## Algorithms for Nearest Neighbors

Classic Ideas, New Ideas

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## Outline

- Problem Statement
  - Applications
  - Data Models

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- Classic Ideas
  - Search Trees
  - Random Projections
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  - Look-Up Methods
- New Ideas
  - Proving Hardness of Nearest Neighbors
  - Probabilistic Analysis for NN
  - New Data Models

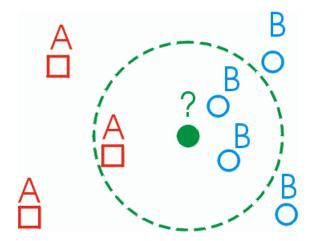
# Part I Formulating the Problem

## Informal Problem Statement

To preprocess a database of *n* objects so that given a query object, one can effectively determine its nearest neighbors in database

# First Application (1960s)

#### Nearest neighbors for classification:



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- Text classification
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- Pattern recognition: characters, faces
- Code plagiarism detection
- Coding theory
- Data compression

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- Statistical data analysis, e.g. medicine diagnosis
- Pattern recognition: characters, faces
- Code plagiarism detection
- Coding theory
- Data compression
- Web: recommendation systems, on-line ads, personalized news aggregation, long queries in web search, near-duplicates detection

## Data Model in General

Formalization for nearest neighbors consists of:

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Remark 1: Usually there is original and "reduced" representation for every object

**Remark 2:** Accuracy of NN-based algorithms depends solely on a data model, no matter what specific exact NN algorithm we use

# Data Models (1/2)

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  - Similarity:  $l^2$ , scalar product, cosine
- String Model
  - Similarity: Hamming distance, edit distance
- Black-box model
  - Similarity: given by oracle
     The only knowledge is triangle inequality

# Data Models (2/2)

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#### More data models?

## Variations of the Computation Task

- Range queries: retrieve all objects within given range from query object
- Approximate nearest neighbors
- Multiple nearest neighbors (many queries)
- Nearest assignment
- All over-threshold neighbor pairs
- Nearest neighbors in dynamically changing database: moving objects, deletes/inserts, changing similarity function

# Part II Classic Ideas

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#### **Directions for improvement:**

order of scanning, pruning

#### **Preprocessing:**

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Go down to the leaf corresponding to the the query point and compute the distance;

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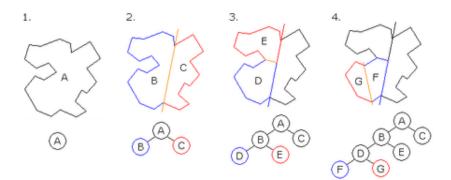
#### Query processing:

Go down to the leaf corresponding to the the query point and compute the distance;

(Recursively) Go one step up, check whether the distance to the second branch is larger than that to current candidate neighbor if "yes" go up, else check this second branch

#### **BSP-Trees**

**Generalization:** BSP-tree allows to use any hyperplanes in tree construction



#### **VP-Trees**

```
Partitioning condition: d(p,x) <? r
Inner branch: B(p,r(1+\varepsilon))
Outer branch: R^d/B(p,r(1-\delta))
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#### Search:

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If d(p, q) < r go to inner branch If d(p, q) > r go to outer branch
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#### Search:

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If d(p,q) < r go to inner branch
If d(p,q) > r go to outer branch and
return minimum between obtained result
and d(p,q)
```

# Kleinberg Algorithm (1/3)

#### **Preprocessing**

- ① Choose / random vectors  $V = \{v_1, \dots, v_l\}$  with unit norm
- ② Precompute all scalar products between database points and vectors from V

# Kleinberg Algorithm (2/3)

#### **Random Projection Test**

```
Input: points x,y and q, vectors u_1, \ldots, u_k Question: what is smaller |x - q| or |y - q|?
```

#### Test:

```
For all i compare (x \cdot v_i - q \cdot v_i) with (y \cdot v_i - q \cdot v_i)
Return the point which has "smaller"
on majority of vectors
```

# Kleinberg Algorithm (3/3)

#### **Query Processing**

- **1** Choose a random subset  $\Gamma$  of V,  $|\Gamma| = \log^3 n$
- ② Compute scalar products between query point q and vectors from  $\Gamma$
- Make a tournament for choosing a nearest neighbor:
  - **1** Draw a binary tree of height  $\log n$
  - Assign all database points to leafs
  - **3** For every internal point (say, x vs. y) make a random projection test using some vectors from  $\Gamma$

#### Inverted Index

**Data model:** every object is a (weighted) set of terms from some dictionary

#### **Preprocessing:**

For very term store a list of all documents in database with nonzero weight on it

#### Query processing:

Retrieve all point that have at least one common term with the query documet; Perform linear scan on them

# Locality-Sensitive Hashing

#### **Desired hash family** $\mathcal{H}$ :

- If  $||p-q|| \leq R$  then  $\mathcal{P}r_{\mathcal{H}}[h(p) = h(q)] \geq p_1$
- If  $||p-q|| \ge cR$  then  $\mathcal{P}r_{\mathcal{H}}[h(p) = h(q)] \le p_2$

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Choose at random several hash functions from  ${\cal H}$  Build inverted index for hash values of object in database

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# Part III New Ideas

This section represents:

- Some of my own ideas
- Joint work with Benjamin Hoffmann and Dirk Nowotka (CSR'07)

# Inclusions with Preprocessing (1/2)

#### Input

Family  $\mathcal{F}$  of subsets of U

#### Query task

```
Given a set f_{new} \subseteq U to decide whether \exists f \in \mathcal{F} : f_{new} \subseteq f
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#### **Constraints**

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Data storage after preprocessing poly(|\mathcal{F}| + |U|)
Time for query processing poly(|U|)
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**Open problem:** is there an algorithm satisfying given constraints?

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Reformulation in SAT style:

#### Input

Formula  $\mathcal{F}$  in DNF with n variables

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Given an assignment x to evaluate  $\mathcal{F}(x)$ 

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# "NP Analogue" for Search Problems

Every problem in **SEARCH** class is characterized by poly-time computable Turing Machine *M*:

#### Input

Strings 
$$x_1, \ldots, x_n$$
,  $|x_i| = m$ 

#### Query task

Given string y of length m to answer whether  $\exists i : M(x_i, y) = yes$ 

# Tractable problems in SEARCH

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Preprocessing in poly(m, n) space

Query processing in poly(m, log n) time with RAM access to preprocessed database

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Inclusions is in SEARCH. Is it tractable?

# Complete problems in SEARCH (1/2)

#### Program Search problem:

#### Input

Turing machines  $P_1 \dots, P_n$ 

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Given string y of length m to answer whether  $\exists i : P_i(y) = yes$  after at most m steps

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#### Parallel Run problem:

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- We define probability distribution over query objects
- We construct a solution that is efficient/accurate with high probability over "random" input/query

# Zipf Model

- Terms  $t_1, \ldots, t_m$
- To generate a document we take every  $t_i$  with probability  $\frac{1}{i}$
- Database is *n* independently chosen documents
- Query document has exactly one term in every interval  $[e^i, e^{i+1}]$
- Similarity between documents is defined as the number of common terms

## Magic Level Theorem

Magic Level 
$$q = \sqrt{2 \log_e n}$$

#### **Theorem**

- With very high probability there exists a document in database having  $\mathbf{q} \varepsilon$  top terms of query document
- **2** With very small probability there exists a document in database having any  $q + \varepsilon$  overlap with query document

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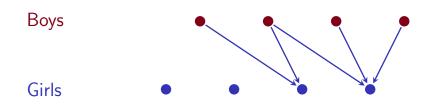
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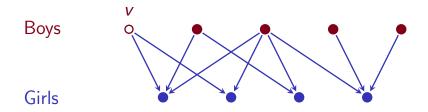
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**Open Problem:** solve NN for sparse vector model within given constraints

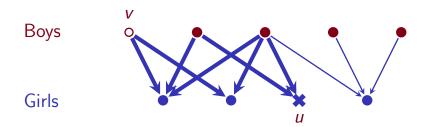
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### Amazon Nearest Neighbors

**Database:** Bipartite graph with n vertices, every vertex of the first part has out degree at most  $k \ll n$ 

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**Open Problem:** solve NN for Amazon model within given constraints

# **Conclusions**

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 Extend classical NN algorithms to new data models and new search task variations

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- Develop theoretical analysis of existing heuristics.
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- Build complexity theory for problems with preprocessing

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- Any relevant work?
- How to improve this talk for the next time?

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- Give my open problems to your students!

### Summary

- Classic ideas: search trees, random projections, locality-sensitive hashing, inverted index
- New ideas: SEARCH class, NN for random texts, Amazon and sparse vector models
- Open problems: lower bound for inclusions with preprocessing, algorithm for 3-step similarity

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# Thanks for your attention! Questions?

# References (1/2)

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