

# LOGISTIC REGRESSION

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- We have already considered the logistic sigmoid:

$$p(\mathcal{C}_1 | \mathbf{x}) = \frac{p(\mathbf{x} | \mathcal{C}_1)p(\mathcal{C}_1)}{p(\mathbf{x} | \mathcal{C}_1)p(\mathcal{C}_1) + p(\mathbf{x} | \mathcal{C}_2)p(\mathcal{C}_2)} = \frac{1}{1 + e^{-a}} = \sigma(a),$$

$$\text{where } a = \ln \frac{p(\mathbf{x} | \mathcal{C}_1)p(\mathcal{C}_1)}{p(\mathbf{x} | \mathcal{C}_2)p(\mathcal{C}_2)}, \quad \sigma(a) = \frac{1}{1 + e^{-a}}.$$

- We have derived LDA and QDA, and trained them with maximal likelihood.

- Let's go back to classification.
- Two classes, the posterior is the logistic sigmoid of a linear function:

$$p(\mathcal{C}_1 | \phi) = y(\phi) = \sigma(\mathbf{w}^\top \phi), \quad p(\mathcal{C}_2 | \phi) = 1 - p(\mathcal{C}_1 | \phi).$$

- *Logistic regression* is when we optimize  $\mathbf{w}$  directly.

- For a dataset  $\{\phi_n, t_n\}$ ,  $t_n \in \{0, 1\}$ ,  $\phi_n = \phi(\mathbf{x}_n)$ :

$$p(\mathbf{t} | \mathbf{w}) = \prod_{n=1}^N y_n^{t_n} (1 - y_n)^{1-t_n}, \quad y_n = p(\mathcal{C}_1 | \phi_n).$$

- We look for maximal likelihood parameters by minimizing  $-\ln p(\mathbf{t} | \mathbf{w})$ :

$$E(\mathbf{w}) = -\ln p(\mathbf{t} | \mathbf{w}) = -\sum_{n=1}^N [t_n \ln y_n + (1 - t_n) \ln(1 - y_n)].$$

- Since  $\sigma' = \sigma(1 - \sigma)$ , we take the gradient:

$$\nabla E(\mathbf{w}) = \sum_{n=1}^N (y_n - t_n) \phi_n.$$

- If we now perform gradient descent, we get the separating surface.
- Note that if the data are actually separable, we could get heavy overfitting:  $\|\mathbf{w}\| \rightarrow \infty$ , and the sigmoid turns into a Heaviside function.
- We have to regularize.

- Logistic regression does not yield a closed form solution because of the sigmoid.
- But function  $E(\mathbf{w})$  is convex, and we can use Newton–Raphson’s method: use local quadratic approximation to the loss function on each step:

$$\mathbf{w}^{\text{new}} = \mathbf{w}^{\text{old}} - \mathbf{H}^{-1} \nabla E(\mathbf{w}),$$

where  $\mathbf{H}$  (Hessian) is the matrix of second derivatives for  $E(\mathbf{w})$ .

- Aside: let us apply Newton–Raphson’s method to regular linear regression with quadratic error:

$$\nabla E(\mathbf{w}) = \sum_{n=1}^N (\mathbf{w}^\top \phi_n - t_n) \phi_n = \Phi^\top \Phi \mathbf{w} - \Phi^\top \mathbf{t},$$

$$\nabla \nabla E(\mathbf{w}) = \sum_{n=1}^N \phi_n \phi_n^\top = \Phi^\top \Phi,$$

and the optimization step will be

$$\begin{aligned} \mathbf{w}^{\text{new}} &= \mathbf{w}^{\text{old}} - (\Phi^\top \Phi)^{-1} [\Phi^\top \Phi \mathbf{w}^{\text{old}} - \Phi^\top \mathbf{t}] = \\ &= (\Phi^\top \Phi)^{-1} \Phi^\top \mathbf{t}, \end{aligned}$$

i.e., we get a solution in one step.

- For logistic regression:

$$\nabla E(\mathbf{w}) = \sum_{n=1}^N (y_n - t_n) \phi_n = \Phi^\top (\mathbf{y} - \mathbf{t}),$$

$$\mathbf{H} = \nabla \nabla E(\mathbf{w}) = \sum_{n=1}^N y_n (1 - y_n) \phi_n \phi_n^\top = \Phi^\top R \Phi$$

for a diagonal matrix  $R$  c  $R_{nn} = y_n(1 - y_n)$ .



- Optimization step formula:

$$\mathbf{w}^{\text{new}} = \mathbf{w}^{\text{old}} - (\Phi^{\top} R \Phi)^{-1} \Phi^{\top} (\mathbf{y} - \mathbf{t}) = (\Phi^{\top} R \Phi)^{-1} \Phi^{\top} R \mathbf{z},$$

where  $\mathbf{z} = \Phi \mathbf{w}^{\text{old}} - R^{-1} (\mathbf{y} - \mathbf{t})$ .

- This is like a weighted least squares optimization problem with matrix of weights  $R$ .
- Hence the title: iterative reweighted least squares (IRLS).

- In case of several classes

$$p(\mathcal{C}_k | \phi) = y_k(\phi) = \frac{e^{a_k}}{\sum_j e^{a_j}} \text{ for } a_k = \mathbf{w}_k^\top \phi.$$

- Consider the ML estimate again; first,

$$\frac{\partial y_k}{\partial a_j} = y_k ([k = j] - y_j).$$

- Let us now write the likelihood: for a 1-of- $K$  coding scheme we have target vector  $\mathbf{t}_n$  and likelihood

$$p(\mathbf{T} \mid \mathbf{w}_1, \dots, \mathbf{w}_K) = \prod_{n=1}^N \prod_{k=1}^K p(\mathcal{C}_k \mid \phi_n)^{t_{nk}} = \prod_{n=1}^N \prod_{k=1}^K y_{nk}^{t_{nk}}$$

for  $y_{nk} = y_k(\phi_n)$ ; taking the log, we get

$$E(\mathbf{w}_1, \dots, \mathbf{w}_K) = -\ln p(\mathbf{T} \mid \mathbf{w}_1, \dots, \mathbf{w}_K) = -\sum_{n=1}^N \sum_{k=1}^K t_{nk} \ln y_{nk}, \quad \forall$$

$$\nabla_{\mathbf{w}_j} E(\mathbf{w}_1, \dots, \mathbf{w}_K) = -\sum_{n=1}^N (y_{nj} - t_{nj}) \phi_n.$$

- Again, we can optimize with Newton–Raphson’s method; the Hessian is

$$\nabla_{\mathbf{w}_k} \nabla_{\mathbf{w}_j} E(\mathbf{w}_1, \dots, \mathbf{w}_K) = - \sum_{n=1}^N y_{nk} ([k = j] - y_{nj}) \phi_n \phi_n^\top.$$

- What if we have a different sigmoid?
- The same setting: two classes,  $p(t = 1 | a) = f(a)$ ,  $a = \mathbf{w}^\top \phi$ ,  $f$  is the activation function.
- Consider an activation function with threshold  $\theta$ : for each  $\phi_n$  we compute  $a_n = \mathbf{w}^\top \phi_n$ , and

$$\begin{cases} t_n = 1, & \text{if } a_n \geq \theta, \\ t_n = 0, & \text{if } a_n < \theta. \end{cases}$$

- If  $\theta$  is taken by distribution  $p(\theta)$ , this corresponds to

$$f(a) = \int_{-\infty}^a p(\theta) d\theta.$$

- Suppose, e.g., that  $p(\theta)$  is a Gaussian with zero mean and unit variance. Then

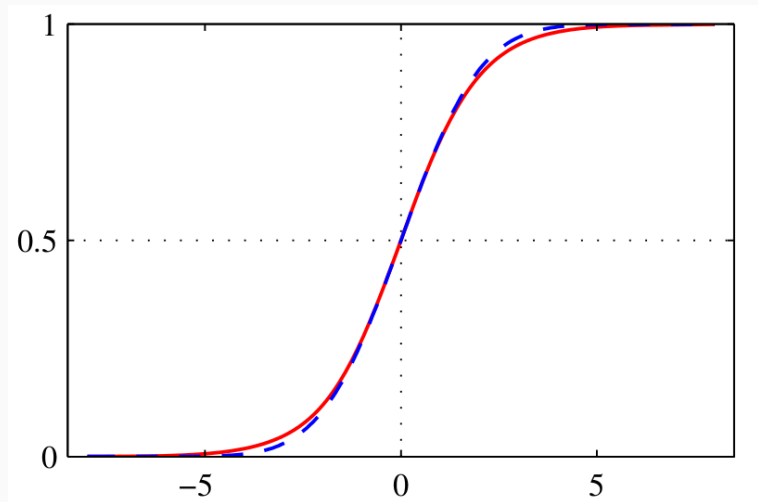
$$f(a) = \Phi(a) = \int_{-\infty}^a \mathcal{N}(\theta | 0, 1) d\theta.$$

- This is called the *probit function*; it's non-elementary, related to

$$\operatorname{erf}(a) = \frac{2}{\sqrt{\pi}} \int_0^a e^{-\frac{\theta^2}{2}} d\theta :$$

$$\Phi(a) = \frac{1}{2} \left[ 1 + \frac{1}{\sqrt{2}} \operatorname{erf}(a) \right].$$

- Probit regression is the model with probit activation function.





# LAPLACE APPROXIMATION AND BAYESIAN LOGISTIC REGRESSION

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- An aside: how do we approximate a complex distribution with a simpler one?
- E.g., how do we approximate a distribution near its maximum with a Gaussian? (a very natural idea)
- Let's first consider the distribution of a single continuous variable  $p(z) = \frac{1}{Z}f(z)$ .

- Step 1: find the maximum  $z_0$ .
- Step 2: decompose into Taylor series

$$\ln f(z) \approx \ln f(z_0) - \frac{1}{2}A(z - z_0)^2, \text{ where } A = -\frac{d^2}{dz^2} \ln f(z) \Big|_{z=z_0} .$$

- Step 3: approximate

$$f(z) \approx f(z_0)e^{-\frac{A}{2}(z-z_0)^2},$$

and it will be a Gaussian after normalization.

- This can be generalized to the multidimensional case

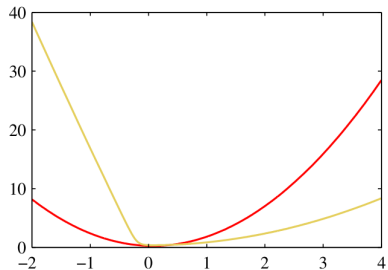
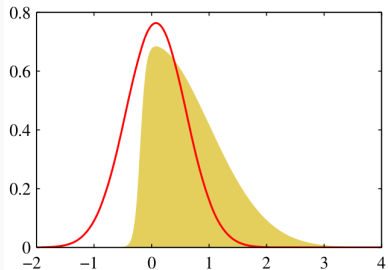
$$p(\mathbf{z}) = \frac{1}{Z} f(\mathbf{z}):$$

$$f(\mathbf{z}) \approx f(\mathbf{z}_0) e^{-\frac{1}{2}(\mathbf{z}-\mathbf{z}_0)^\top \mathbf{A}(\mathbf{z}-\mathbf{z}_0)},$$

$$\text{where } \mathbf{A} = -\nabla \nabla \ln f(\mathbf{z}) \big|_{z=\mathbf{z}_0}.$$

**Exercise.** What is the normalizing constant here?

# LAPLACE APPROXIMATION



- Having understood Laplace approximation, let us apply it first to model selection.
- To compare models from  $\{\mathcal{M}_i\}_{i=1}^L$ , by the test set  $D$  we estimate the posterior

$$p(\mathcal{M}_i | D) \propto p(\mathcal{M}_i)p(D | \mathcal{M}_i).$$

- If a model is defined parametrically, we get  
 $p(D | \mathcal{M}_i) = \int p(D | \theta, \mathcal{M}_i)p(\theta | \mathcal{M}_i)d\theta$ .
- This is the probability to generate  $D$  if we choose model parameters according to its prior; the denominator from Bayes' theorem:

$$p(\theta | \mathcal{M}_i, D) = \frac{p(D | \theta, \mathcal{M}_i)p(\theta | \mathcal{M}_i)}{p(D | \mathcal{M}_i)}.$$

## MODEL COMPARISON WITH LAPLACE APPROXIMATION

- Earlier we approximated it with a nearly piecewise constant function.
- Let us now approximate with a Gaussian; integrating, we get

$$Z = \int f(\mathbf{z}) d\mathbf{z} \approx \int f(\mathbf{z}_0) e^{-\frac{1}{2}(\mathbf{z}-\mathbf{z}_0)^\top \mathbf{A}(\mathbf{z}-\mathbf{z}_0)} d\mathbf{z} = f(\mathbf{z}_0) \frac{(2\pi)^{M/2}}{|\mathbf{A}|^{1/2}}.$$

- And we have  $Z = p(D)$ ,  $f(\theta) = p(D | \theta)p(\theta)$ .

- We get

$$\ln p(D) \approx \ln p(D | \theta_{\text{MAP}}) + \ln P(\theta_{\text{MAP}}) + \frac{M}{2} \ln(2\pi) - \frac{1}{2} \ln |\mathbf{A}|.$$

- $\ln P(\theta_{\text{MAP}}) + \frac{M}{2} \ln(2\pi) - \frac{1}{2} \ln |\mathbf{A}|$  is called the *Occam's factor*.
- $\mathbf{A} = -\nabla\nabla \ln p(D | \theta_{\text{MAP}})p(\theta_{\text{MAP}}) = -\nabla\nabla \ln p(\theta_{\text{MAP}} | D)$ .



- We get

$$\ln p(D) \approx \ln p(D | \theta_{\text{MAP}}) + \ln P(\theta_{\text{MAP}}) + \frac{M}{2} \ln(2\pi) - \frac{1}{2} \ln |\mathbf{A}|.$$

- If the Gaussian prior  $p(\theta)$  is wide enough, and  $\mathbf{A}$  has full rank, we can roughly approximate (prove it!) as

$$\ln p(D) \approx \ln p(D | \theta_{\text{MAP}}) - \frac{1}{2} M \ln N,$$

where  $M$  is the number of parameters,  $N$  is the number of points in  $D$ , and we have omitted additive constants.

- This is called the *Bayesian information criterion* (BIC), or *Schwarz criterion*.

- And now the full Bayesian treatment.
- Logistic regression is not as simple as linear regression: we can't get an exact answer out of a product of logistic sigmoids.
- We'll make a Laplace approximation.

- Gaussian prior:

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} \mid \mu_0, \Sigma_0).$$

- The posterior is then

$$p(\mathbf{w} \mid \mathbf{t}) \propto p(\mathbf{w})p(\mathbf{t} \mid \mathbf{w}), \text{ и}$$

$$\ln p(\mathbf{w} \mid \mathbf{t}) = -\frac{1}{2} (\mathbf{w} - \mu_0)^\top \Sigma_0^{-1} (\mathbf{w} - \mu_0)$$

$$+ \sum_{n=1}^N [t_n \ln y_n + (1 - t_n) \ln(1 - y_n)] + \text{const},$$

where  $y_n = \sigma(\mathbf{w}^\top \phi_n)$ .

- To approximate, we first find the maximum  $\mathbf{w}_{\text{MAP}}$ , and then the covariance matrix is the matrix of second derivatives

$$\Sigma_N = -\nabla\nabla \ln p(\mathbf{w} \mid \mathbf{t}) = \Sigma_0^{-1} + \sum_{n=1}^N y_n(1 - y_n)\phi_n\phi_n^\top.$$

- Our approximation is now

$$q(\mathbf{w}) = \mathcal{N}(\mathbf{w} \mid \mathbf{w}_{\text{MAP}}, \Sigma_N).$$

- And we can now get the Bayesian prediction:

$$p(\mathcal{C}_1 | \phi, \mathbf{t}) = \int p(\mathcal{C}_1 | \phi, \mathbf{w})p(\mathbf{w} | \mathbf{t})d\mathbf{w} \approx \int \sigma(\mathbf{w}^\top \phi)q(\mathbf{w})d\mathbf{w}.$$

- Note that  $\sigma(\mathbf{w}^\top \phi)$  depends on  $\mathbf{w}$  only via its projection on  $\phi$ .
- We denote  $a = \mathbf{w}^\top \phi$ :

$$\sigma(\mathbf{w}^\top \phi) = \int \delta(a - \mathbf{w}^\top \phi)\sigma(a)da.$$

- $\sigma(\mathbf{w}^\top \phi) = \int \delta(a - \mathbf{w}^\top \phi) \sigma(a) da$ , and therefore

$$\int \sigma(\mathbf{w}^\top \phi) q(\mathbf{w}) d\mathbf{w} = \int \sigma(a) p(a) da,$$

$$\text{where } p(a) = \int \delta(a - \mathbf{w}^\top \phi) q(\mathbf{w}) d\mathbf{w}.$$

- $p(a)$  is the marginalization of Gaussian  $q(\mathbf{w})$ , where we integrate over everything which is orthogonal to  $\phi$ .

- $p(a)$  is the marginalization of Gaussian  $q(\mathbf{w})$ , where we integrate over everything which is orthogonal to  $\phi$ .
- Hence,  $p(a)$  is a Gaussian too, and we can find its parameters

$$\begin{aligned}\mu_a &= \mathbb{E}[a] = \int a p(a) da = \int q(\mathbf{w}) \mathbf{w}^\top \phi d\mathbf{w} = \mathbf{w}_{\text{MAP}}^\top \phi, \\ \sigma_a^2 &= \int (a^2 - \mathbb{E}[a])^2 p(a) da = \\ &= \int q(\mathbf{w}) [(\mathbf{w}^\top \phi)^2 - (\mu_N^\top \phi)^2]^2 d\mathbf{w} = \phi^\top \Sigma_N \phi.\end{aligned}$$

- Thus, we get that

$$p(\mathcal{C}_1 | \mathbf{t}) = \int \sigma(a) p(a) da = \int \sigma(a) \mathcal{N}(a | \mu_a, \sigma_a^2) da.$$

- $p(\mathcal{C}_1 | \mathbf{t}) = \int \sigma(a) \mathcal{N}(a | \mu_a, \sigma_a^2) da.$
- This integral is not easy to take, because sigmoid is hard, but we can approximate it by approximating  $\sigma(a)$  with the probit:  
 $\sigma(a) \approx \Phi(\lambda a)$  for  $\lambda = \sqrt{\pi/8}.$

**Exercise.** Prove that  $\lambda = \sqrt{\pi/8}$  if  $\sigma$  and  $\Phi$  have the same slope at zero.



- And if we pass to the probit function, its convolution with a Gaussian will be another probit:

$$\int \Phi(\lambda a) \mathcal{N}(a \mid \mu, \sigma^2) da = \Phi\left(\frac{\mu}{\sqrt{\frac{1}{\lambda^2} + \sigma^2}}\right).$$

Exercise. Prove it.

- As a result, we get the approximation

$$\int \sigma(a) \mathcal{N}(a | \mu, \sigma^2) da \approx \sigma(\kappa(\sigma^2)\mu),$$

$$\text{where } \kappa(\sigma^2) = \frac{1}{\sqrt{1 + \frac{\pi}{8}\sigma^2}}.$$

- And now, putting it all together, we get the predictive distribution:

$$p(\mathcal{C}_1 | \phi, \mathbf{t}) = \sigma(\kappa(\sigma_a^2)\mu_a), \text{ where}$$

$$\mu_a = \mathbf{w}_{\text{MAP}}^\top \phi,$$

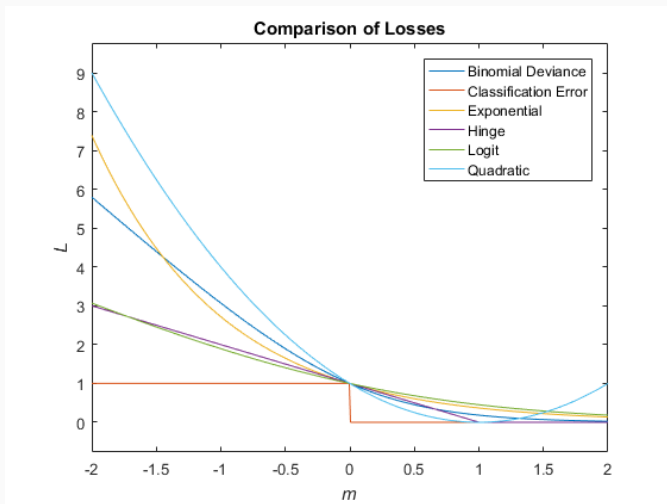
$$\sigma_a^2 = \phi^\top \Sigma_N \phi,$$

$$\kappa(\sigma^2) = \frac{1}{\sqrt{1 + \frac{\pi}{8}\sigma^2}}.$$

- By the way, the separating hyperplane  $p(\mathcal{C}_1 | \phi, \mathbf{t}) = \frac{1}{2}$  is defined by equation  $\mu_a = 0$ , and it's the same as just using  $\mathbf{w}_{\text{MAP}}$ .
- The difference is important only for more complex criteria.

- And a different look at classification: different methods differ by which loss function they optimize.
- Classification has a problem with the “correct” error function, i.e., misclassification rate:
  - it’s not differentiable everywhere,
  - and its derivative is useless.
- Let us look at different loss functions; we have seen several of them, but there are lots more.

# LOSS FUNCTIONS IN CLASSIFICATION



Thank you for your attention!