

$$EPE[\hat{f}] = \text{Bias}^2 + \text{Variance} + \text{Noise}$$

$$E[(E\hat{f} - \hat{f})^2] + E[(\hat{f} - E\hat{f})^2] + E[(y - \hat{f})^2]$$

Bayesian model selection

D - $(\mathcal{M}_1, \mathcal{M}_2, \mathcal{M}_3, \mathcal{M}_4, \dots)$

$$p(D | \bar{\theta}_2, \mathcal{M}_2)$$

$$p(D | \bar{\theta}_3, \mathcal{M}_3)$$

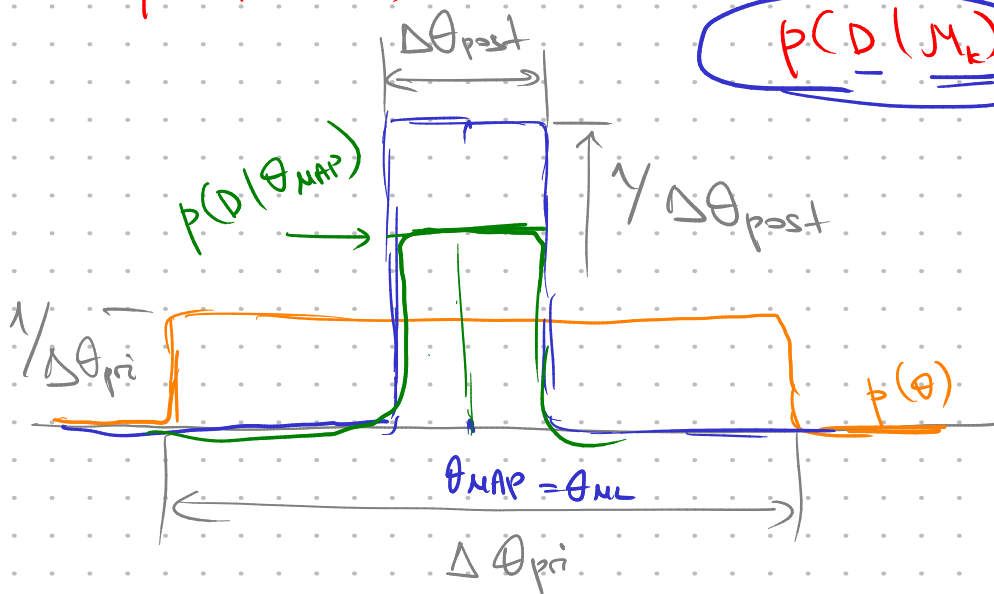
$$\bar{\theta}_1^{ML}$$

$$\bar{\theta}_3^{ML}$$

$$p(\bar{\theta}_1 | \mathcal{M}_1)$$

$$\bar{\theta}_1^{MAP} = \underset{\bar{\theta}_s}{\text{argmax}} p(\bar{\theta}_s | \mathcal{M}_1) p(D | \bar{\theta}_s, \mathcal{M}_1)$$

$$p(\bar{\theta}_k | \mathcal{M}_k) = \frac{p(\bar{\theta}_k | \mathcal{M}_k) p(D | \bar{\theta}_k, \mathcal{M}_k)}{p(D | \mathcal{M}_k)}$$

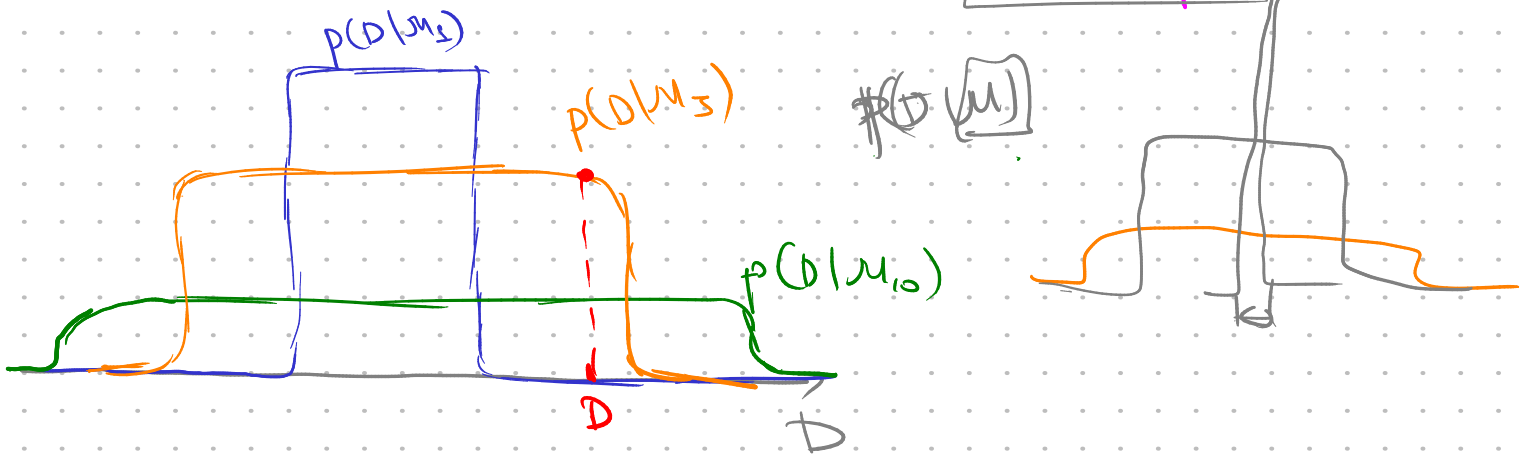


$$p(D | \mathcal{M}_k) = \int p(\bar{\theta} | \mathcal{M}_k) p(D | \bar{\theta}, \mathcal{M}_k) d\bar{\theta}$$

$$p(D) = \int p(\theta) p(D | \theta) d\theta = \int_{\Delta\theta_{pri}} \frac{1}{\Delta\theta_{pri}} \cdot p(D | \theta) d\theta =$$

$$= \int_{\Delta\theta_{post}} \frac{1}{\Delta\theta_{pri}} \cdot p(D | \theta_{MAP}) d\theta = p(D | \theta_{MAP}) \cdot \frac{\Delta\theta_{post}}{\Delta\theta_{pri}}$$

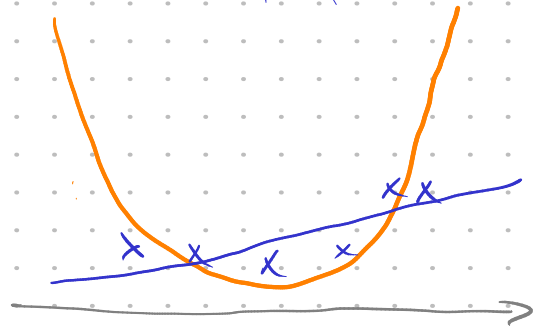
$$\ln p(D) \approx \ln p(D | \theta_{MAP}) + M \cdot \ln \frac{\Delta \theta_{post}}{\Delta \theta_{pri}}$$



$$D \sim \mathcal{M}_{true}$$

$\{(\bar{x}, \bar{y})\} \quad y_n \sim p(y | \bar{x}_n, \mathcal{M}_{true})$

$$p(D | \mathcal{M}_{true}) \neq p(D | \mathcal{M})$$



0?

$$E_{D \sim p(D | \mathcal{M}_{true})} \left[\ln \frac{p(D | \mathcal{M}_{true})}{p(D | \mathcal{M})} \right] =$$

$$= \int p(D | \mathcal{M}_{true}) \ln \frac{p(D | \mathcal{M}_{true})}{p(D | \mathcal{M})} dD =$$

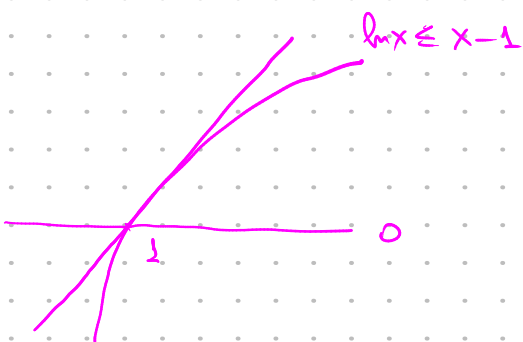
$$= KL(p(D | \mathcal{M}_{true}) || p(D | \mathcal{M}))$$

$$KL(p || q) = \int p(\bar{x}) \ln \frac{p(\bar{x})}{q(\bar{x})} d\bar{x} \geq 0$$

$$= \int p(\bar{x}) \ln \frac{q(\bar{x})}{p(\bar{x})} d\bar{x} \geq$$

$$\geq - \int p(\bar{x}) \left(\frac{q(\bar{x})}{p(\bar{x})} - 1 \right) d\bar{x} =$$

$$= - \int q(\bar{x}) d\bar{x} + \int p(\bar{x}) d\bar{x} = 0$$



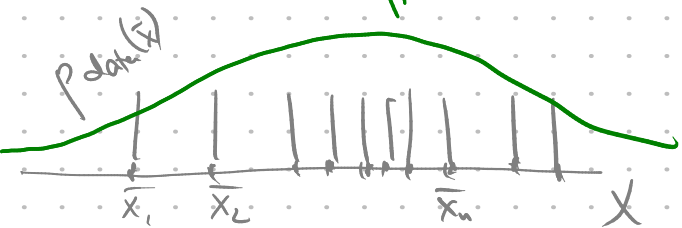
$$\ln p(D|\bar{\theta}) = \sum_{n=1}^N \ln p(\bar{x}_n|\bar{\theta}) \rightarrow \max$$

$$D = \{\bar{x}_1, \dots, \bar{x}_N\}$$

$$p_{\text{model}}(\bar{x}|\bar{\theta}) \approx$$

$$p_{\text{data}}(\bar{x}) = \text{Unit}(D) =$$

$$= \frac{1}{N} \cdot \sum_n \delta(\bar{x} - \bar{x}_n)$$



$$KL(p_{\text{model}} \parallel p_{\text{data}})$$

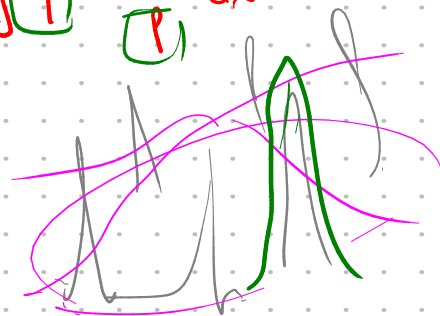
$$KL(p_{\text{data}} \parallel p_{\text{model}}) = \int p_{\text{data}}(\bar{x}) \ln \frac{p_{\text{data}}(\bar{x})}{p_{\text{model}}(\bar{x})} d\bar{x} =$$

$$= \int p_{\text{data}}(\bar{x}) \ln p_{\text{data}}(\bar{x}) d\bar{x} - \int p_{\text{data}}(\bar{x}) \ln p_{\text{model}}(\bar{x}) d\bar{x} =$$

$$= \int \dots d\bar{x} - \sum_{n=1}^N \ln p_{\text{model}}(\bar{x}_n) \xrightarrow{\bar{\theta}} \min$$

$$KL(p \parallel q) = \int p \ln \frac{p}{q} dx \quad KL(q \parallel p) = \int q \ln \frac{q}{p} dx$$

min \leftarrow $\leftarrow \text{argmin } KL(q \parallel p)$



$\leftarrow \text{argmin } KL(p \parallel q)$

\bar{x}

$$p(D) = \int \underbrace{p(D|\theta) p(\theta)}_{\approx \mathcal{N}} d\theta$$

$$p(D) = \int \underbrace{f(\bar{\theta})}_{\theta_{MAP}} d\bar{\theta} \approx \int f(\bar{\theta}_0) e^{-\frac{1}{2}(\bar{\theta} - \bar{\theta}_0)^T A (\bar{\theta} - \bar{\theta}_0)} d\bar{\theta} =$$

$$= \underbrace{f(\bar{\theta}_0)}_{\text{max a posteriori}} \sqrt{\frac{(2\pi)^M}{\det A}}$$

$$A = -\nabla \nabla \ln f(\bar{\theta})$$

$$\ln p(D) \approx \underbrace{\ln p(D|\theta_{MAP})}_{\text{max a posteriori}} + \underbrace{\ln p(\theta_{MAP}) + \frac{M}{2} \ln 2\pi - \frac{1}{2} \ln |A|}_{\text{Occam's factor}}$$

Occam's factor

$$\boxed{\ln p(D) \approx \ln p(D|\theta_{MAP}) - \frac{1}{2} M \ln N} \quad \text{BIC}$$

