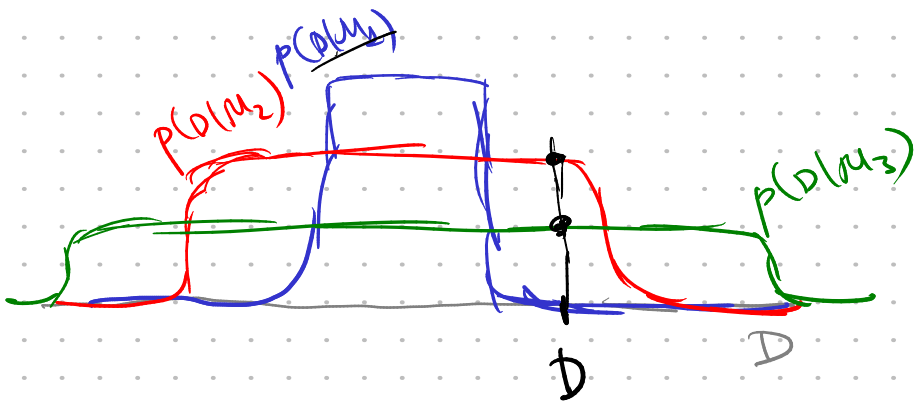
$$\ln p(D) = \ln p(D | \theta_{ML}) - M \cdot \ln \frac{\Delta\theta_{pri}}{\Delta\theta_{post}}$$

$$p(\theta), p(\theta | D) \approx \mathcal{N}(\dots)$$

BIC - Bayesian Information Criterion

← число параметров
← число точек G-D

$$\ln p(D) \approx \ln p(D | \theta_{ML}) - \frac{1}{2} M \ln N$$



Kullback-Leibler divergence

$$KL(p||q) = \int p(x) \ln \frac{p(x)}{q(x)} dx$$

$$KL(q||p) = \int q(x) \ln \frac{q(x)}{p(x)} dx$$

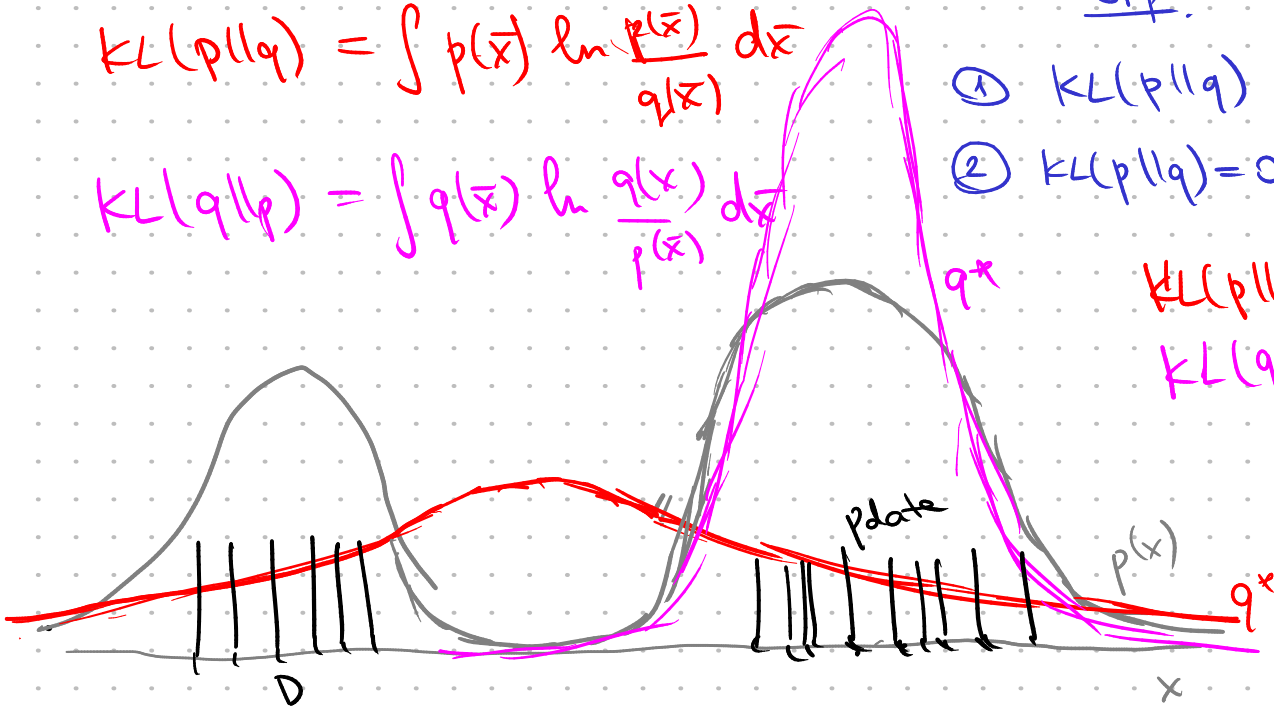
Imp.

① $KL(p||q) \geq 0$

② $KL(p||q) = 0 \Leftrightarrow p = q$ a.e.

$KL(p||q) \rightarrow \min$

$KL(q||p) \rightarrow \min$



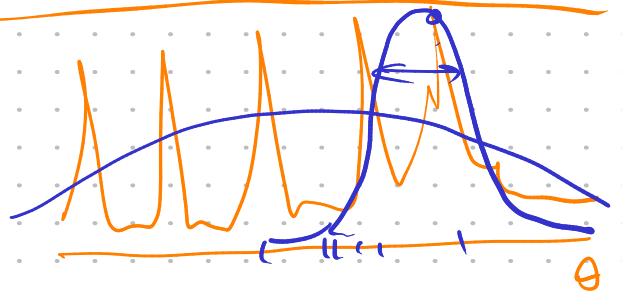
$$\int p_{data}(x) f(x) dx = \sum_{x \in D} f(x)$$

$\ln p(D|\theta) \rightarrow \max$

$\sum_{x \in D} \ln p(x|\theta) = \int p_{data}(x) \ln p(x|\theta) dx \rightarrow \max_{\theta}$

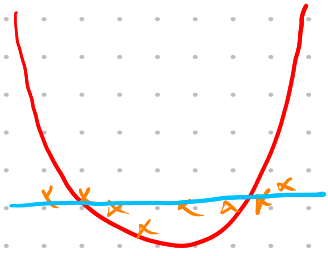
$KL(p_{data}||p) = \int p_{data}(x) \ln \frac{p_{data}(x)}{p(x|\theta)} dx \rightarrow \min_{\theta}$

$p(\theta) = \underbrace{p(\theta|D)}_{\approx q(\theta)} \propto p(\theta) p(D|\theta)$



$JSD(p||q) = KL(p||\frac{p+q}{2}) + KL(q||\frac{p+q}{2})$

Sanity check:



$$p(D|w_{true}) \Rightarrow p(D|w_{true}) \neq p(D|w)$$

$$\ln p(D|w_{true}) \neq \ln p(D|w)$$

$$\int p(D|w_{true}) \ln p(D|w_{true}) dD - \int \ln p(D|w) p(D|w_{true}) dD \neq 0$$

$$KL(p_{true}|p) = \int p(D|w_{true}) \ln \frac{p(D|w_{true})}{p(D|w)} dD \geq 0$$

$$\begin{pmatrix} 1 \\ x \end{pmatrix} \begin{pmatrix} 1 \\ y \end{pmatrix}$$

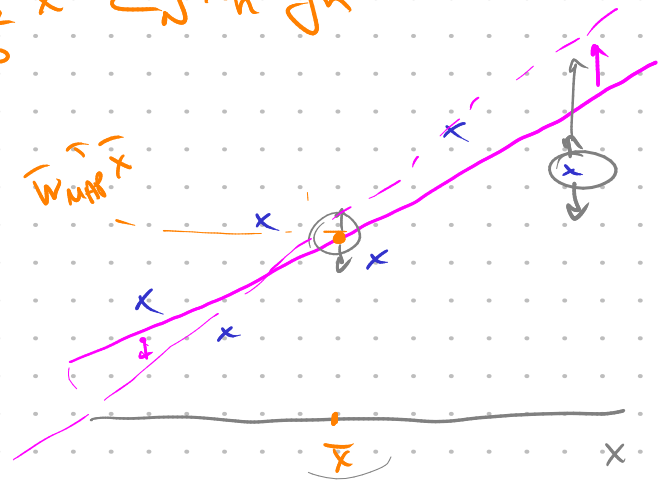
Equivalent kernel

$$p(y|\bar{x}, D) = \mathcal{N}(y | \underbrace{\bar{w}_{MAP}^T \bar{x}}_{\text{kernel}}, \sigma^2), \quad \sigma^2 = \sigma_0^2 + \bar{x}^T \Sigma_N \bar{x}$$

$$\bar{w}_{MAP} = \frac{1}{\sigma_0^2} \sum_N X^T \bar{y}$$

$$\bar{x}^T \bar{w}_{MAP} = \frac{1}{\sigma_0^2} \bar{x}^T \sum_N \begin{pmatrix} X^T \\ \bar{y} \end{pmatrix} = \sum_{n=1}^N \frac{1}{\sigma_0^2} \bar{x}^T X_n \bar{y}_n$$

$$\bar{x}^T \bar{w}_{MAP} = \sum_{n=1}^N \underbrace{k(\bar{x}, X_n)}_{\text{kernel}} \bar{y}_n$$



Empirische Bayes

Empirical Bayes

$$\beta = \frac{1}{\sigma^2}$$

$$p(D|\bar{w}) = \prod_n \mathcal{N}(y_n | \bar{w}^T X_n, \frac{1}{\beta})$$

$$p(\bar{w}) = \prod_i \mathcal{N}(w_i | 0, \frac{1}{\alpha}) \quad \leftarrow \text{hyperparameters}$$

non-informative priors

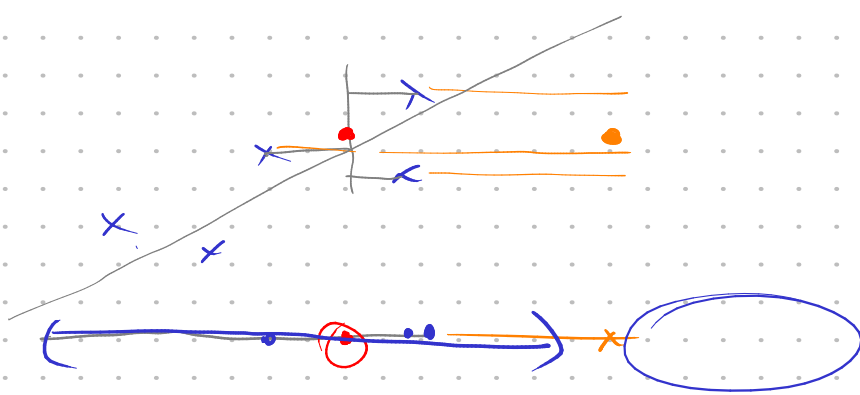
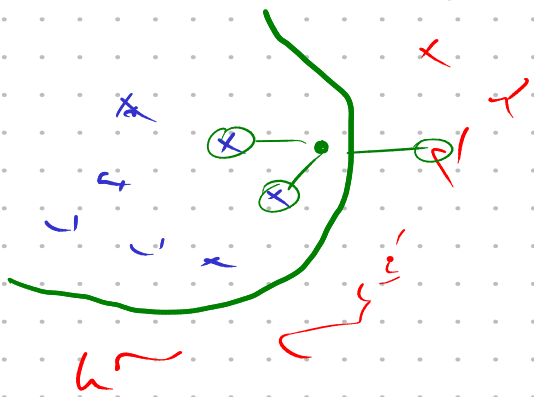
$$p(\alpha, \beta | D) \propto p(D|\alpha, \beta) p(\alpha, \beta)$$

$$p(D|\alpha, \beta) = \int p(D|\bar{w}, \beta) p(\bar{w}|\alpha) d\bar{w}$$

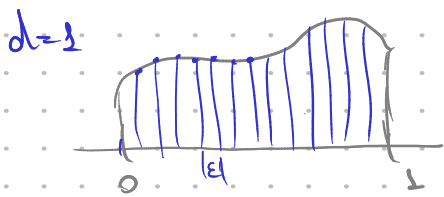
$$\ln p(D|\alpha, \beta) = \frac{d}{2} \ln \alpha + \frac{N}{2} \ln \beta - \frac{1}{2} \ln \det A - \frac{N}{2} \ln 2\pi - \frac{\beta}{2} \sum_n (y_n - \bar{w}^T X_n)^2 - \frac{\alpha}{2} \bar{w}^T \bar{w}$$

$$A = \beta X^T X + \alpha I$$

Nearest neighbors

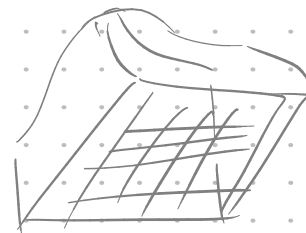


Curse of dimensionality



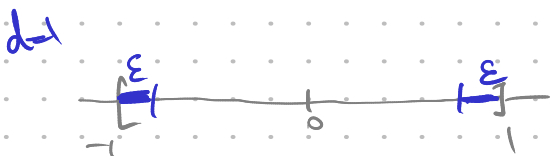
$$1/\epsilon$$

$d=2$

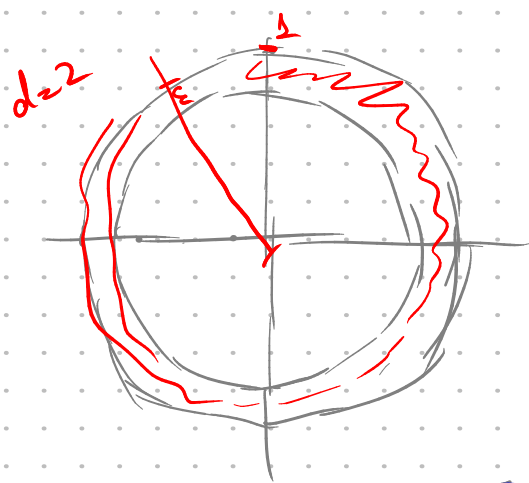


$$1/\epsilon^2$$

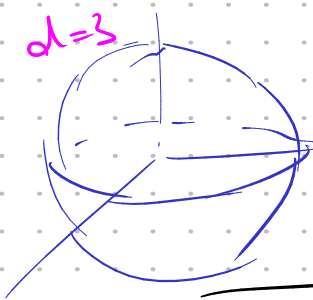
$$d(x, y) = \sum_{i=1}^d (x_i - y_i)^2$$



ϵ

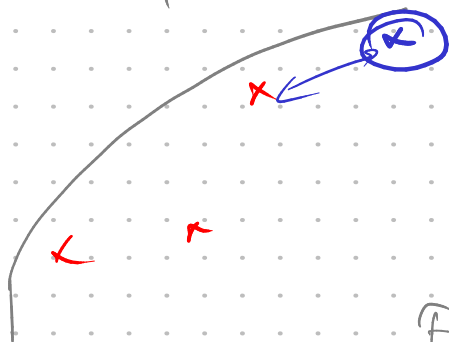


$$\frac{\pi \cdot 1^2 - \pi(1-\epsilon)^2}{\pi} = 1 - (1-\epsilon)^2$$



$$\frac{\frac{4}{3}\pi - \frac{4}{3}\pi(1-\epsilon)^3}{\frac{4}{3}\pi} = 1 - (1-\epsilon)^3$$

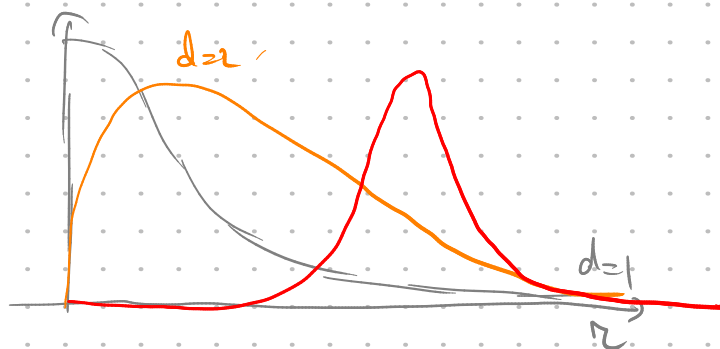
$$1 - (1-\epsilon)^d \quad d \rightarrow \infty$$



$$\bar{x} \sim \mathcal{N}(\bar{0}, \mathbf{I})$$

$$d(\bar{x}_i, 0) = \sum_{i=1}^d \bar{x}_i^2$$

$\bar{x}_i \sim \mathcal{N}(0, 1)$



Statistical decision theory

$$\bar{x} \in \mathbb{R}^d$$

$$y \in \mathbb{R}$$

$$D = \{(\bar{x}_n, y_n)\}$$

$$p(\bar{x}, y)$$

$$f(\bar{x}) \quad f: \bar{x} \mapsto y$$

$$L(\bar{x}) = (f(\bar{x}) - y)^2 = \underbrace{p(\bar{x})}_{=} \underbrace{p(y|\bar{x})}_{=}$$

$$EPE[f] = E_{p(\bar{x}, y)}[(f(\bar{x}) - y)^2] = \int \underbrace{p(\bar{x}, y)}_{=} (f(\bar{x}) - y)^2 d\bar{x} dy =$$

exp. pred. error $f \rightarrow \min$

$$= \int \left(\int (f(\bar{x}) - y)^2 p(y|\bar{x}) dy \right) p(\bar{x}) d\bar{x}$$

$f(\bar{x})$
min

$f \rightarrow \min$

regression function

$$\int (z - a)^2 p(z) dz \xrightarrow{a} \min$$

$$a = E[z]$$

$$\hat{f}(\bar{x}) = E_{p(y|\bar{x})}[y]$$

$$\hat{f}(\bar{x}) = E_{p(y|\bar{x})}[y] \approx \frac{1}{R} \sum_{z=1}^R y_z \approx \frac{1}{R} \sum_{z=1}^R \underline{y'_z}$$

$y'_z = k\text{-NN no } \bar{x}$

$$L(y, y') = \begin{cases} 1, & y \neq y' \\ 0, & y = y' \end{cases}$$

$$EPE[f] = E_{p(\bar{x}, y)}[L(y, f(\bar{x}))] = \int \left(\sum_{k=1}^K L(y, f_k) p(y_k|\bar{x}) \right) p(\bar{x}) d\bar{x}$$

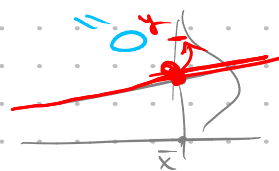
$$\hat{f}(\bar{x}) = \underset{k}{\operatorname{argmax}} p(y_k|\bar{x})$$

Optimal Bayes classifier

$$EPE[f] = \iint p(\bar{x}, y) (f(\bar{x}) - y)^2 d\bar{x} dy =$$

$$= \iint p(\bar{x}, y) (f(\bar{x}) - \hat{f}(\bar{x}) + \hat{f}(\bar{x}) - y)^2 d\bar{x} dy = \int \underbrace{(f(\bar{x}) - \hat{f}(\bar{x}))^2}_{=0} p(y|\bar{x}) dy$$

$$= \iint p(\bar{x}, y) (f(\bar{x}) - \hat{f}(\bar{x}))^2 d\bar{x} dy + 2 \iint p(\bar{x}, y) (f(\bar{x}) - \hat{f}(\bar{x})) (\hat{f}(\bar{x}) - y) d\bar{x} dy + \iint p(\bar{x}, y) (\hat{f}(\bar{x}) - y)^2 d\bar{x} dy$$

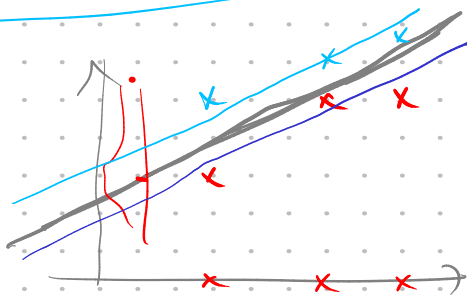


$$EPE[f] = \underbrace{E_{p(\bar{x}, y)} [(f(\bar{x}) - \hat{f}(\bar{x}))^2]}_{\text{variance}} + \underbrace{E_{p(\bar{x}, y)} [(\hat{f}(\bar{x}) - y)^2]}_{\text{noise}}$$

NOISE

$$f(\bar{x}) = f(\bar{x}; \mathcal{D})$$

$$\mathcal{D} \sim p(\bar{x}, y)$$



$$\iint p(\bar{x}, y) (f(\bar{x}) - \hat{f}(\bar{x}))^2 d\bar{x} dy = \iint p(\bar{x}, y) (f(\bar{x}) - E_{\mathcal{D}} f(\bar{x}) + E_{\mathcal{D}} f(\bar{x}) - \hat{f}(\bar{x}))^2 d\bar{x} dy$$

$$= \iint p(\bar{x}, y) (f - E_{\mathcal{D}} f)^2 d\bar{x} dy + 2 \iint p(\bar{x}, y) (f - E_{\mathcal{D}} f) (E_{\mathcal{D}} f - \hat{f}) d\bar{x} dy + \iint p(\bar{x}, y) (E_{\mathcal{D}} f - \hat{f})^2 d\bar{x} dy$$

$$EPE[f] = E_{p(\bar{x}, y)} [(f(\bar{x}; \mathcal{D}) - E_{\mathcal{D}} f(\bar{x}; \mathcal{D}))^2]$$

variance

$$+ E_{p(\bar{x}, y)} [(E_{\mathcal{D}} f(\bar{x}; \mathcal{D}) - \hat{f}(\bar{x}))^2]$$

bias

$$+ E_{p(\bar{x}, y)} [(\hat{f}(\bar{x}) - y)^2]$$

noise

Bias-variance-noise decomposition